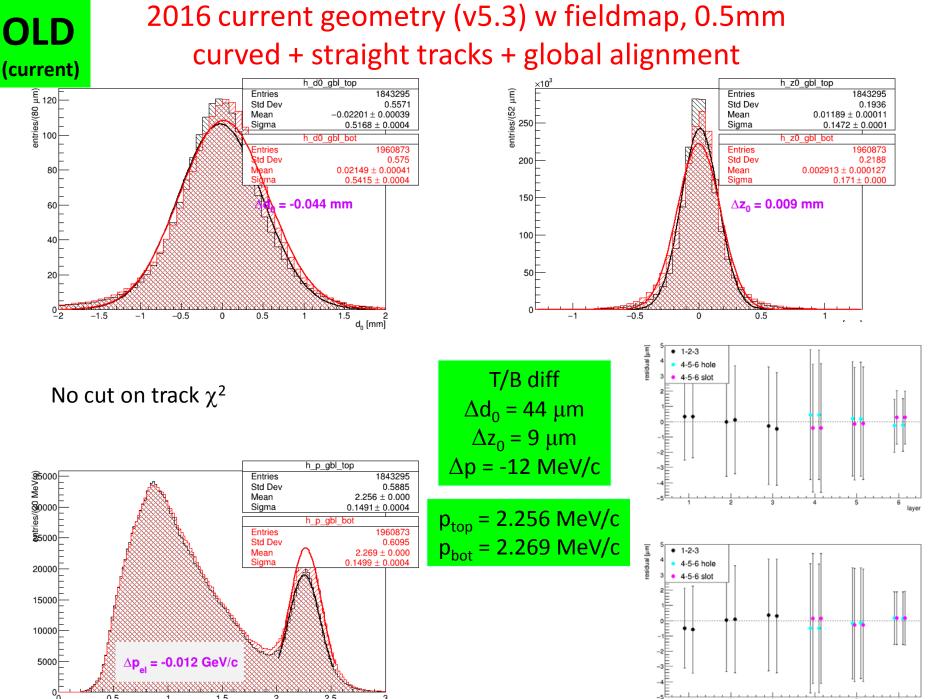
New alignments updates 2016 0.5 mm alignment

Alessandra Filippi March 26, 2018

2016 data @ 0.5 mm alignment

- Need to improve currently available detector (v 5.3)
- Start from scratch following the steps used for 2015 data + additional sensors free to float (max 2 at a time)
 - Curved + straight tracks
 - Two independent versions: my own + Mariangela's
 - Merged to get the best of the two (Mariangela's works better for bottom tracks)
- 2-3 final versions to compare with current one
- Need to check final resolution to decide which is the best one
 - Still not perfect: sensor 4 problematic (as always)

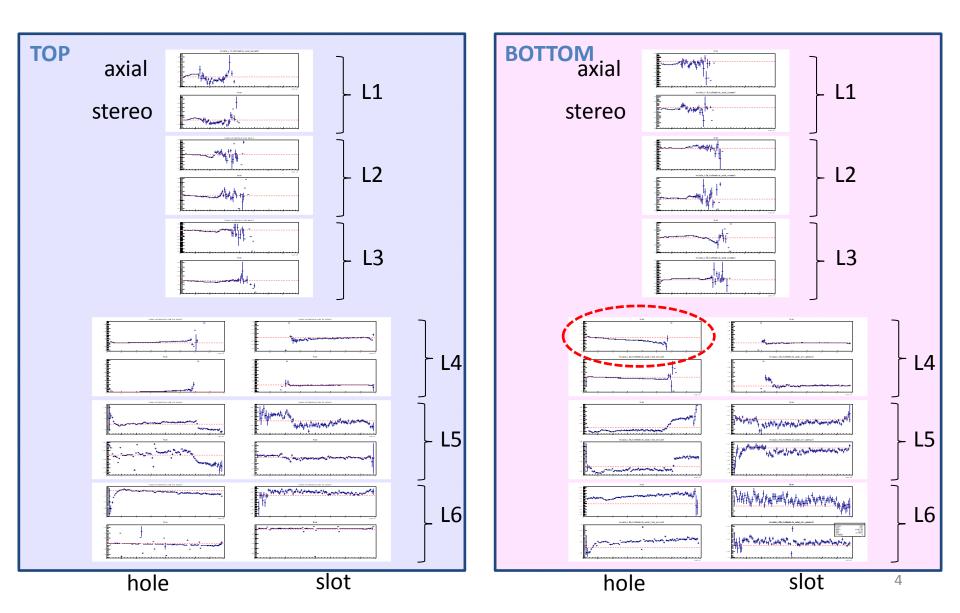


2 2.5 track momentum [GeV/c]

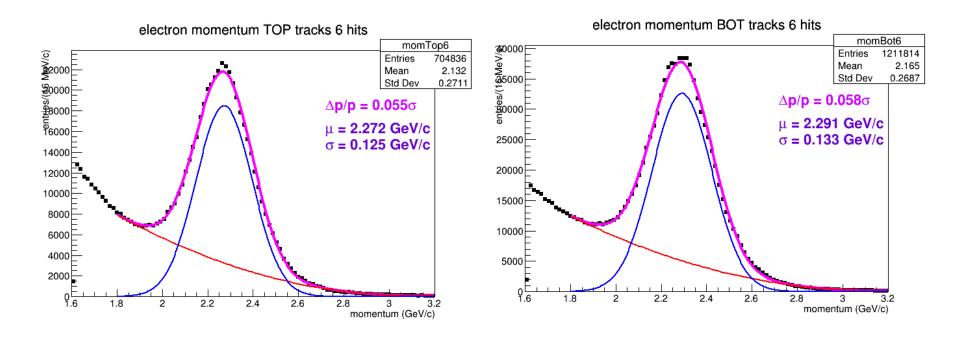
0.5

1.5

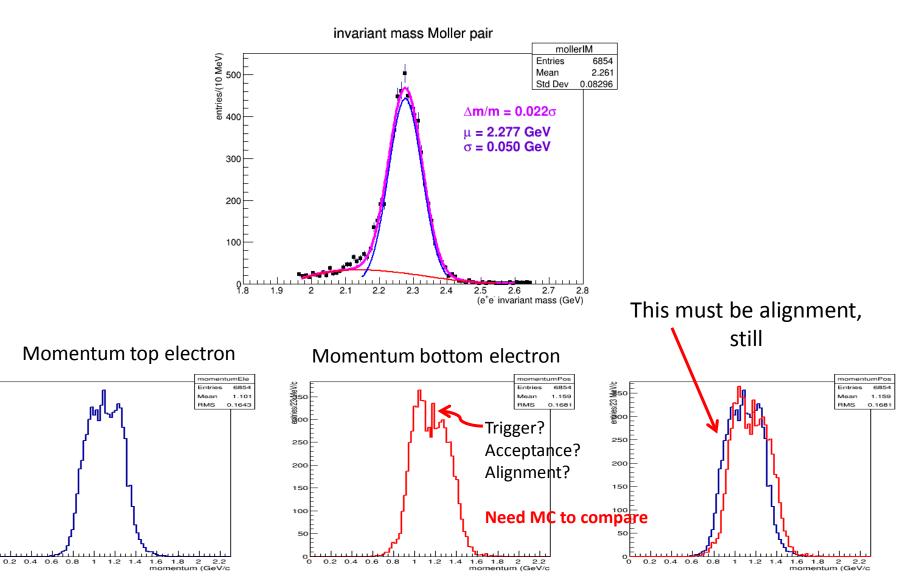
Current best geometry 2016 (v5.3) GBL u residuals vs v position, curved tracks



Current best geometry 2016 (v5.3) Resolution on elastic events

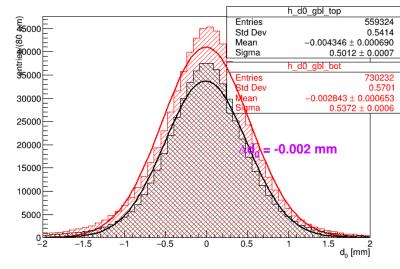


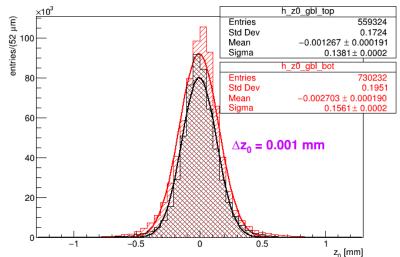
Current best geometry 2016 (v5.3) Resolution on Moller events



entries/23 MeV/c

v5.7 detector w fieldmap, 0.5mm curved + straight tracks + global alignment

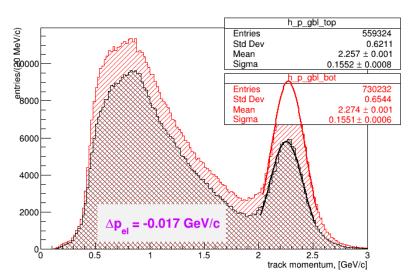




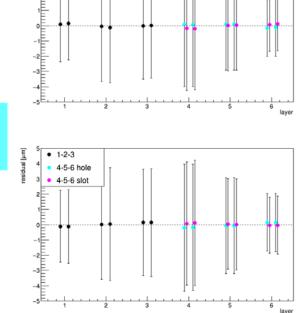
1-2-3
4-5-6 hole

4-5-6 slot

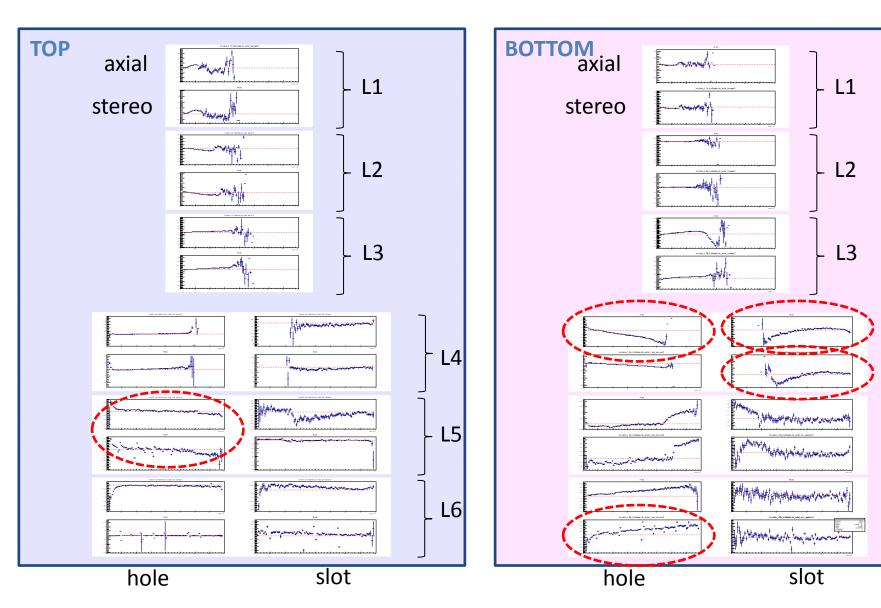
Cut on track χ^2 (<40)







V5.7 detector 2017 GBL u residuals vs v position, curved tracks

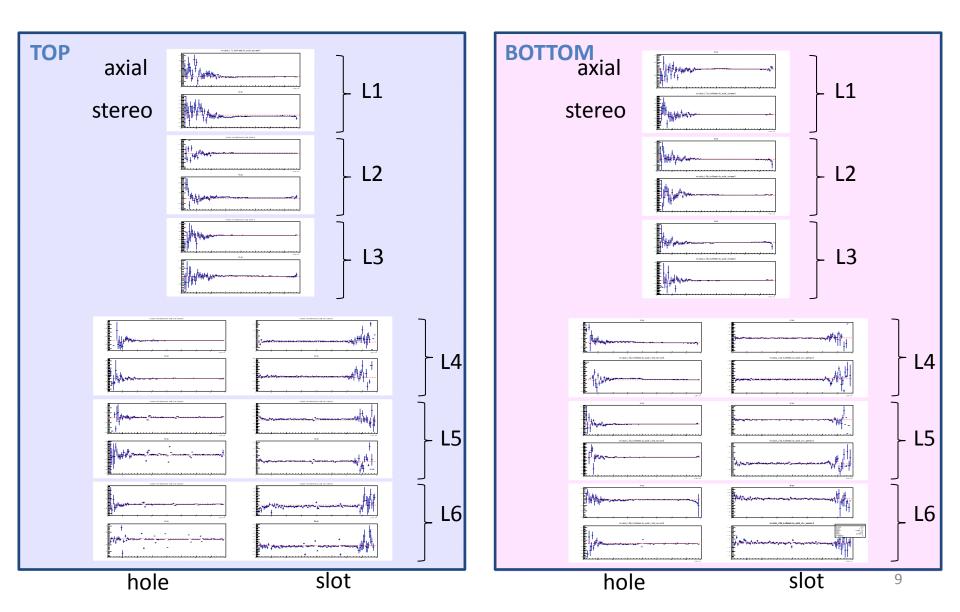


L4

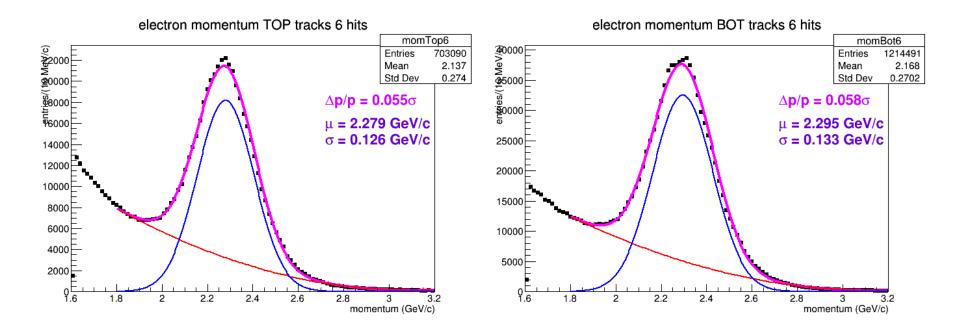
L5

L6

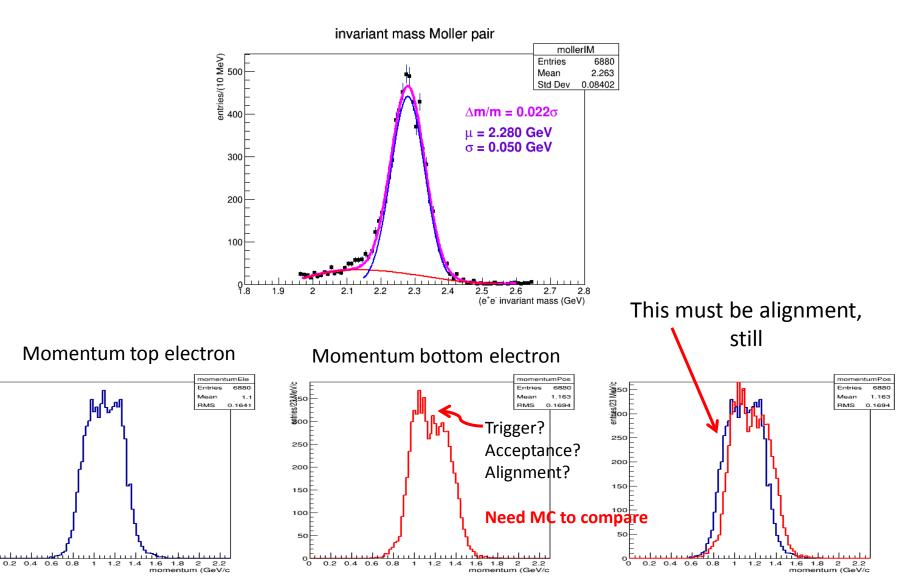
V5.7 2016 detector GBL u residuals vs v position, straight tracks



New detector 2016 v5.7 Resolution on elastic events

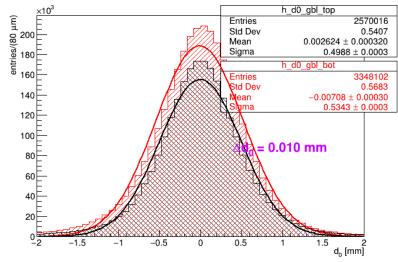


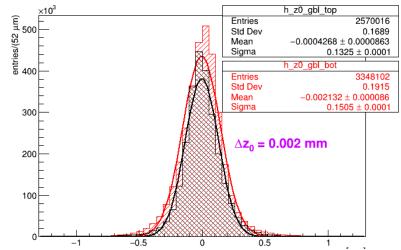
Current best geometry 2016 (v5.7) Resolution on Moller events



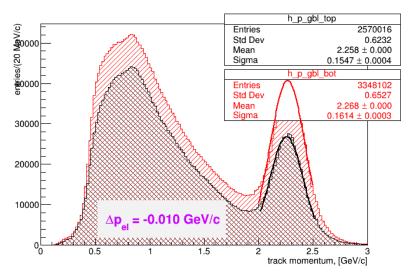
entrijes/23 MeV/c

V5.11 2016 detector w fieldmap, 0.5mm curved + straight tracks + global alignment

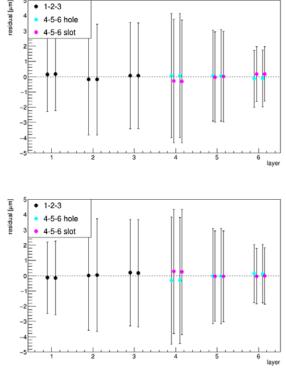




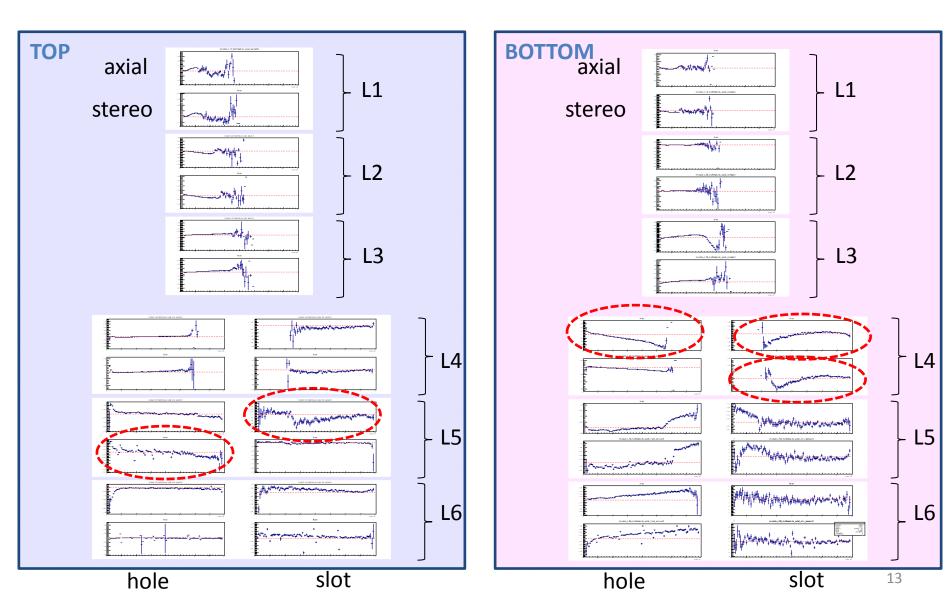
Cut on track χ^2 (<40) Global alignment can be easily Improved with one more iteration



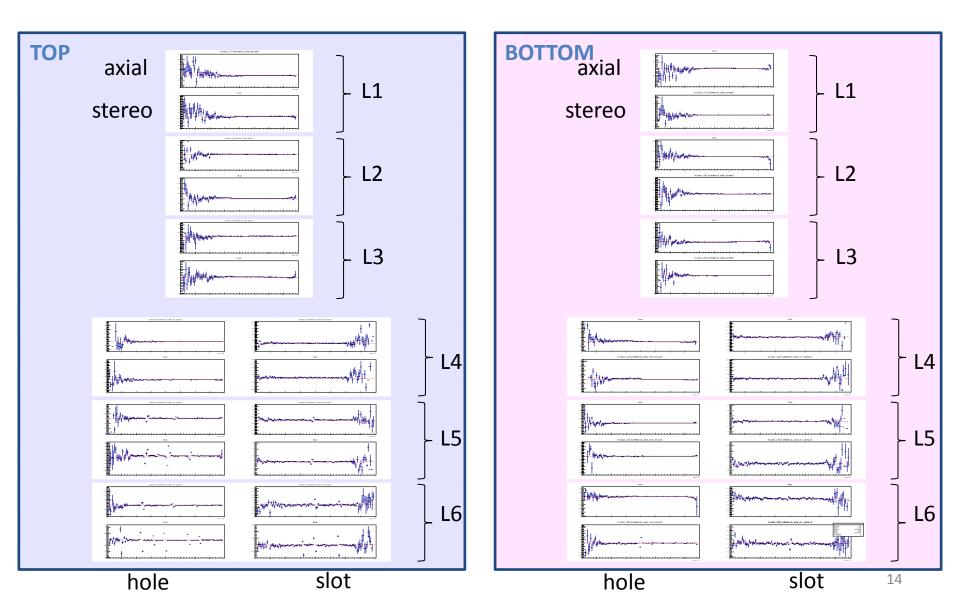




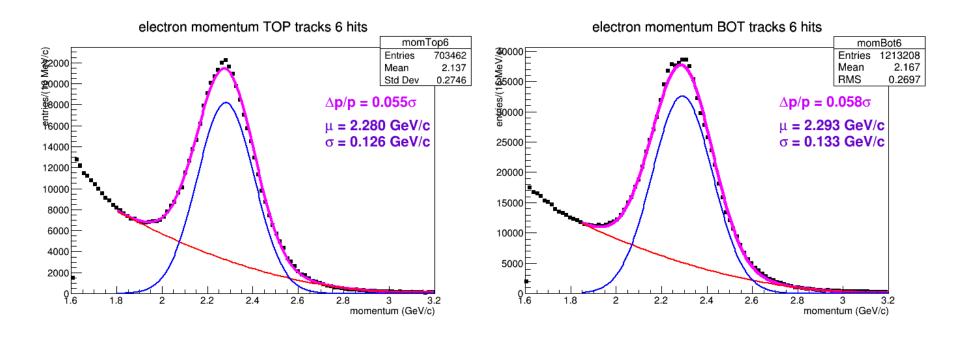
V5.11 2016 detector GBL u residuals vs v position, curved tracks



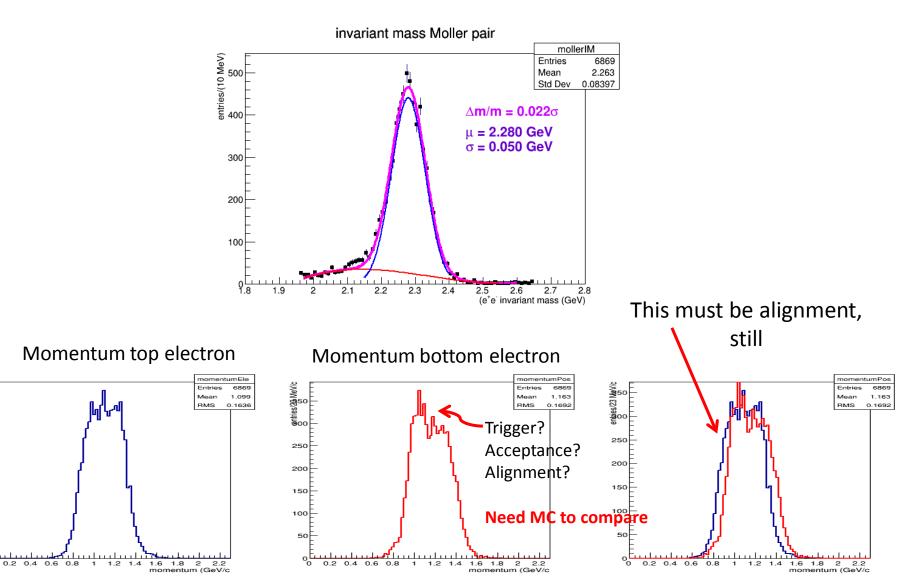
v.11 2016 detectors GBL u residuals vs v position, **straight tracks**



New detector 2016 v5.11 Resolution on elastic events

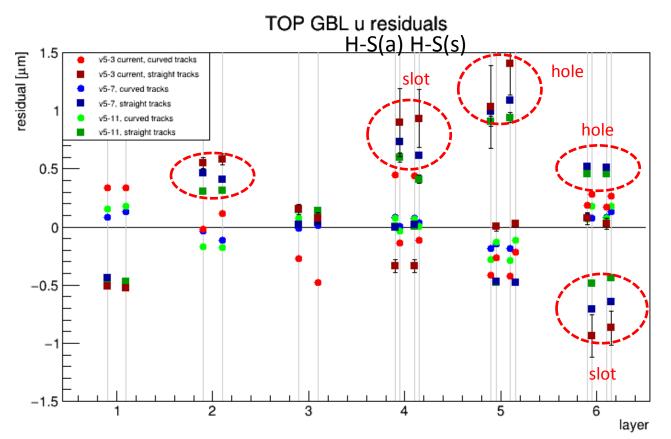


Current best geometry 2016 (v 5.11) Resolution on Moller events



entries/23 MeV/c

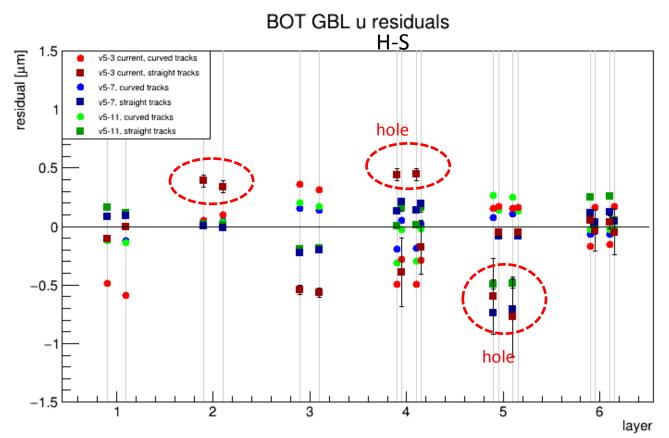
Comparison of u residuals TOP (GBL) curved & straight tracks



Current detector: red points Squares: straight tracks Circles: curved tracks Errors: residual σ

General improvement with new detectors Straight tracks always worse

Comparison of u residuals TOP (GBL) curved & straight tracks



Current detector: red points Squares: straight tracks Circles: curved tracks Errors: residual σ

General improvement with new detectors Better as compared to top spread Straight tracks always worse, exp. Hole side

Figures of merit – summary

- Straight tracks u residuals
 - could be better, worse than with curved tracks in general
- Straight tracks u residuals vs v
 - ALL OK
- Curved tracks u residuals
 - Satisfactory, largely within 1 um
- Curved tracks u residuals vs v
 - sensor 4 slot worst of all (as usual)
- Impact parameters not really relevant they can be adjusted with global alignment (2-3 iterations max) without sensible effects on momentum and resolution
- Elastic peak momentum
 - Top tracks: same for all, 5.5%σ
 - Bottom tracks: same for all, $5.8\%\sigma$
- Moller resolution (invariant mass or total momentum)
 - Same for all: $2.2\%\sigma$

		N evts top	N evts bot	Res elastic peak top (σ)	Res elastic peak bot (σ)	N events Moller	Res Moller invariant mass (σ)
	V 5.3	704836	1211814	5.5%	5.8%	6854	2.2%
	V 5.7	703090	1214491	5.5%	5.8%	6680	2.2%
	V 5.11	703462	1213208	5.5%	5.8%	6869	2.2%

- Do we have some references to compare? A set of standard cuts? A comparison with MC data?
- ... no easy way to choose the best detector (and this is almost likely a -fake- relative minimum)