

Data Acquisition at FACET-II

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- High-level overview of SLAC data system including EPICS
- Beam synchronous vs. non-beam synchronous data
- Quasi-BSA options with motion controllers

Four Layers to Data Acquisition

User/Client

Python

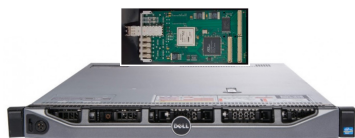
Matlab

GUIs

DAQ

Timing

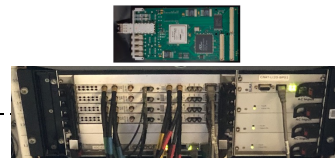
EPICS



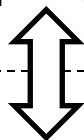
Controls Server



Camera Server



VME Crate



Channel Access (CA)



EVG (S10 RF Hut)



Fiber



EVR

Driver



XPS Controller

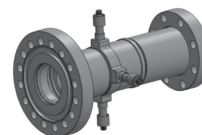
Device



UTS Stage



GigE Camera



BPM

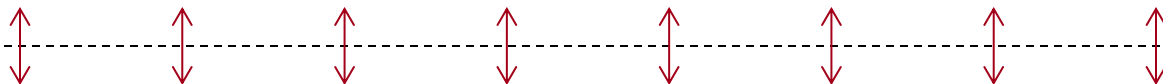
Timing

EVG (S10 RF Hut)

Beam Rate (e.g. 10 Hz)



TTL Camera Trigger



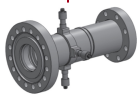
EVR (camera server)



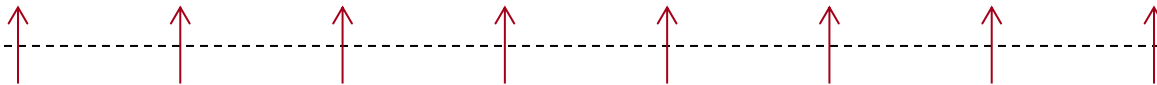
Software interrupt with timestamp and Pulse ID



Software interrupt with timestamp and Pulse ID



BPM does not receive trigger



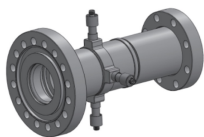
EPICS in one slide

- EPICS is a unified interface for communicating with devices on the controls network.
 - It is widely used: <https://epics-controls.org/>
- Devices are controlled by Input-Output Controllers (IOCs). IOCs exist for many devices:
 - Hardware devices: <https://epics.anl.gov/modules/manufacturer.php>
 - Software devices: <https://epics-controls.org/resources-and-support/modules/soft-support/>
 - Cameras: <https://areadetector.github.io/master/index.html>
 - SLAC devices: <https://github.com/slac-epics>
- It is *relatively* easy to create an IOC if the manufacturer provides firmware and an SDK.
- The IOC exposes Process Variables (PVs) that you can “get”, “set”, and “monitor”.
- We interact with PVs using the Channel Access, a TCP/IP protocol.
 - All data flows over the network!

There are a lot of resources on EPICS! For a very detailed tutorial, check out this 2019 USPAS class.
https://controlsoftware.sns.ornl.gov/training/2019_USPAS/

Beam Synchronous Acquisition

- Some devices record “scalar” data on every beam event. These include BPMs, toroids, and beam loss monitors.



BPM



Toroid



PMT

- Data from these devices are stored in buffer of length 2800 (SLC convention).
 - The buffer contains the data AND the timestamp/Pulse ID.
- The EVG coordinates buffers between devices and allows you to get synchronous data from many devices. This is called “Beam Synchronous Acquisition” (BSA).

Non-Beam Synchronous Acquisition

- Many devices do not support BSA. These include magnet and motor settings:



UTS Stage



Quadrupole

- The devices that control magnets and motors typically do not include EVRs. The devices do not know the timestamp and PulseID of a current event.
- Nevertheless, the controller *can* provide precise timestamps and this might be “good enough” for some applications.

Quasi-BSA option for motion control

User/Client

Python:

- 10 Hz Get/Set for motion controller
- 10 Hz (or triggered?) polling for EPICS IOC
- 10 Hz Get/Monitor for camera (works for 1 camera)

Timing

EPICS



Controls Server

Network



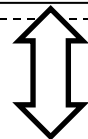
Driver



XPS Controller

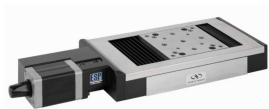


Camera Server



Channel Access (CA)

Device



UTS Stage



GigE Camera



EVG (S10 RF Hut)

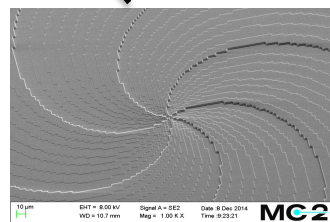
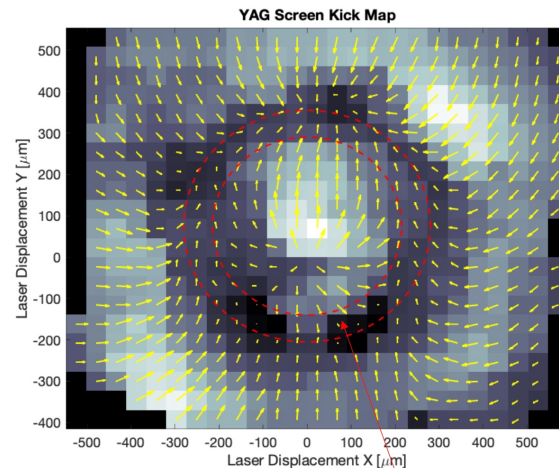
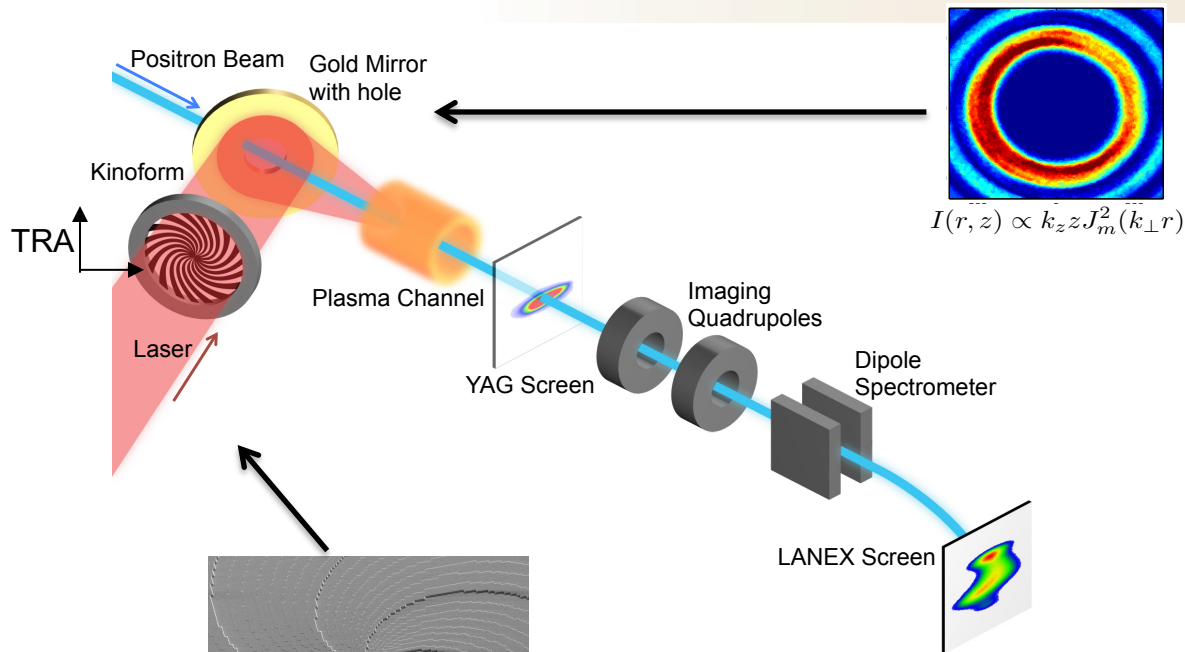


Fiber



EVR

Multi-Camera Raster Scan with FACET DAQ

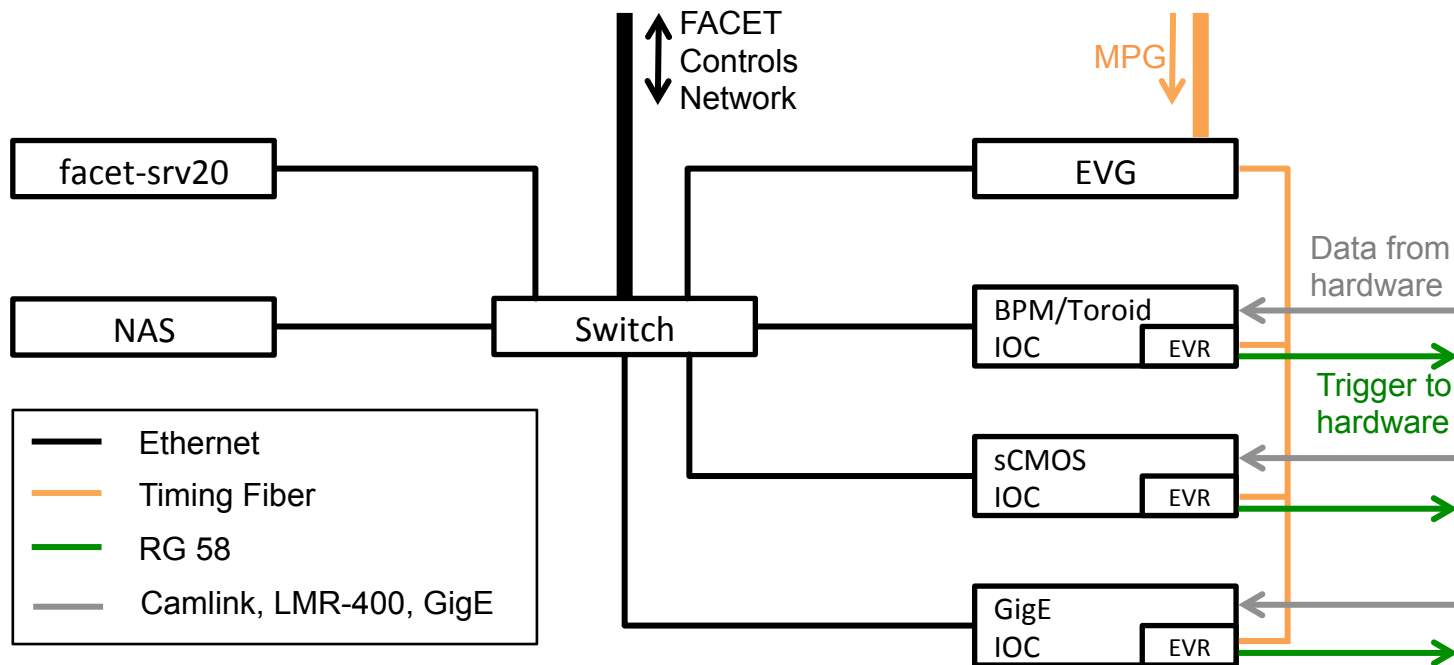


$$\Psi_m = k_{\perp} r + m\phi$$

Raster scan dataset with 2700 shots
(about 15 minutes to acquire and analyze)

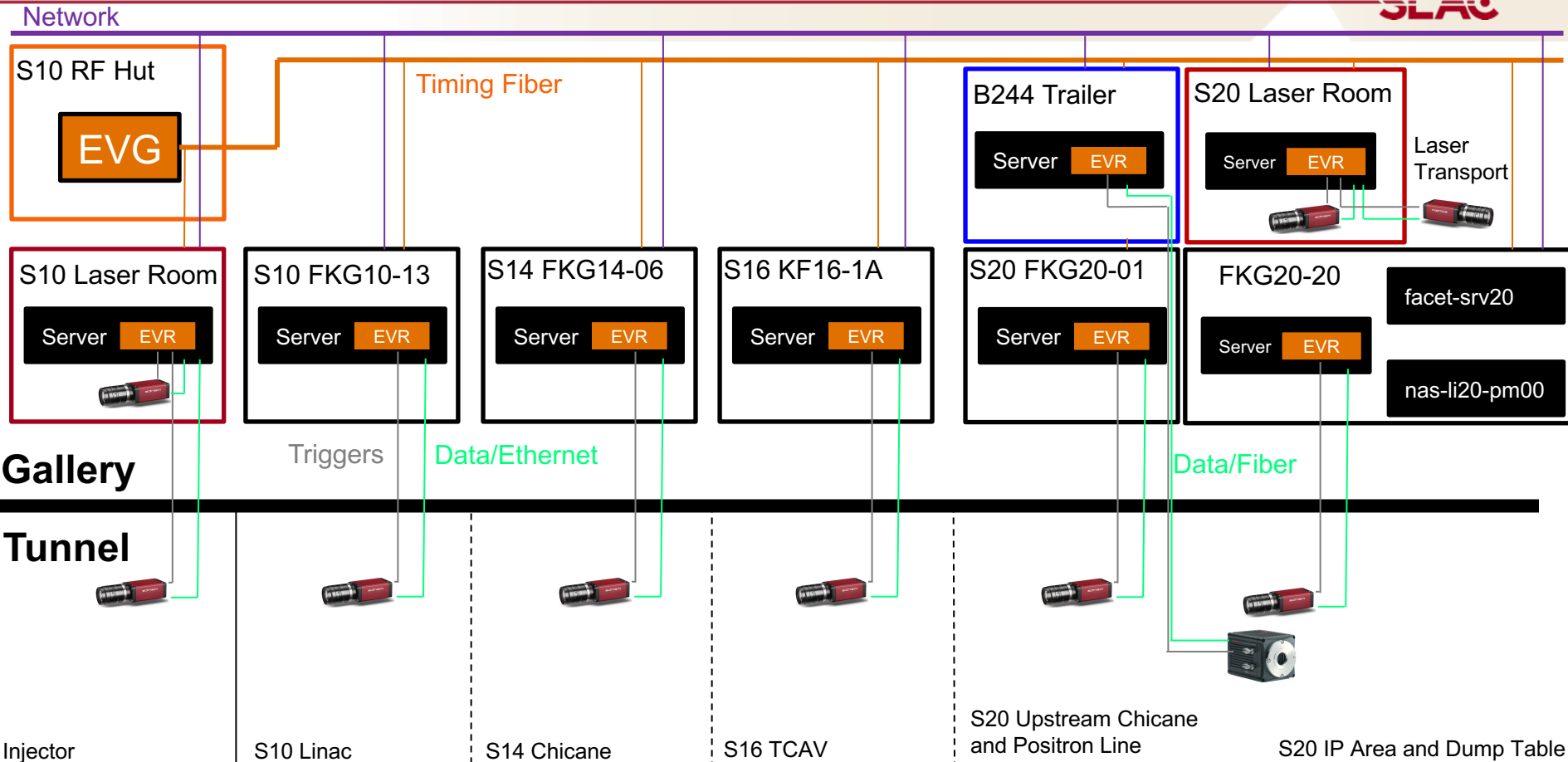
- FACET DAQ is designed to handle the problem of recording data from multiple cameras simultaneously.
- There are 60 cameras in use at FACET-II.
- At 10 Hz, the data from 10 cameras may overload the network.
- Data is written to Network Attached Storage (NAS) instead of being streamed over the network.

S20 Network Topology



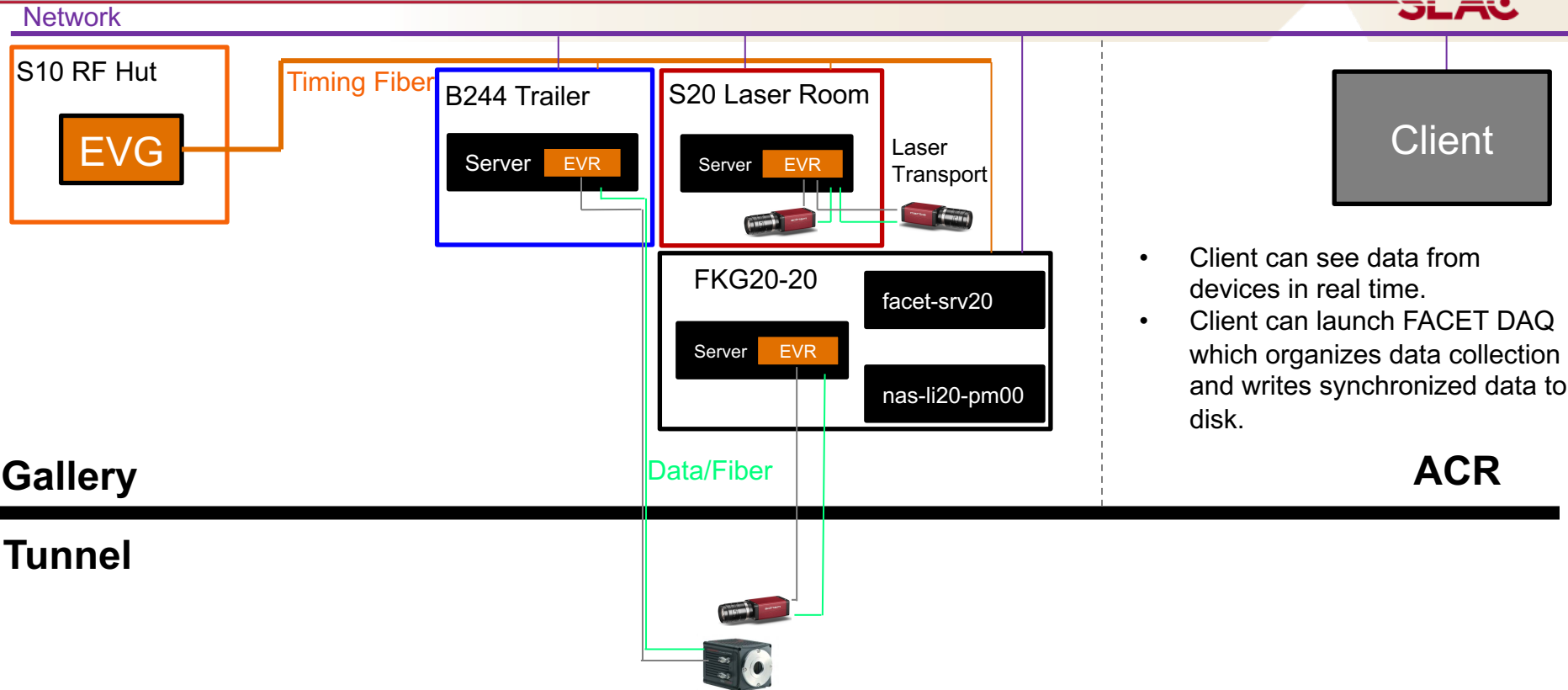
FACET-II Camera System

SLAC



FACET-II Camera System

SLAC

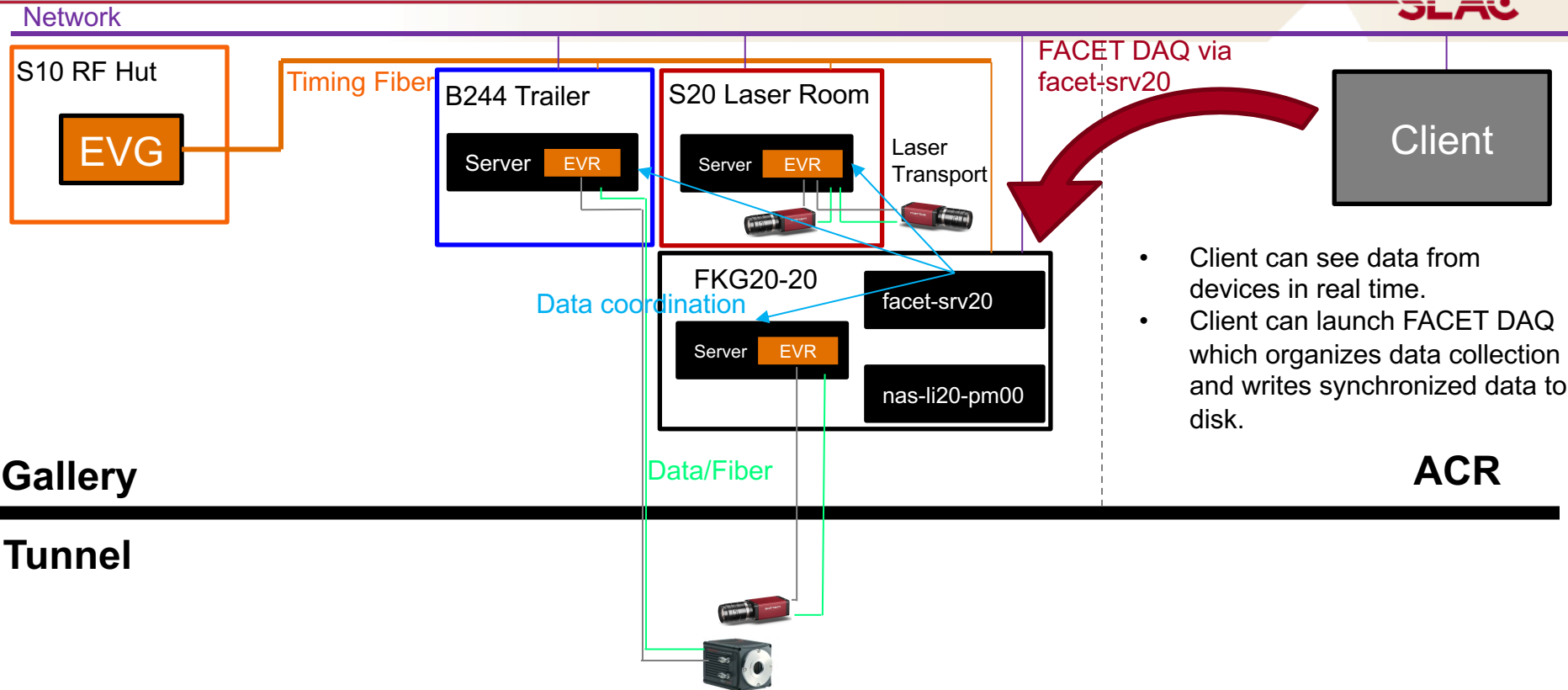


- Client can see data from devices in real time.
- Client can launch FACET DAQ which organizes data collection and writes synchronized data to disk.

ACR

FACET-II Camera System

SLAC

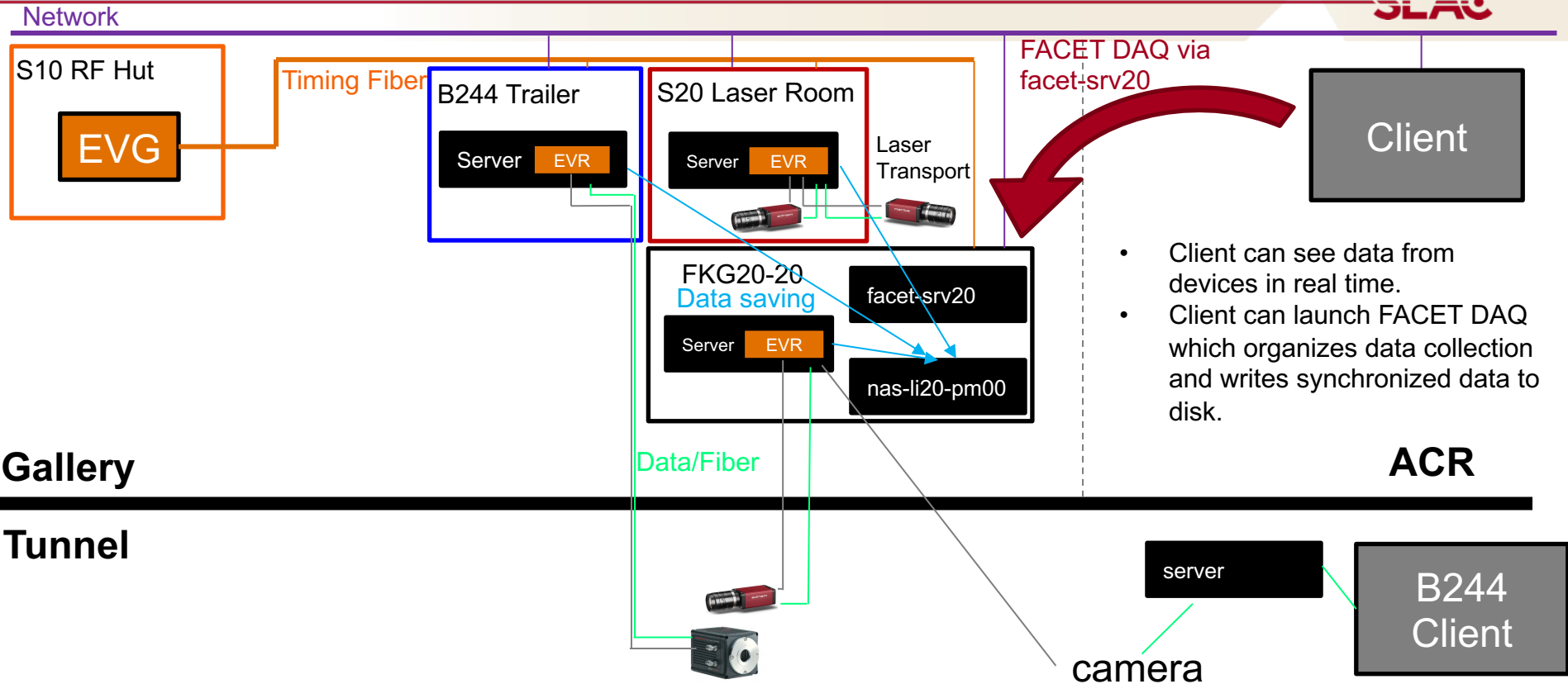


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FACET-II Camera System

SLAC



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