# Test Stand that works (PEPPEx Chassis)

Parameter file name: test\_stand\_061422.prm

Motor: HT23-601C (Applied Motion)

Encoder: Resolute Encoder RL26BAE050D30A

Pitch: 5mm

Positive Dir: to the left

#### Counts/unit

Encoder = 50nm resolution => 1 count of encoder = 5 \* 10^(-5) mm

Counts/unit =  $1/(5*10^{-5})$ ) = 20000

### Counts/rev

1 motor revolution = 5 mm

=> 20000\*5 = 100000

## If 0 pos is set at right end:

#### Speed at 1mm/sec:

CW end of travel limit switch encoder reading: 139.2416mm

CCW end of travel limit switch encoder reading: 52.6566mm

mid point= 95.9622mm

## 0 pos is set at middle:

## Speed at 1mm/sec:

CW end of travel limit switch encoder reading: 43.3323mm

CCW end of travel limit switch encoder reading: -43.3531mm