

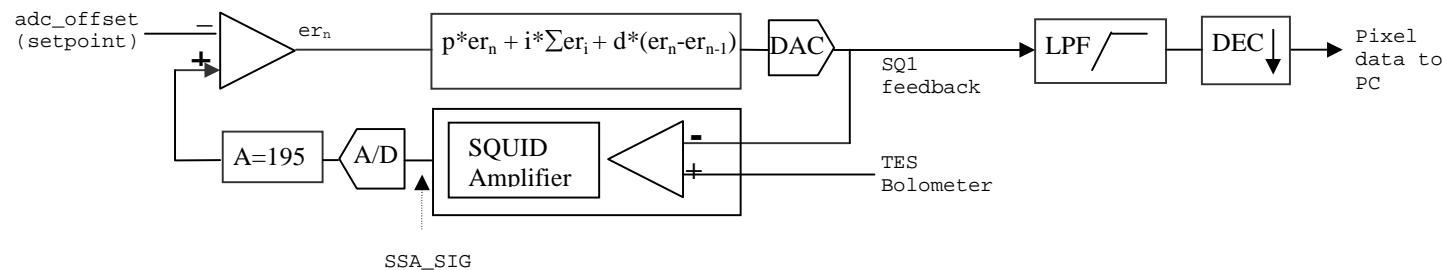
Servo mode:
0: const 1: const 2: ramp 3: PID servo

data mode:

0: error	1: pre-scale feedback	2: filtered fb	3: raw
4: 18b fb + 14b er	5: 24b fb+ 8b flux_cnt	7: 22b filtered fb + 10b er	
9: 24b filtered fb + 8b flux_cnt			

The SQUID Readout Servo Loop

A	gain of the preamp chain on readout-card
SSA_SIG	Series-array Signal from the cryostat, $\text{SSA_SIG} = a \cdot \cos((d+z) / 2\pi) + \text{offset1}$ where z is the phase-shift introduced by trapped flux offset1 is the overall shift of output from zero
LPF	Low-pass filter with $f_{3\text{dB}}=100\text{Hz}$ when $f_s=12195$ ($50\text{MHz}/(\text{row_len} \cdot \text{num_rows}) = 50\text{MHz}/(100 \cdot 41)$)



MCE internal scaling factors

When servo_mode = 3 or PID calculation is activated, calculation result for feedback is internally stored as a 64b word. The following diagram shows different windowing parameters of the 64b result.

