

HXR Undulator EPICS 7 Upgrade

1. EPICS IOC Prepared

a. HXR IOC Configuration:

i. git repo: Undulator_HXR

1. branch: epics7-update

ii. \$(git_repo)/configure/RELEASE:

- IOCADMIN_MODULE_VERSION = R3.1.16-1.3.2
SNCSEQ_MODULE_VERSION = R2.2.4-1.0
AUTOSAVE_MODULE_VERSION = R5.8-2.1.0
BUSY_MODULE_VERSION = R1.7.2.1-0.1.2
CAPUTLOG_MODULE_VERSION = R4.0-1.0.0
CALC_MODULE_VERSION = R3.7-1.0.1
SSCAN_MODULE_VERSION = R2.10.2-1.0.0
SPLINE_MODULE_VERSION = R2.0.2

ASYN_MODULE_VERSION = R4.39-1.0.1
#MOTOR_MODULE_VERSION = motor-git-hgvpv
MOTOR_MODULE_VERSION = motor-git
#MOTOR_MODULE_VERSION = R6.10.1-2.5.0

IPAC

IPAC_MODULE_VERSION = ipac-git
IP330_MODULE_VERSION = ip330-asyn-git
SOFTGLUE_MODULE_VERSION = softGlue-git
IPUNIDIG_MODULE_VERSION = ipUnidig-git

XIPIO_MODULE_VERSION = R1.2.0

VME

A16VME_MODULE_VERSION = R1.1.0
CEXP_MODULE_VERSION = R1.1.2

iii. \$(git_repo)/configure/RELEASE_SITE:

- BASE_MODULE_VERSION=R7.0.3.1-1.0
EPICS_SITE_TOP=/afs/slac/g/lcls/epics
BASE_SITE_TOP=/afs/slac/g/lcls/epics/base
MODULES_SITE_TOP=/afs/slac/g/lcls/epics/R7.0.3.1-1.0/modules
EPICS_MODULES=/afs/slac/g/lcls/epics/R7.0.3.1-1.0/modules
IOC_SITE_TOP=/afs/slac/g/lcls/epics/iocTop
PACKAGE_SITE_TOP=/afs/slac/g/lcls/package
MATLAB_PACKAGE_TOP=/afs/slac/g/lcls/package/matlab
PSPKG_ROOT=/afs/slac/g/lcls/pkg_mgr
TOOLS_SITE_TOP=/afs/slac/g/lcls/tools
ALARM_CONFIGS_TOP=/afs/slac/g/lcls/tools/AlarmConfigsTop

iv. \$(git_repo)/configure/CONFIG_SITE:

- CHECK_RELEASE = YES

CROSS_COMPILER_TARGET_ARCHS = RTEMS-mvme3100

PKG_ARCH=\$(T_A)

SHARED_LIBRARIES=NO
STATIC_BUILD=YES

ALGLIB_PACKAGE_NAME = alglib
ALGLIB_VERSION = 3.14.0
ALGLIB_TOP = \$(PACKAGE_SITE_TOP)/\$(ALGLIB_PACKAGE_NAME)/\$(ALGLIB_VERSION)
ALGLIB_LIB = \$(ALGLIB_TOP)/\$(T_A)/lib
ALGLIB_INCLUDE = \$(ALGLIB_TOP)/\$(T_A)/include

-include \$(TOP)/../CONFIG_SITE.local
-include \$(TOP)/configure/CONFIG_SITE.local

2. HXR Upgrade Test Plan

a. Week 1: Practice test on HXU-xxx

i. Prepare work:

1. Record current iocSpecificRelease for ioc-b81-mc01:
 - a. iocSpecificRelease -> ../../iocTop/users/alexmon/Undulator_HXR/dev_FG/
2. Discuss with Namrata and James on VME IOC initialization details
3. Print the checkout sheet

ii. During the test day:

1. Currently ioc-b81-mc01 is running, need to check again before test
2. Before any movement, record all the settings.
 - a. Take screenshots from GUI
 - b. check IOC status
 - c. check network connection: moc-xxx-mc03
 - d. Open undulator gap to 40mm
 - e. Follow [checkout sheet](#) to process the practice tests

3. Boot current EPICS 3 based IOC, record settings:
 4. Open EDM based Undulator GUI
 - a. login lcls-dev3
 5. Set up VME network configuration if necessary;
 6. Practice with K value and Gap convert
 7. According to the checkout sheet, the main motion test should be as follows:
 - a. Move gap from 180mm to 100mm
 - b. Power off controller and turn off ioc
 - c. Power on controller and turn on ioc
 - d. Confirm Encoder RBD value
 - e. Tests will verify the correct operation of the following motion controls:
 - f. Wiring, switch status, ESTOP functionality.
 - g. Coordinated motion for gap adjustment.
 - h. Encoder read back: available, calibrated.
 - i. Limit, tilt, and vacuum switches: single axis, coordinated motion.
 8. Take a look on spline
 9. Stop the test if encounter any issue/hazard, contact Alex for help.
 - iii. After all the test, revert ioc to EPICS v3 version, and recover all the settings as same as saved before.
- b. Week 2: EPICS 7 Upgrade test