

New alignments updates 2016 0.5 mm alignment

Alessandra Filippi

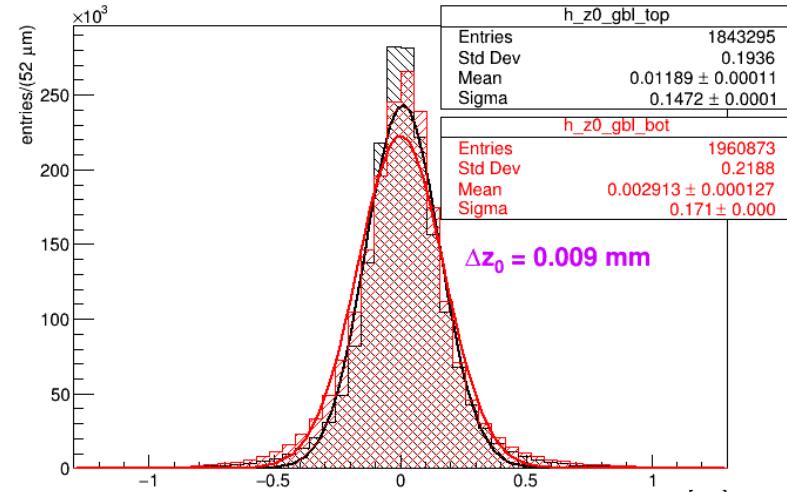
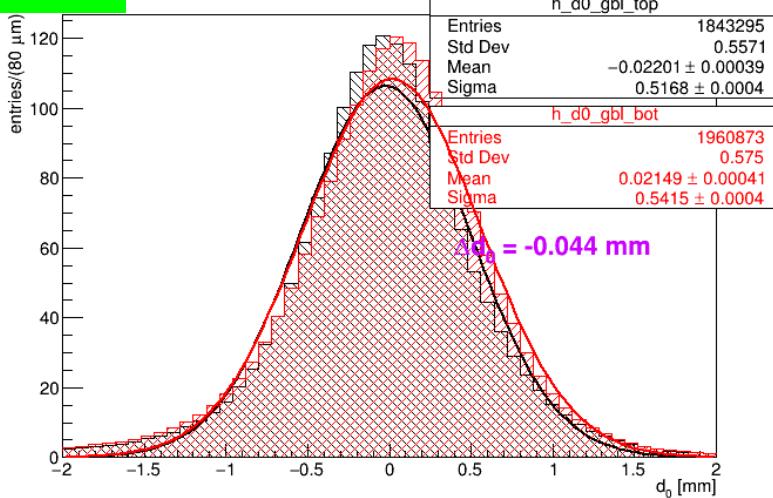
March 26, 2018

2016 data @ 0.5 mm alignment

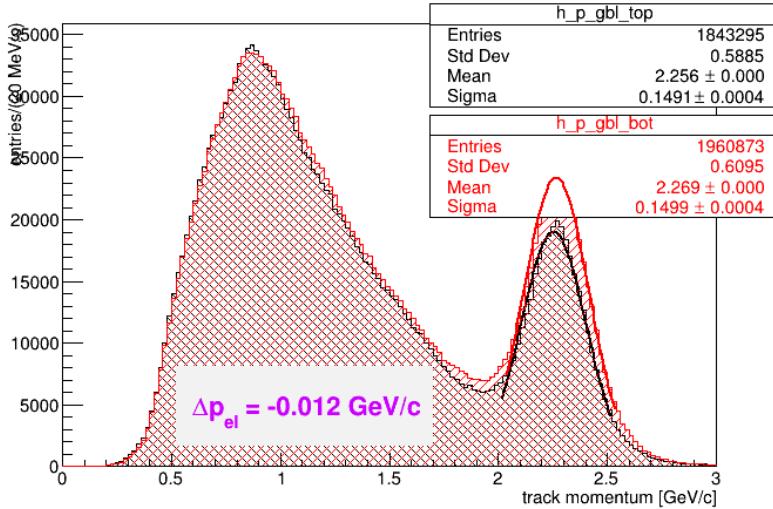
- Need to improve currently available detector (v 5.3)
- Start from scratch following the steps used for 2015 data + additional sensors free to float (max 2 at a time)
 - Curved + straight tracks
 - Two independent versions: my own + Mariangela's
 - Merged to get the best of the two (Mariangela's works better for bottom tracks)
- 2-3 final versions to compare with current one
- Need to check final resolution to decide which is the best one
 - Still not perfect: sensor 4 problematic as ever

OLD
(current)

2016 current geometry (v5.3) w fieldmap, 0.5mm curved + straight tracks + global alignment

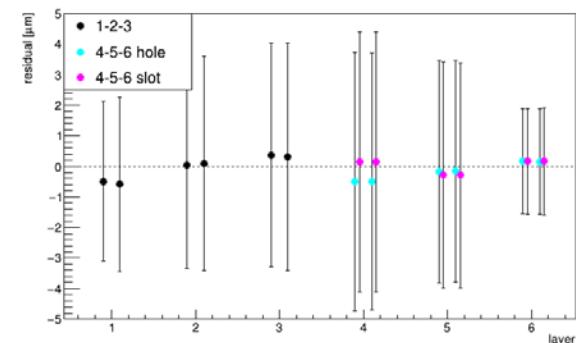
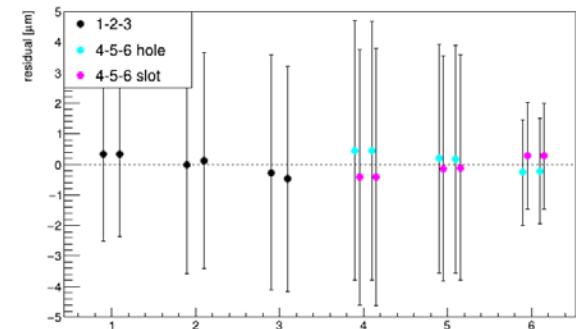


No cut on track χ^2



T/B diff
 $\Delta d_0 = 44 \mu\text{m}$
 $\Delta z_0 = 9 \mu\text{m}$
 $\Delta p = -12 \text{ MeV/c}$

$p_{top} = 2.256 \text{ MeV/c}$
 $p_{bot} = 2.269 \text{ MeV/c}$

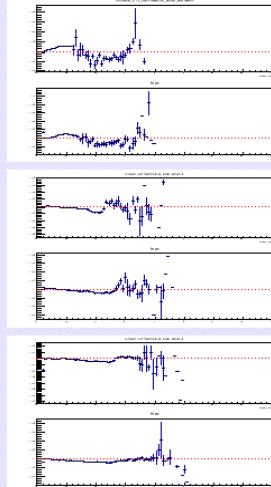


Current best geometry 2016 (v5.3)

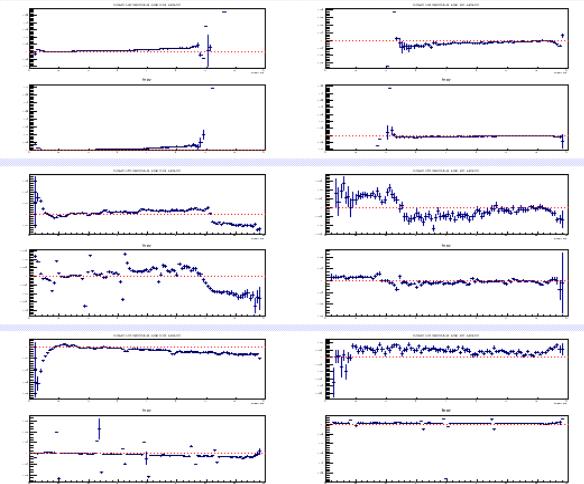
GBL u residuals vs v position, curved tracks

TOP

axial
stereo



L1
L2
L3



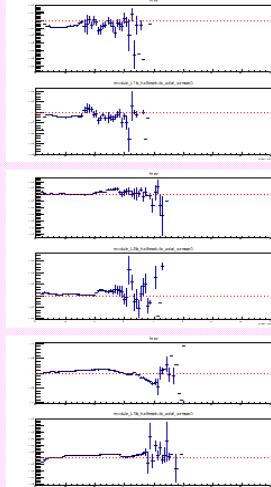
L4
L5
L6

hole

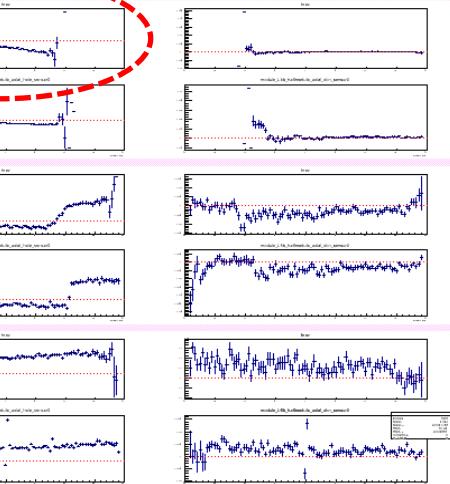
slot

BOTTOM

axial
stereo



L1
L2
L3



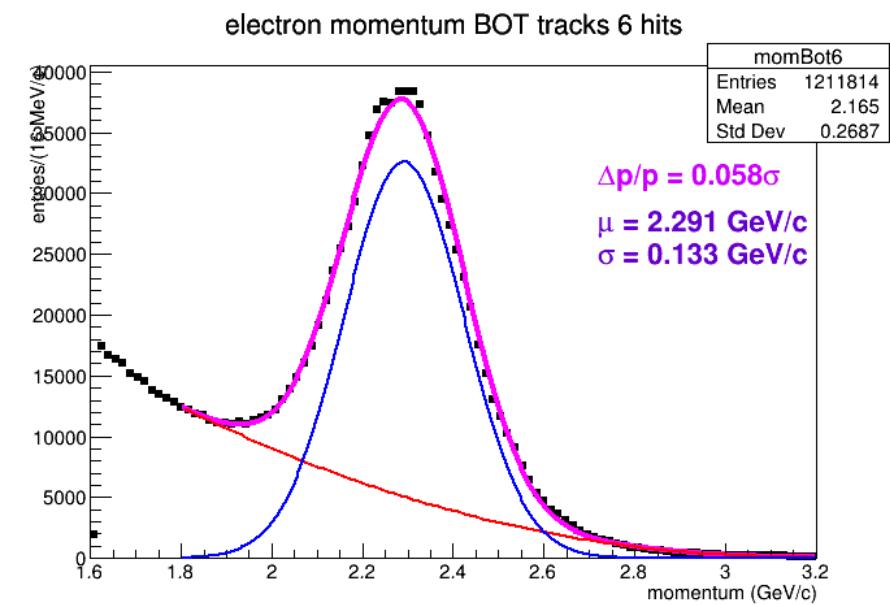
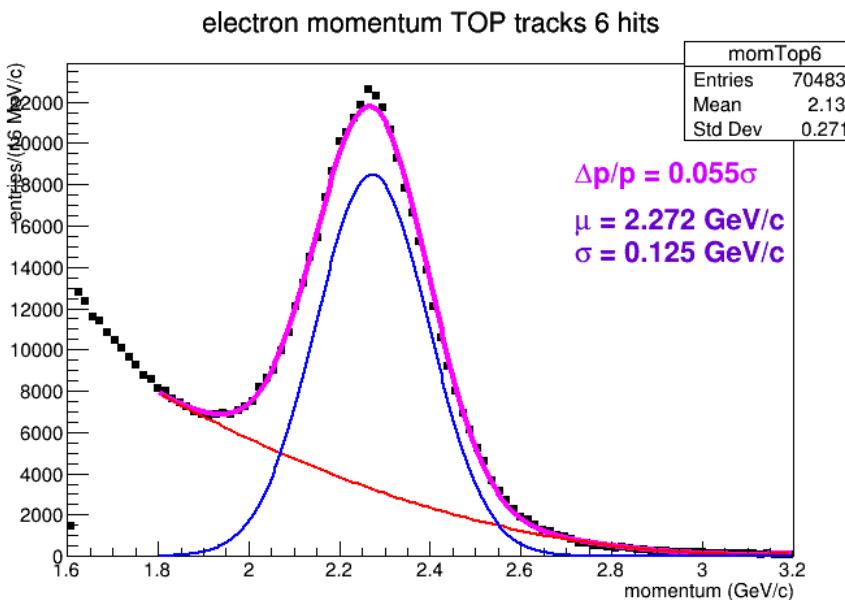
L4
L5
L6

hole

slot

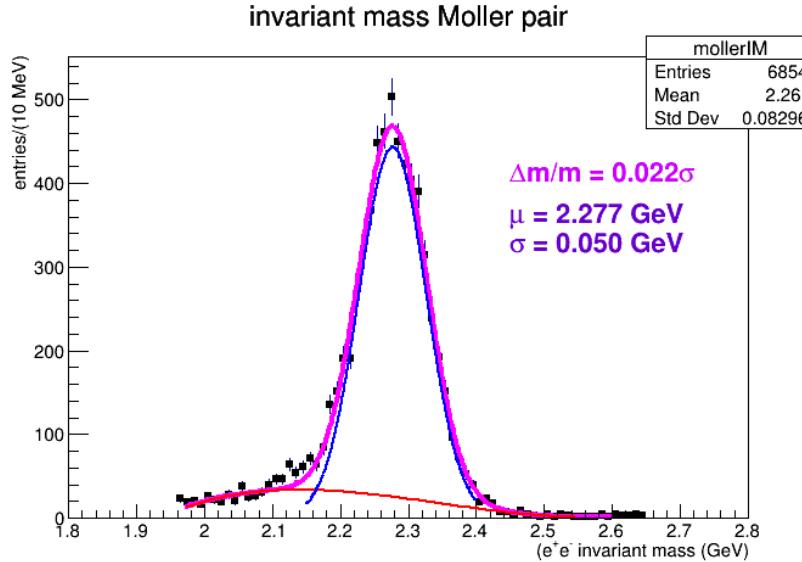
Current best geometry 2016 (v5.3)

Resolution on elastic events

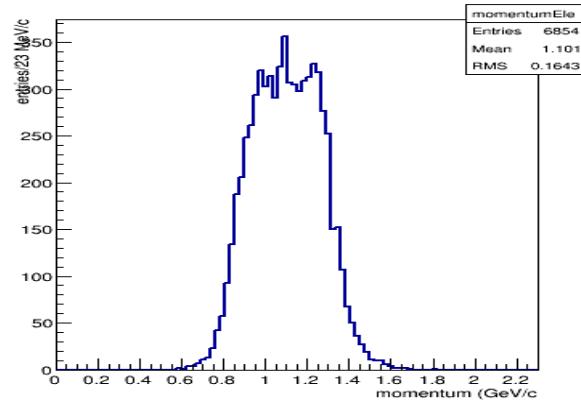


Current best geometry 2016 (v5.3)

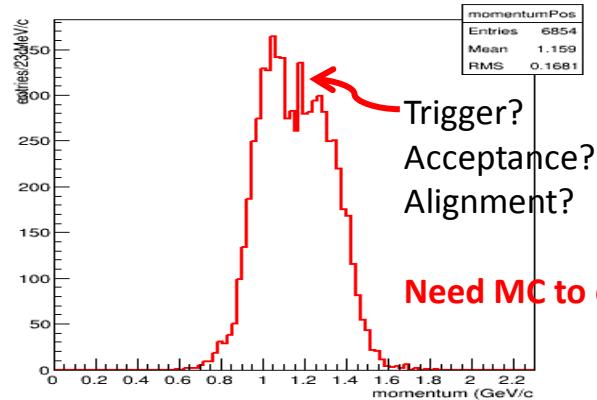
Resolution on Moller events



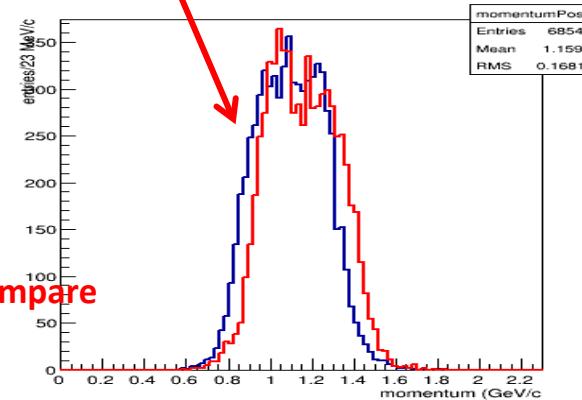
Momentum top electron



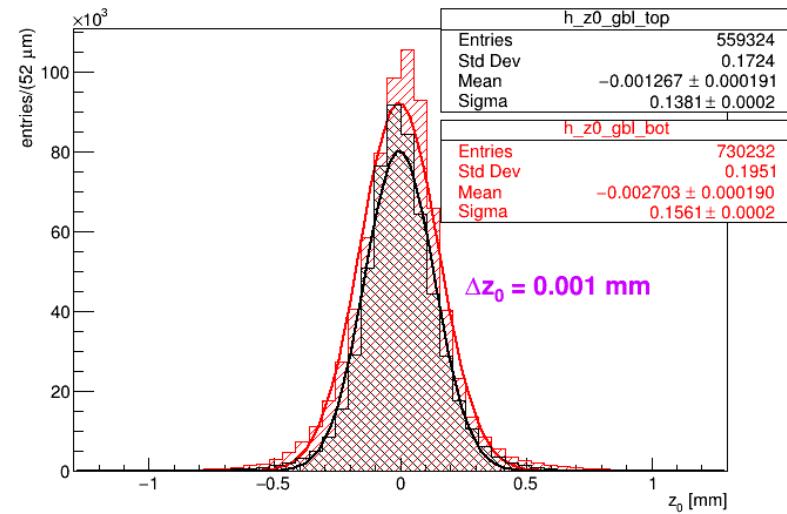
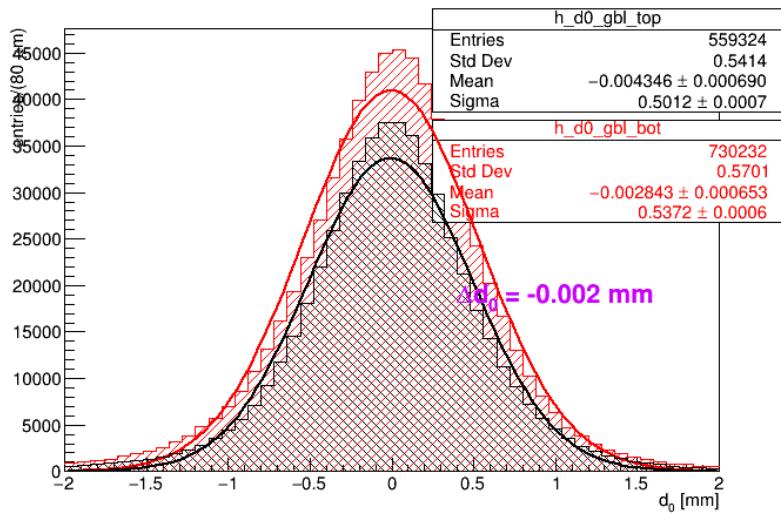
Momentum bottom electron



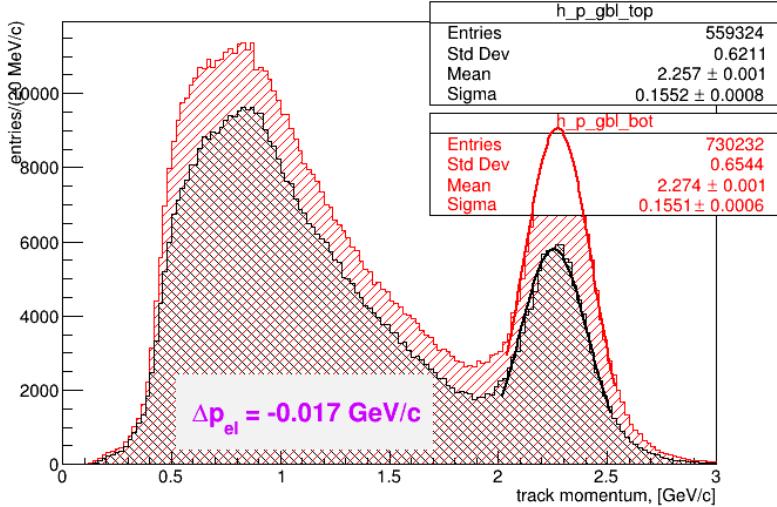
This must be alignment,
still



v5.7 detector w fieldmap, 0.5mm curved + straight tracks + global alignment

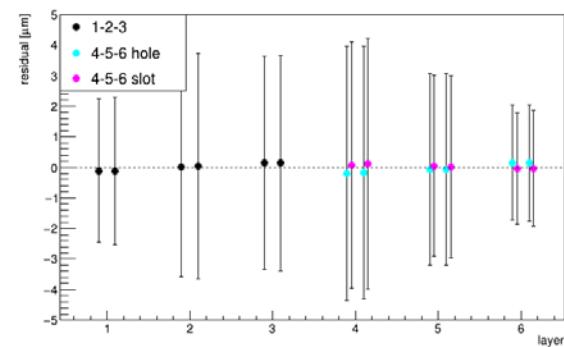
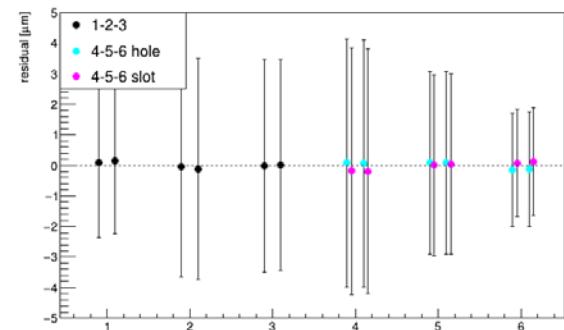


Cut on track $\chi^2 (< 40)$



T/B diff
 $\Delta d_0 = 2 \mu\text{m}$
 $\Delta z_0 = 1 \mu\text{m}$
 $\Delta p = -17 \text{ MeV/c}$

$p_{top} = 2.257 \text{ MeV/c}$
 $p_{bot} = 2.274 \text{ MeV/c}$

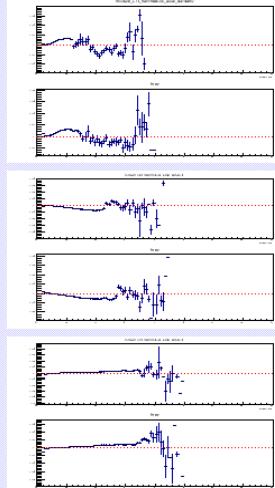


V5.7 detector 2017

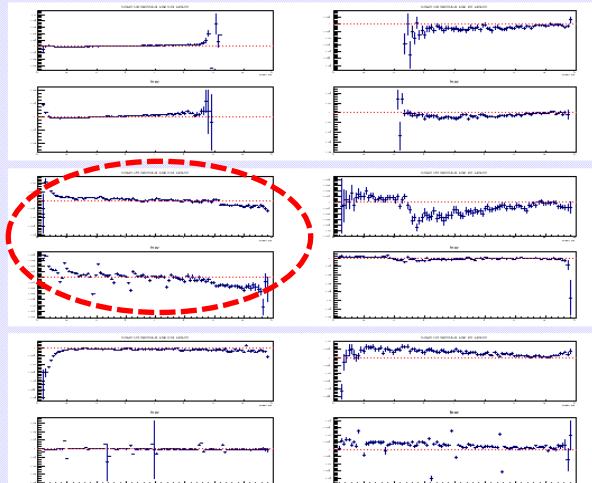
GBL u residuals vs v position, curved tracks

TOP

axial
stereo



L1
L2
L3



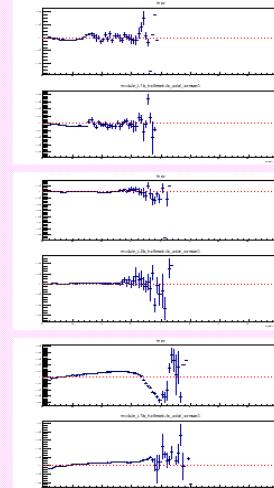
L4
L5
L6

hole

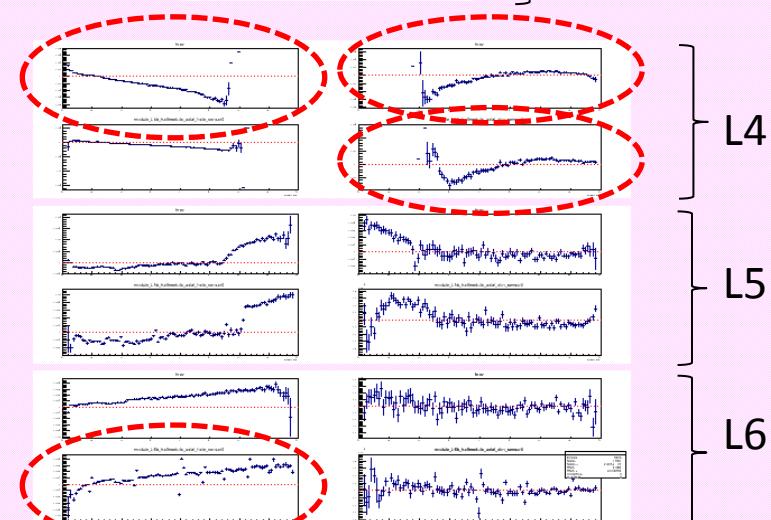
slot

BOTTOM

axial
stereo



L1
L2
L3



hole

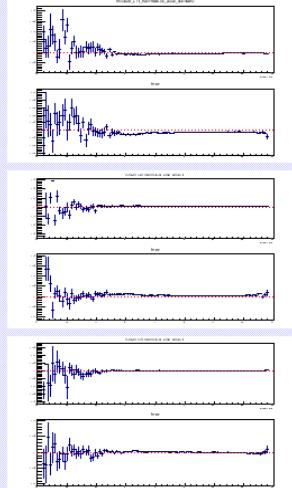
slot

V5.7 2016 detector

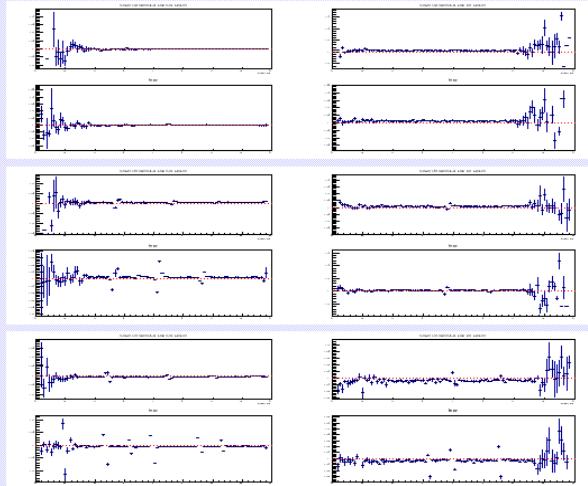
GBL u residuals vs v position, straight tracks

TOP

axial
stereo



L1
L2
L3



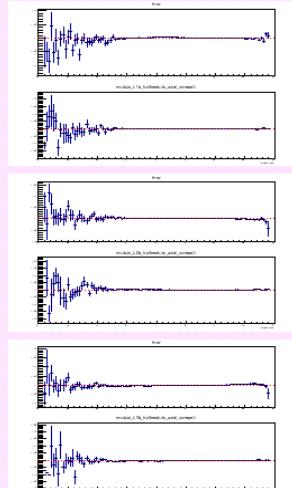
L4
L5
L6

hole

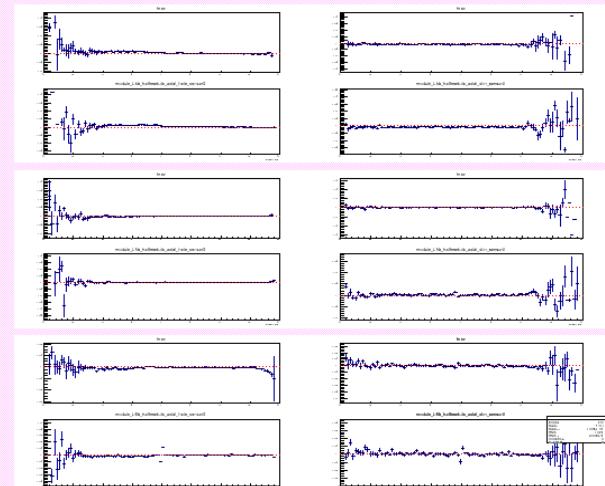
slot

BOTTOM

axial
stereo



L1
L2
L3



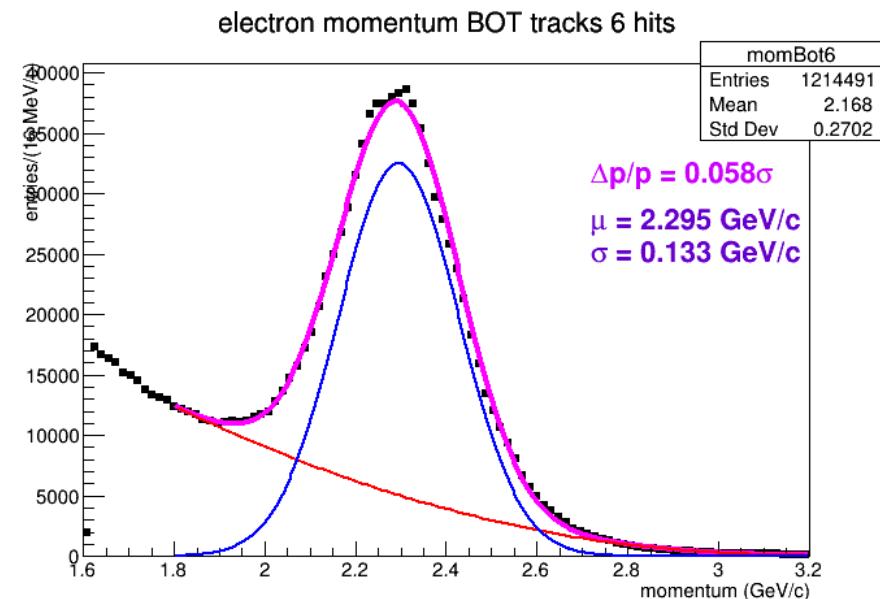
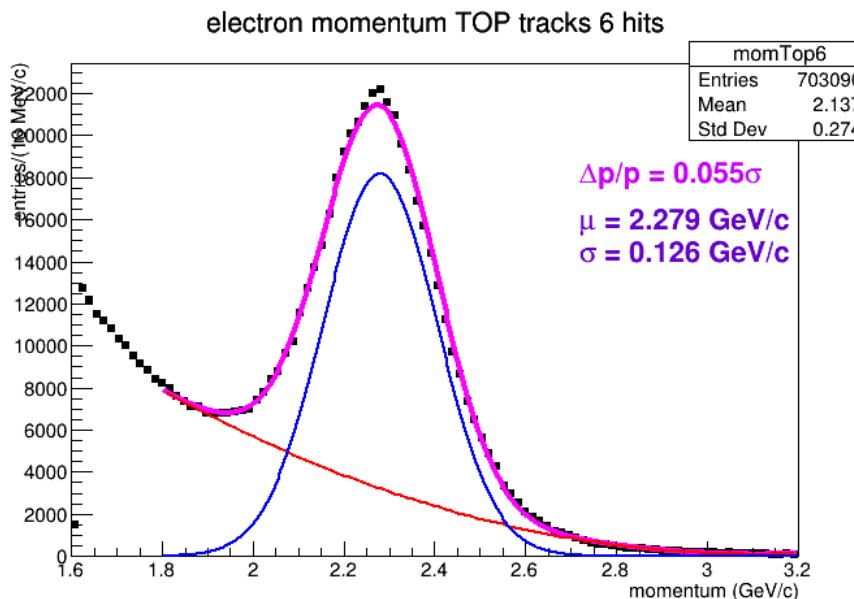
L4
L5
L6

hole

slot

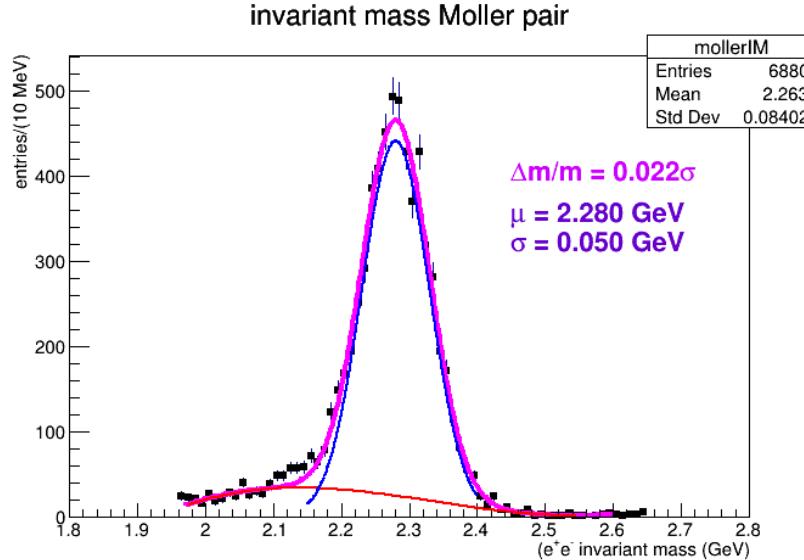
New detector 2016 v5.7

Resolution on elastic events

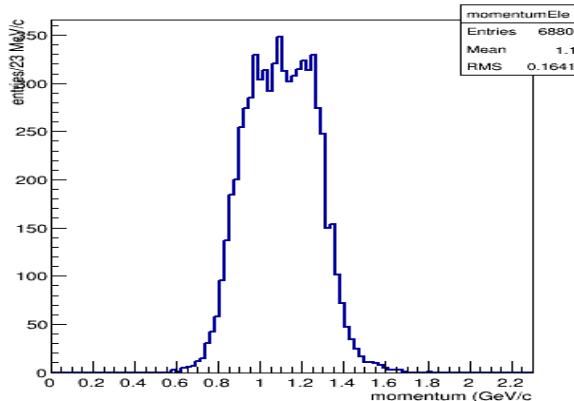


Current best geometry 2016 (v5.7)

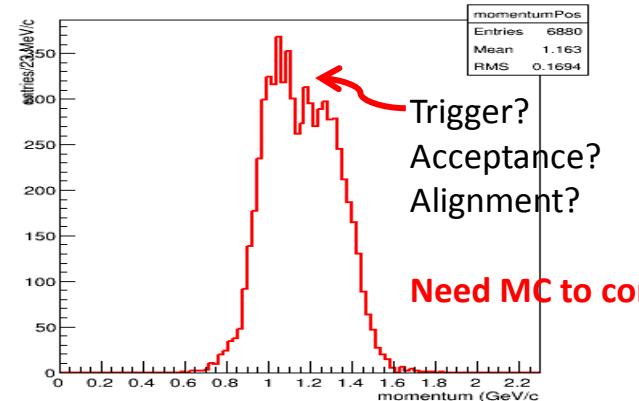
Resolution on Moller events



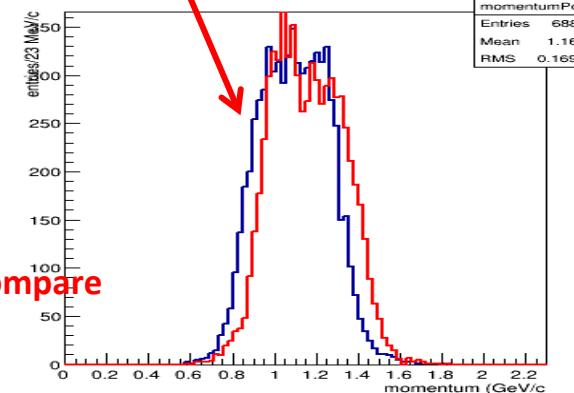
Momentum top electron



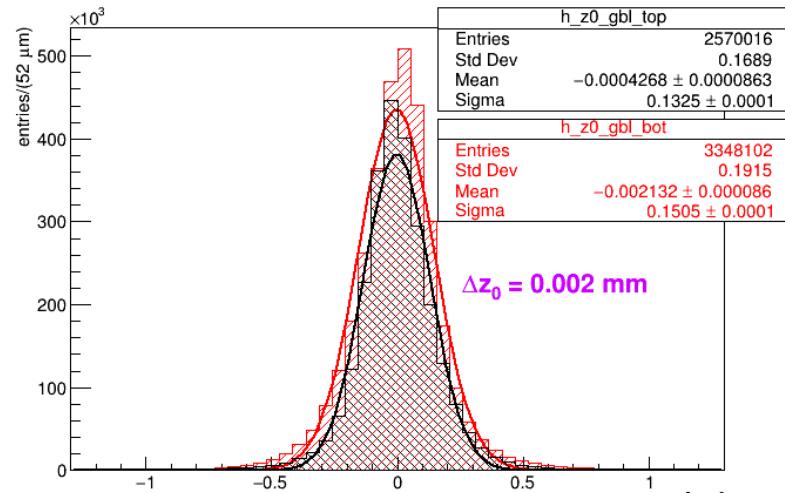
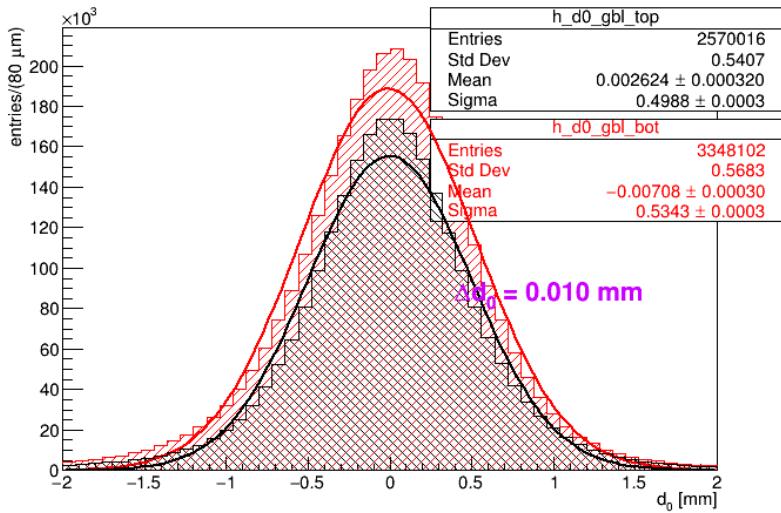
Momentum bottom electron



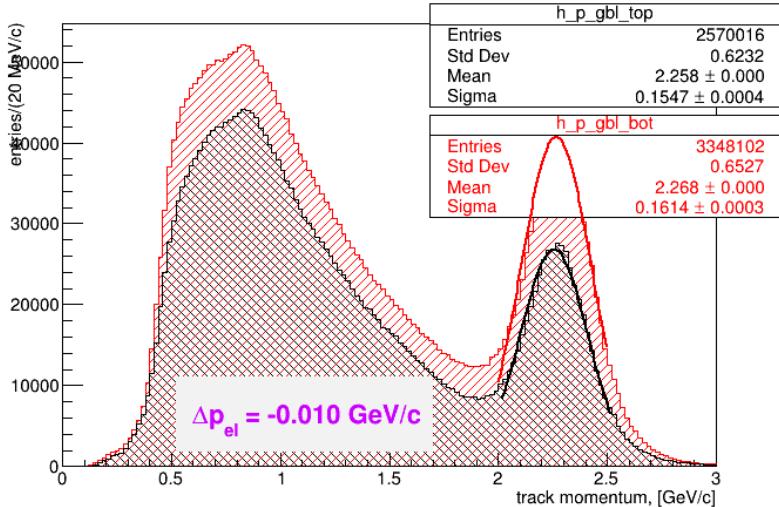
This must be alignment,
still



V5.11 2016 detector w fieldmap, 0.5mm curved + straight tracks + global alignment

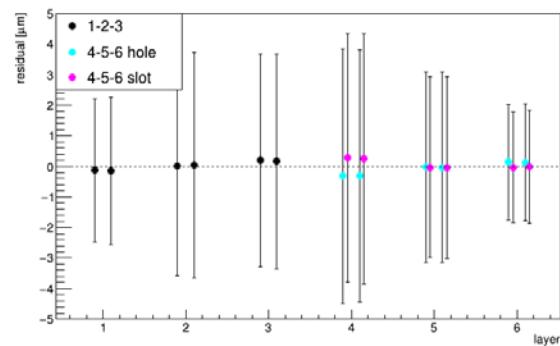
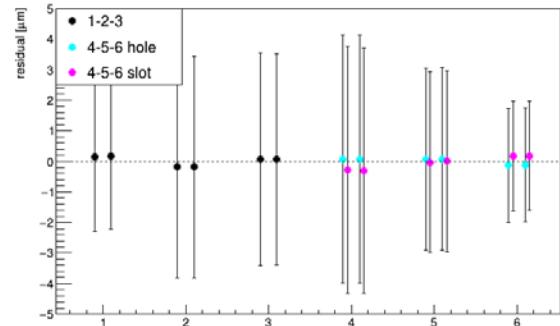


Cut on track $\chi^2 (< 40)$
 Global alignment can be easily
 Improved with one more iteration



T/B diff
 $\Delta d_0 = 10 \mu\text{m}$
 $\Delta z_0 = 2 \mu\text{m}$
 $\Delta p = -10 \text{ MeV}/c$

$p_{top} = 2.258 \text{ MeV}/c$
 $p_{bot} = 2.268 \text{ MeV}/c$

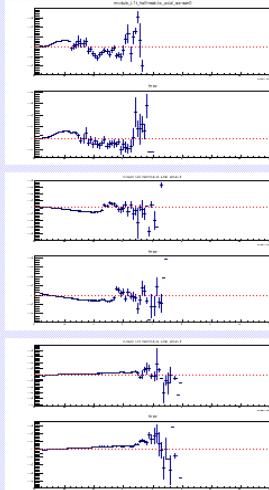


V5.11 2016 detector

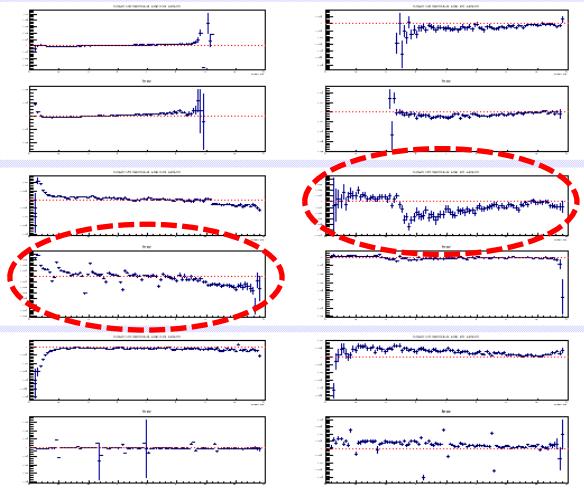
GBL u residuals vs v position, curved tracks

TOP

axial
stereo



L1
L2
L3



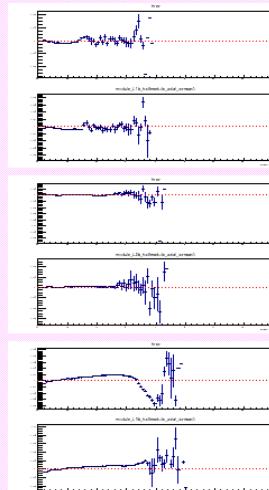
L4
L5
L6

hole

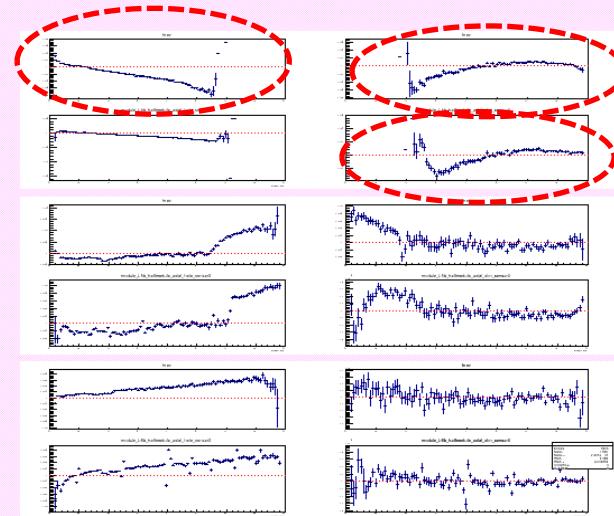
slot

BOTTOM

axial
stereo



L1
L2
L3



L4
L5
L6

hole

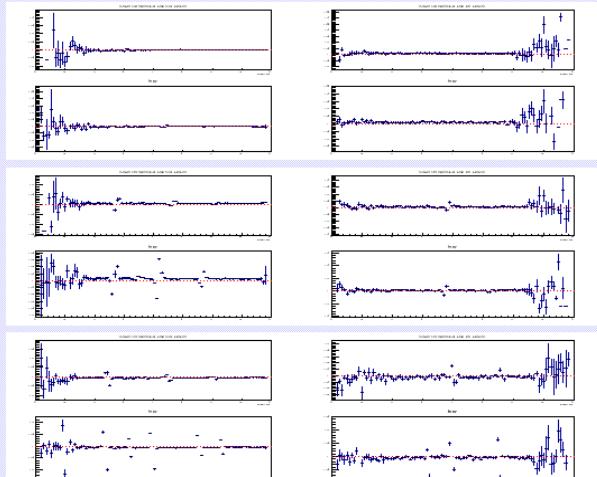
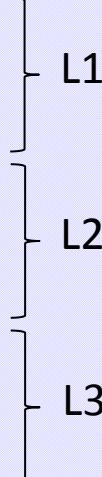
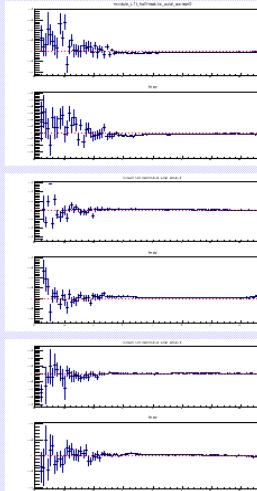
slot

v.11 2016 detectors

GBL u residuals vs v position, straight tracks



axial
stereo

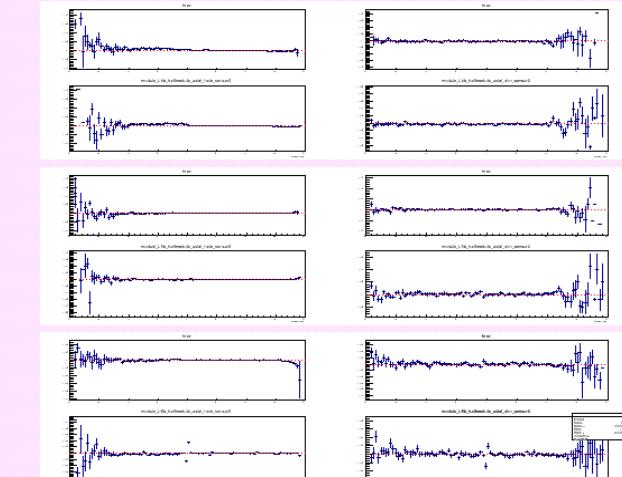
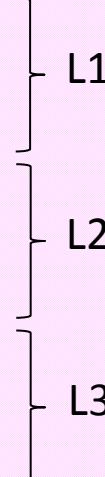
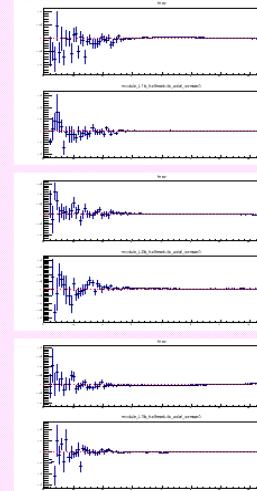


hole

slot

BOTTOM

axial
stereo

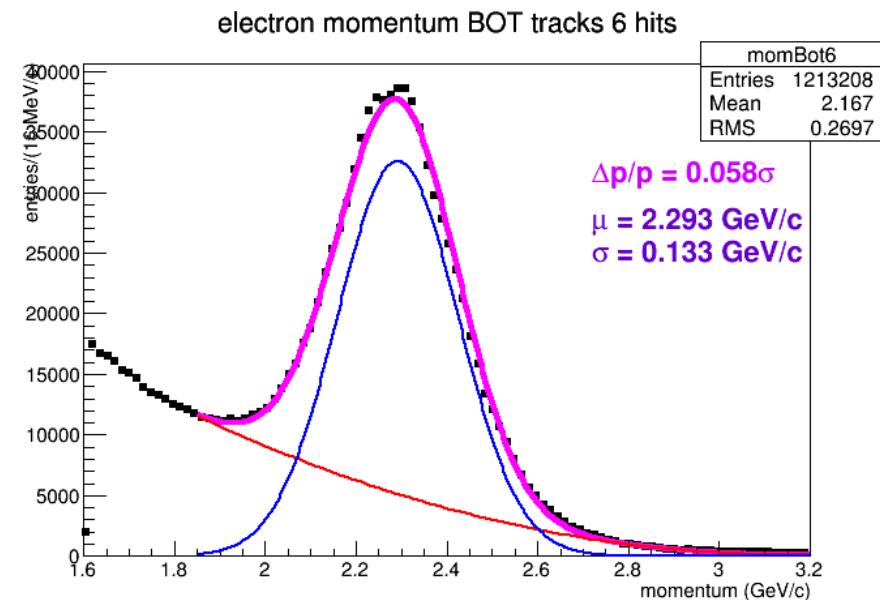
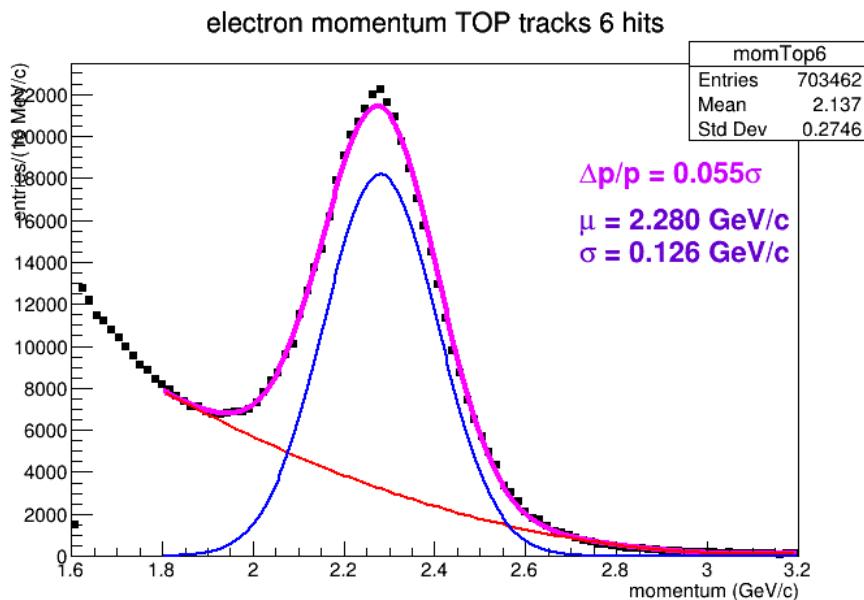


hole

slot

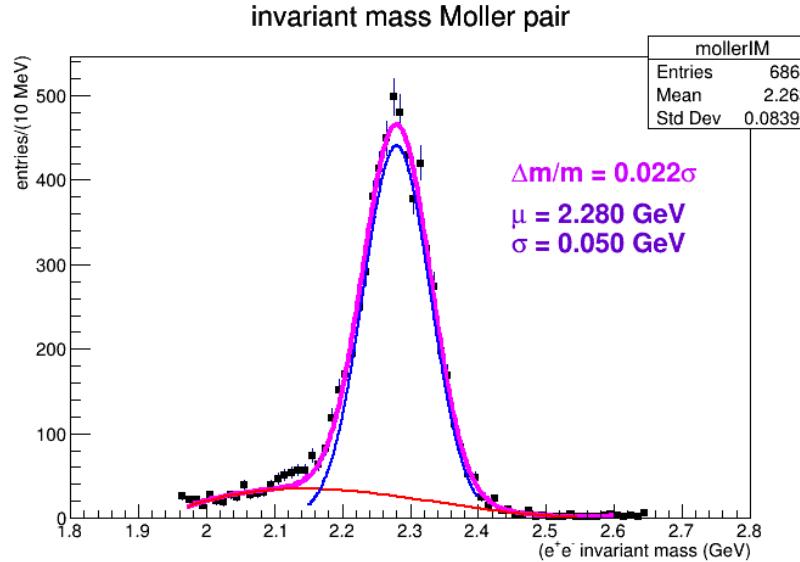
New detector 2016 v5.11

Resolution on elastic events

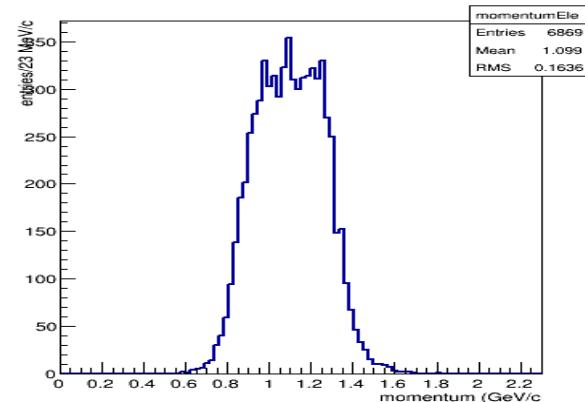


Current best geometry 2016 (v 5.11)

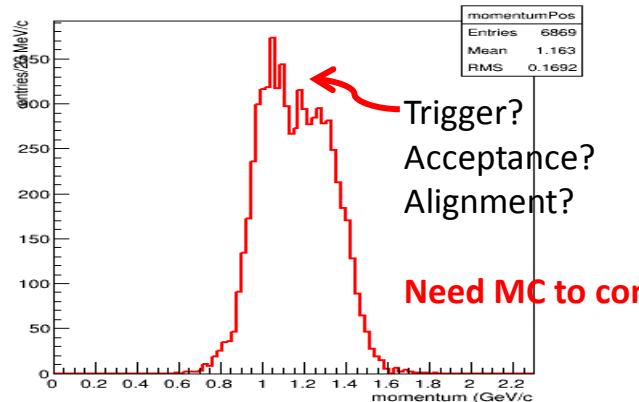
Resolution on Moller events



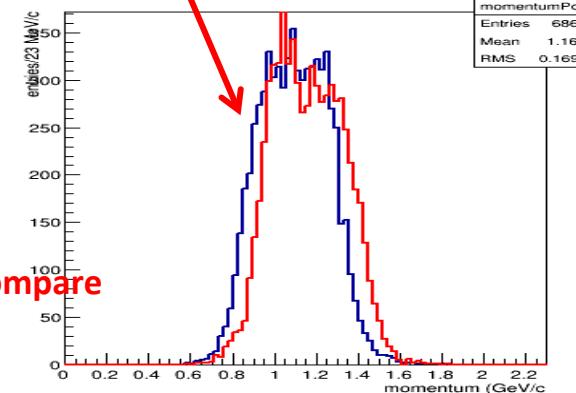
Momentum top electron



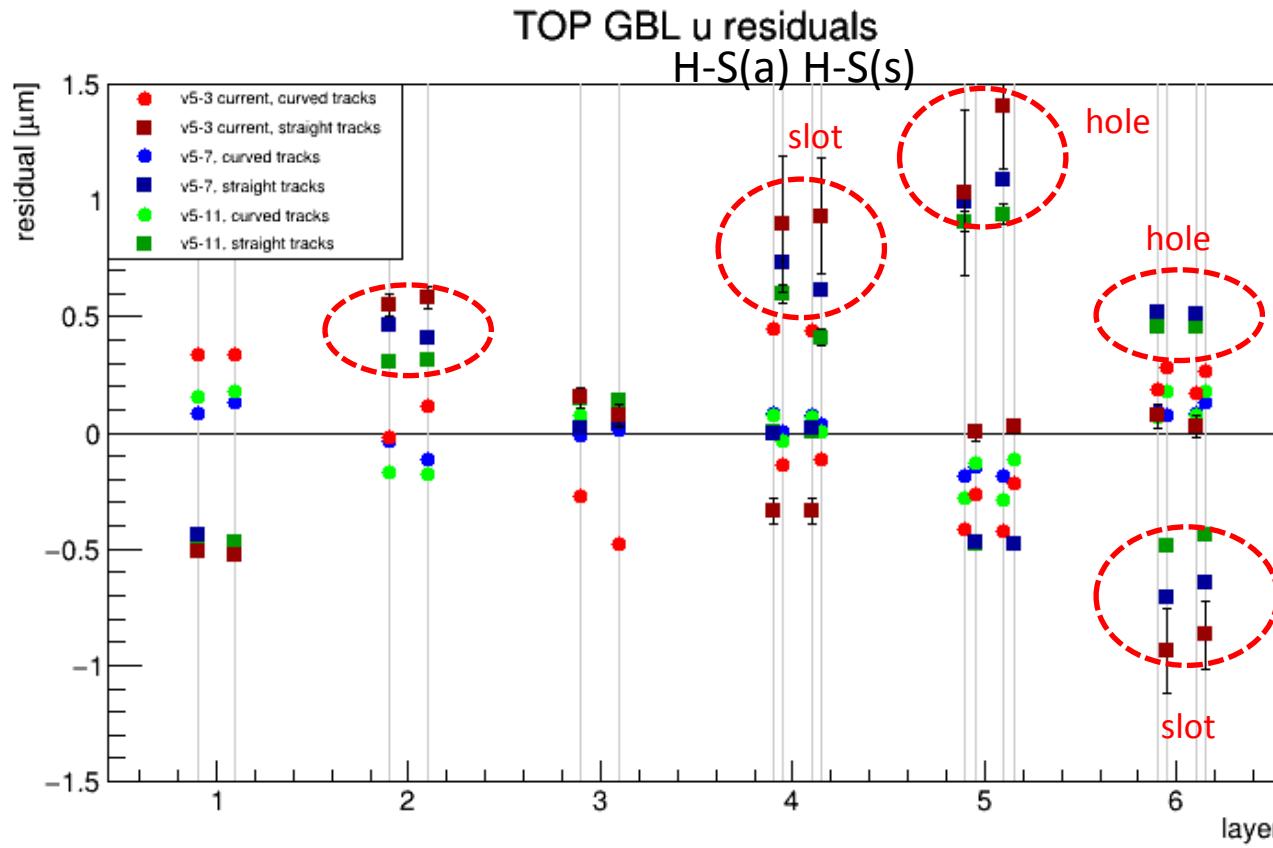
Momentum bottom electron



This must be alignment,
still



Comparison of u residuals TOP (GBL) curved & straight tracks



Current detector: red points

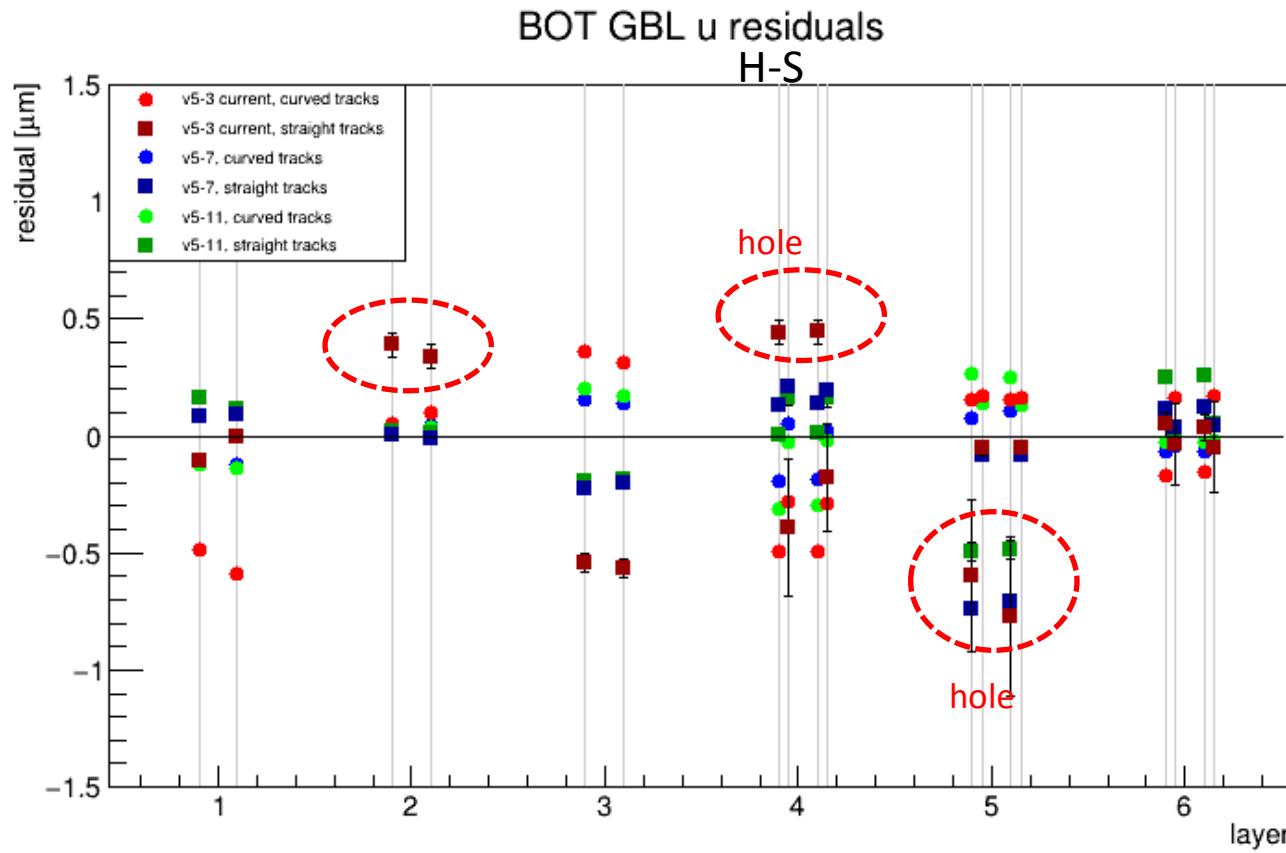
Squares: straight tracks

Circles: curved tracks

Errors: residual σ

General improvement with new detectors
Straight tracks always worse

Comparison of u residuals TOP (GBL) curved & straight tracks



Current detector: red points

Squares: straight tracks

Circles: curved tracks

Errors: residual σ

General improvement with new detectors
Better as compared to top spread
Straight tracks always worse, exp. Hole side

Figures of merit – summary

- Straight tracks u residuals
 - could be better, worse than with curved tracks in general
- Straight tracks u residuals vs v
 - ALL OK
- Curved tracks u residuals
 - Satisfactory, largely within 1 um
- Curved tracks u residuals vs v
 - sensor 4 slot worst of all (as usual)
- Impact parameters not really relevant – they can be adjusted with global alignment (2-3 iterations max) without sensible effects on momentum and resolution

- Elastic peak momentum
 - Top tracks: same for all, $5.5\%\sigma$
 - Bottom tracks: same for all, $5.8\%\sigma$
- Moller resolution (invariant mass or total momentum)
 - Same for all: $2.2\%\sigma$

	N evts top	N evts bot	Res elastic peak top (σ)	Res elastic peak bot (σ)	N events Moller	Res Moller invariant mass (σ)
V 5.3	704836	1211814	5.5%	5.8%	6854	2.2%
V 5.7	703090	1214491	5.5%	5.8%	6680	2.2%
V 5.11	703462	1213208	5.5%	5.8%	6869	2.2%

- Do we have some references to compare? A set of standard cuts? A comparison with MC data?
- ... no easy way to choose the best detector (and this is almost likely a -fake- relative minimum)