#### 2016 Data Pass1 tests

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## **Calibration Files**

- Have selected calibration events from run 7796
  - FEE (Full Energy Electrons)
  - Møller Candidates
  - V0 Candidates
- Have skimmed off the events in evio format
- Run a test of what we currently imagine Pass1 will be over these events.

# Testing the software

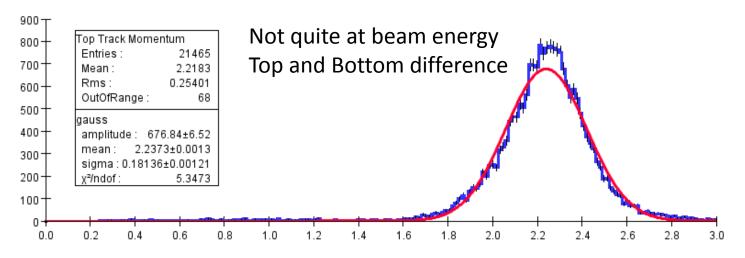
- Running from the master branch:
- > java
  - -cp hps-distribution-3.11-SNAPSHOT-bin.jar
  - org.hps.evio.EvioToLcio
  - -x /org/hps/steering/recon/PhysicsRun2016FullRecon.lcsim -r
  - -d HPS-PhysicsRun2016-v5-3-fieldmap\_globalAlign
  - -DdisableSvtAlignmentConstants=true
  - -DoutputFile=testPass1
  - /path/to/evioFile

# Analysis

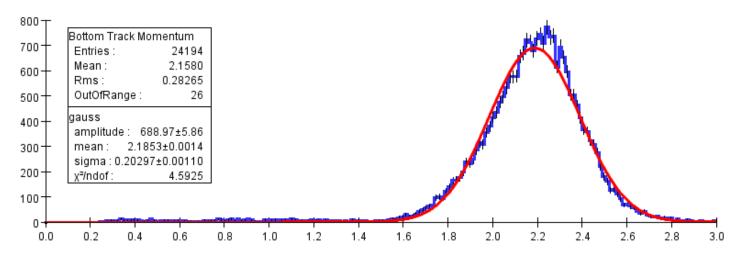
- Concentrating on target position determination
  - FEE: plot track y intercept vs z
    - y=0 gives z of target
    - Location where top and bottom agree
  - Møller:
    - plot unconstrained vertex z
      - Evidence for a bias in the vertex location since both tracks have same curvature (osculation problem)
    - Plot mass of target constrained vertex as function of z
      - Møller mass @2.3GeV = .04848 solve for z.
  - V0:
    - Plot unconstrained vertex z position

### FEE Track Momentum

2016 Run 7796 FEE Top Tracks

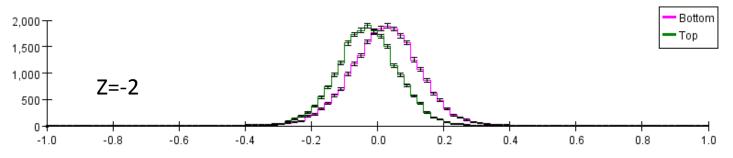


2016 Run 7796 FEE Bottom Tracks

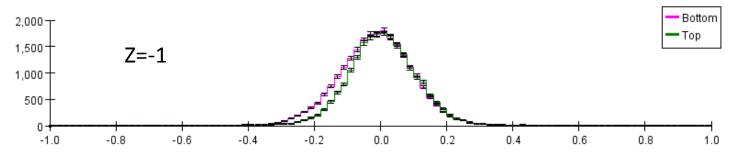


### FEE Y Intercept as function of Z

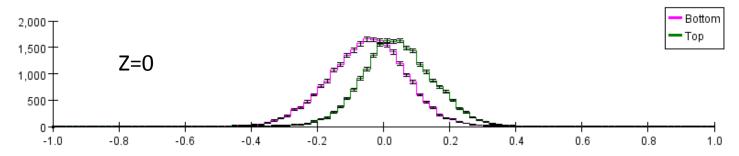
aida4553251623675168487.aida - -2.0 - Track extrap Y at -2.0



aida4553251623675168487.aida - -1.0 - Track extrap Y at -1.0

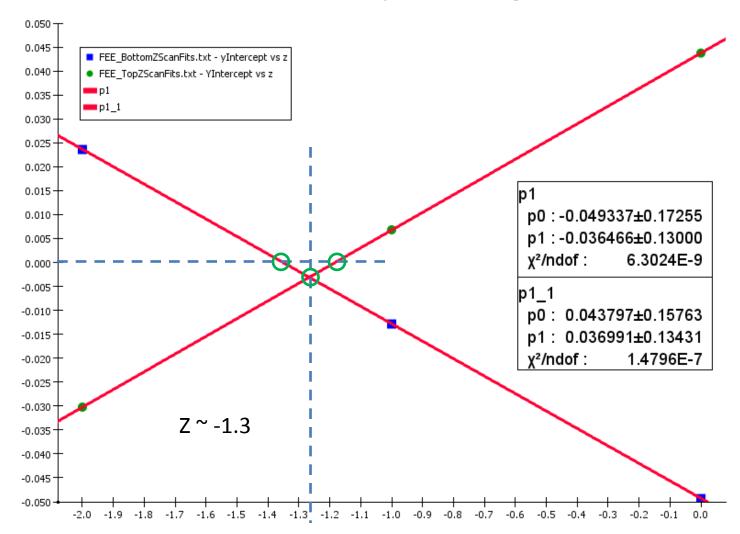


aida4553251623675168487.aida - 0.0 - Track extrap Y at 0.0



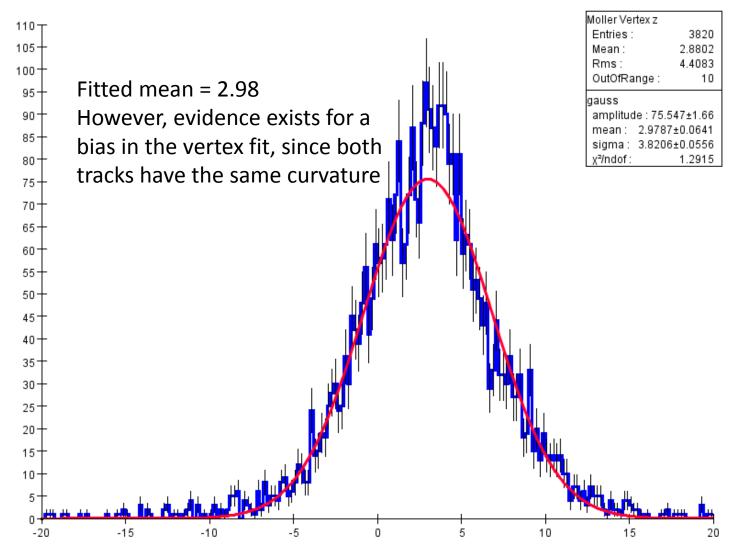
### FEE Y Intercept as function of Z Fits

2016 Run 7996 FEE Y Intercept as function of Target z

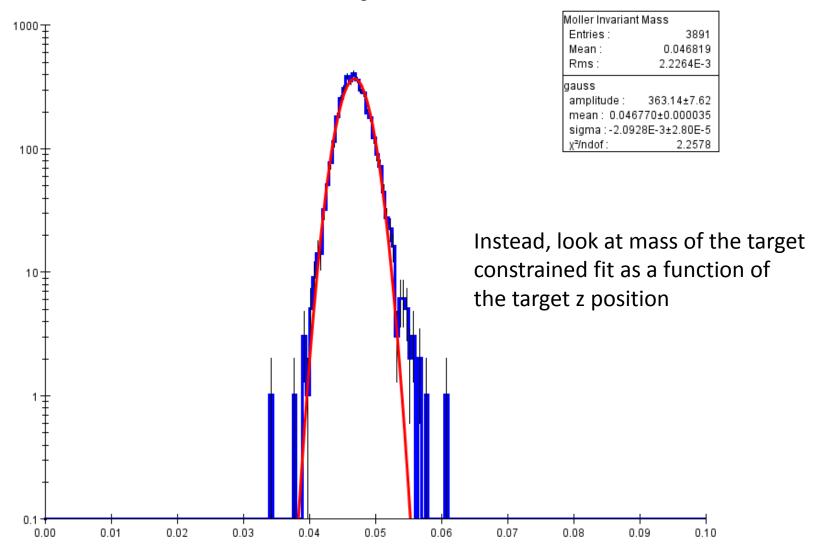


#### Target Unconstrained Møller Vertex z

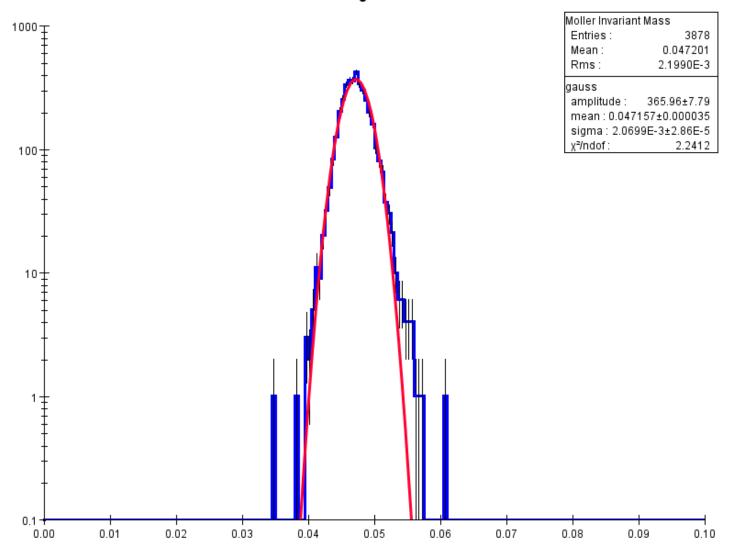
#### 2016 Run 7796 Møller Unconstrained Vertex Z



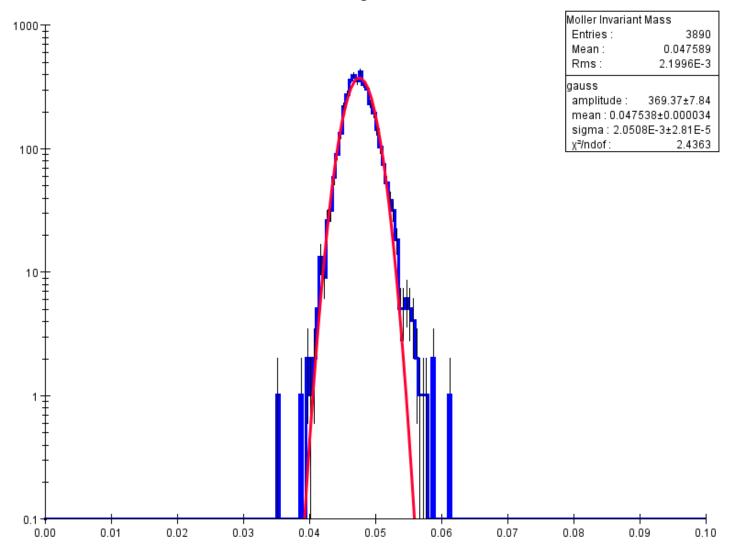
2016 Run 7796 Møller Target Constrained Mass z=-5



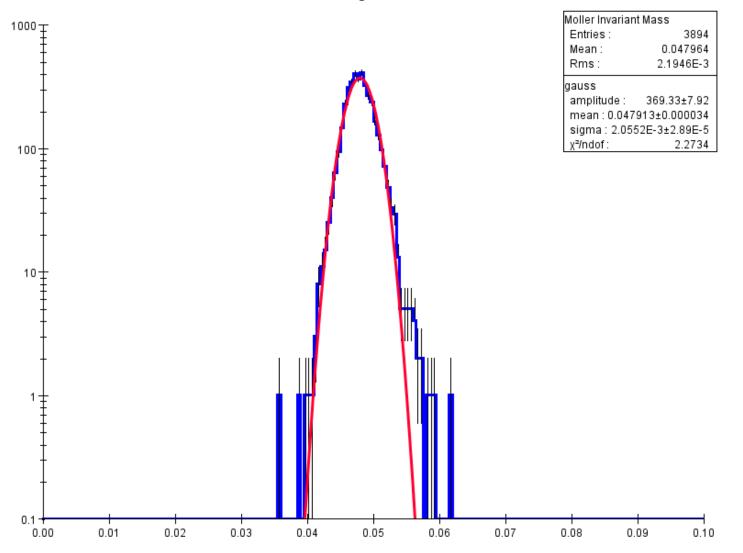
2016 Run 7796 Møller Target Constrained Mass z=-4



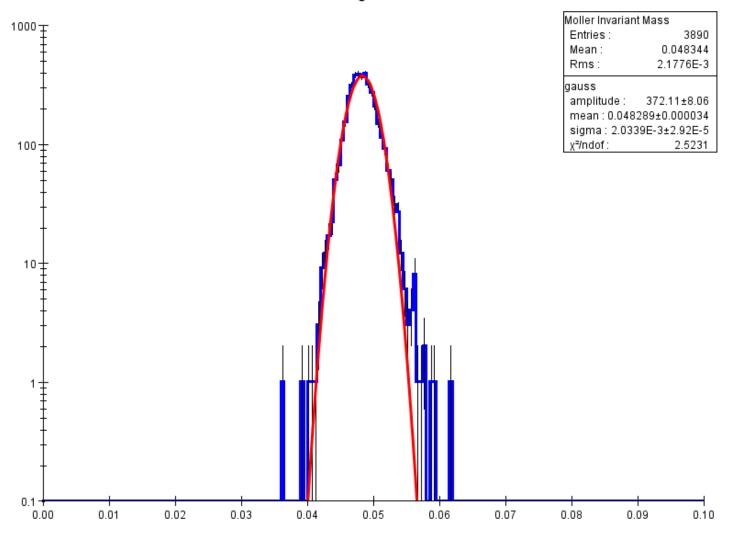
2016 Run 7796 Møller Target Constrained Mass z=-3



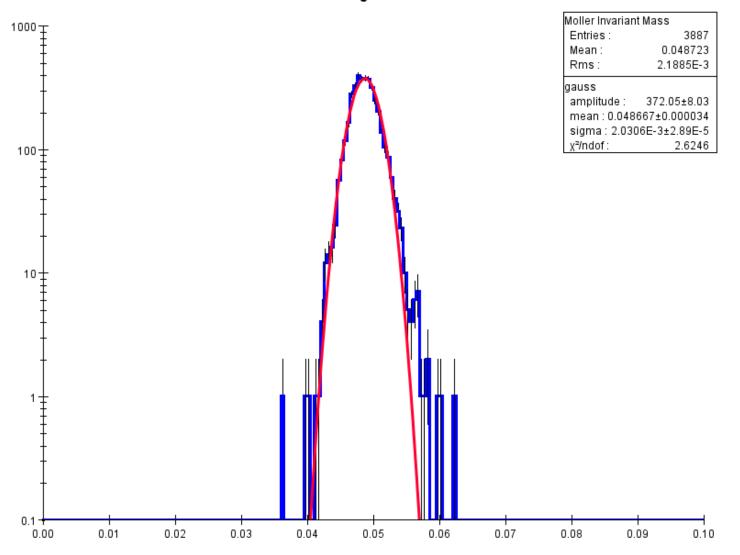
2016 Run 7796 Møller Target Constrained Mass z=-2



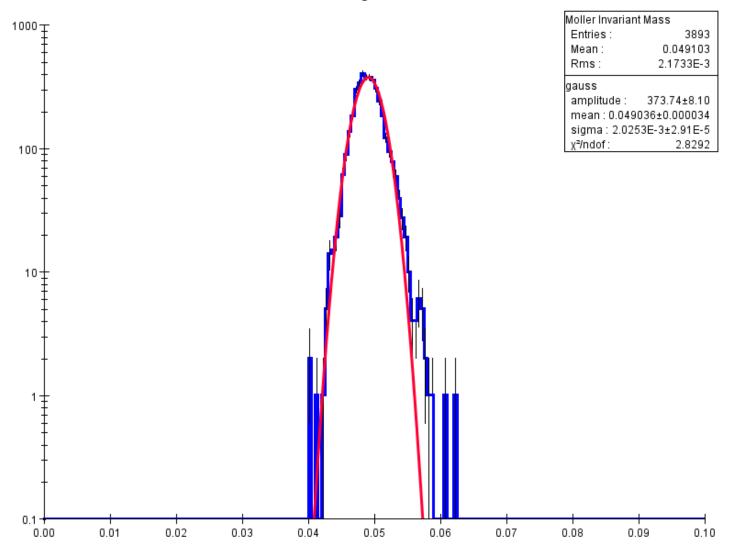
2016 Run 7796 Møller Target Constrained Mass z=-1



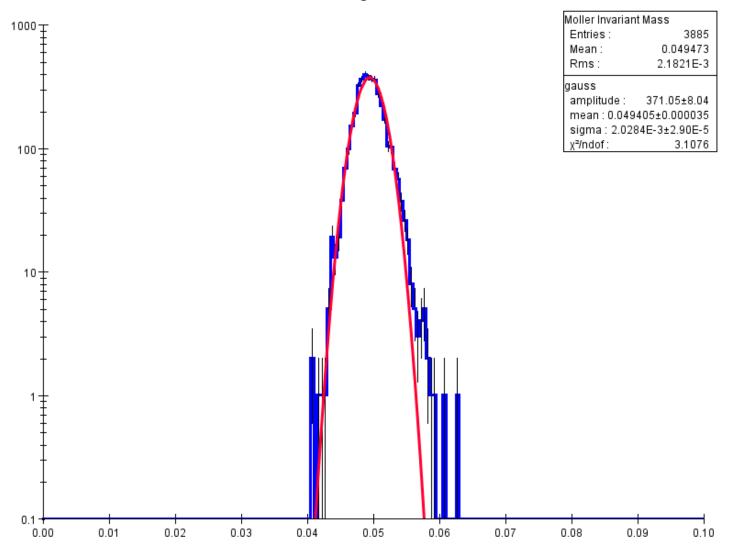
2016 Run 7796 Møller Target Constrained Mass z=0



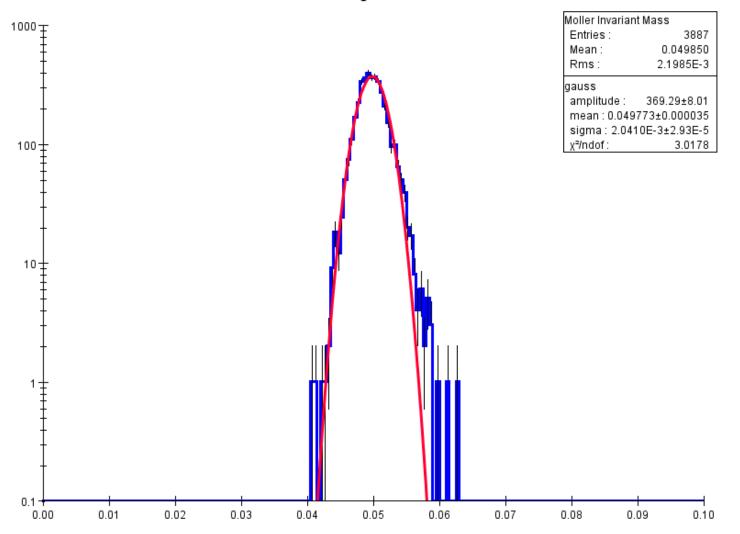
2016 Run 7796 Møller Target Constrained Mass z=1



2016 Run 7796 Møller Target Constrained Mass z=2

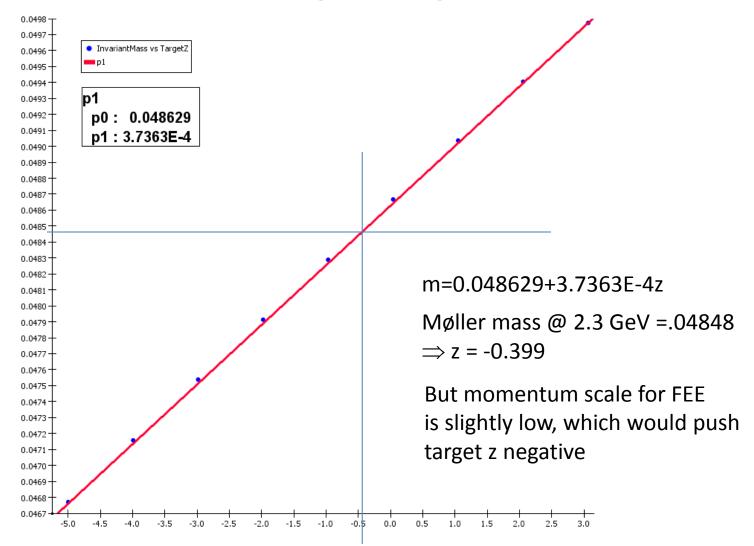


2016 Run 7796 Møller Target Constrained Mass z=3



### Target Constrained Møller Mass Fitted Mean vs z

2016 Run 7796 Møller Invariant Mass Target Constrained vs Target z Position

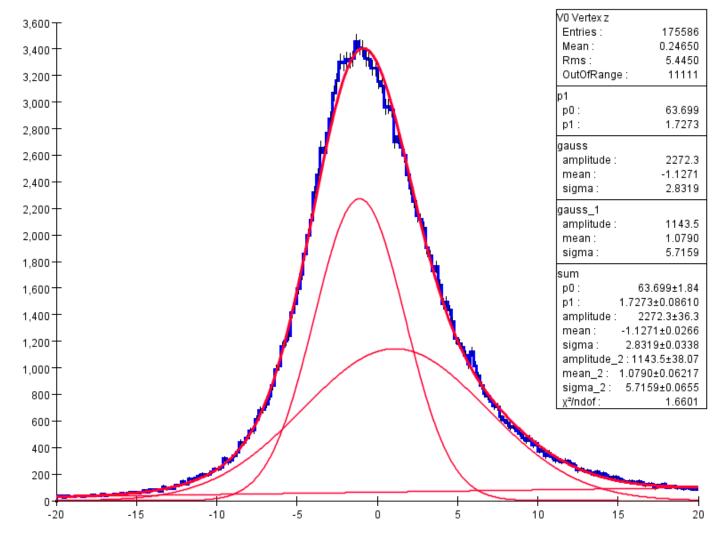


#### Unconstrained V0 vertex z

Hokey assemblage of functions

"Core" Gaussian mean= -1.13

2016 Run 7796 V0 Unconstrained Vertex Z



# Where's the target?

- I'd be happy with -1mm
- but could also leave it at 0 and correct later after we get more statistics and cleaner calibration samples.