# Field-Off Alignment

Norman Graf (SLAC)

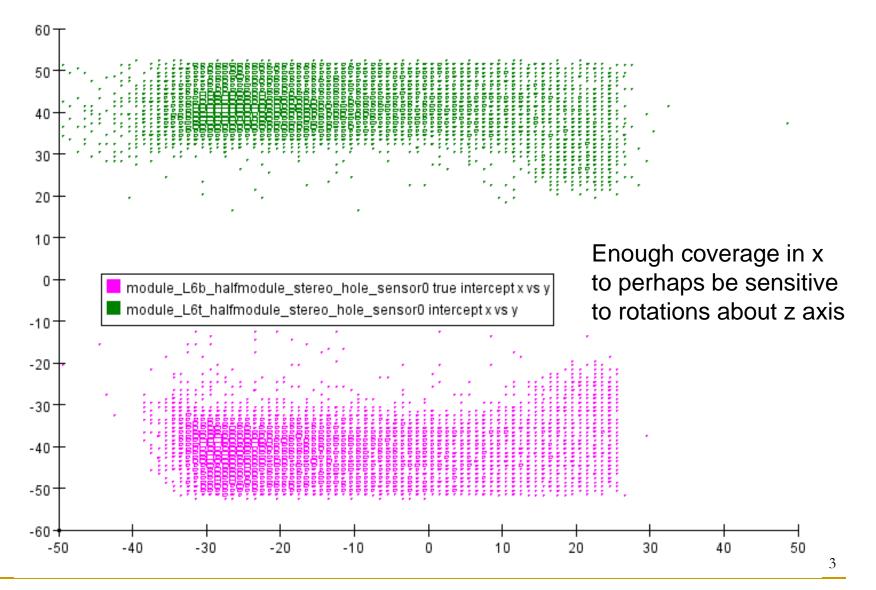
HPS SVT Meeting, 08/24/15

# Alignment Strategy

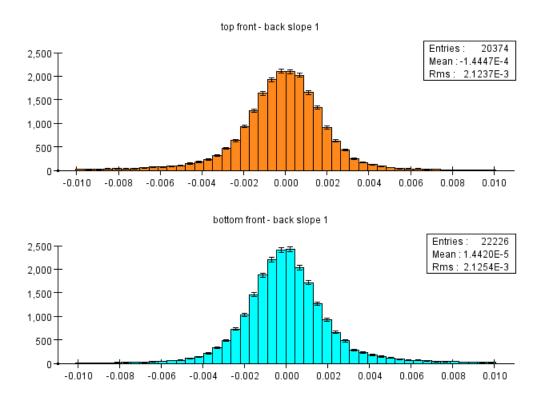
- Start simple
- Skim off clean FEE events
  - 6 hits on track
  - <20 strip clusters/event</p>
- Fix the "target" position at (-67.23, 0.0, -2337.1)
- Pick one other sensor to fix:
  - L4t\_hole\_sensor0
  - L4b\_hole\_sensor0
- Fit straight line to target position and L4 strip hits
- Derive "true" strip residuals for remaining sensors with respect to this line

### Track Coverage in Layer 6 Axial

module\_L6b\_halfmodule\_stereo\_hole\_sensor0 true intercept x vs y - module\_L6t\_halfmodule\_stereo\_hole\_sensor0 interc...



# Check for remaining opening angle Compare slope computed from layer 1,2,3 (front) to that computed from 4,5,6 (back)

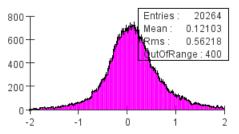


surprisingly good agreement

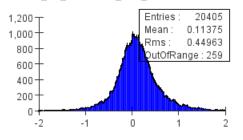
### Top "true" residuals (axial / stereo)

module L1t halfmodule axial sensor0 true resi ... Entries : 20019 600 0.11066 Mean: 500 0.63026 3ms : 400 tOfRange : 645 300 200 100 0 -0 -2 -1

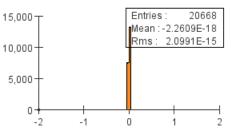
module\_L2t\_halfmodule\_axial\_sensor0 true resi..



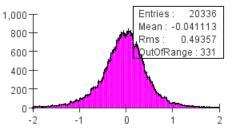
module\_L3t\_halfmodule\_axial\_sensor0 true resi...



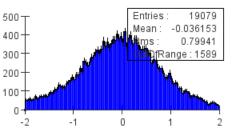
module\_L4t\_halfmodule\_axial\_hole\_sensor0 tru...



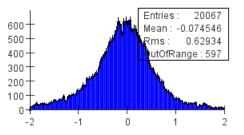
module\_L5t\_halfmodule\_axial\_hole\_sensor0 tru...



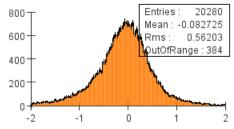
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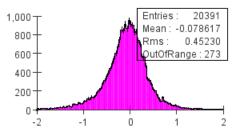
module\_L1t\_halfmodule\_stereo\_sensor0 true re...



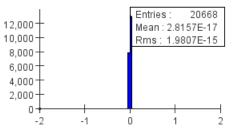
module\_L2t\_halfmodule\_stereo\_sensor0 true re...



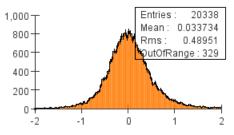
module\_L3t\_halfmodule\_stereo\_sensor0 true re...



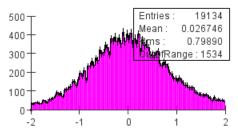
module L4t halfmodule stereo hole sensor0 tr...



module\_L5t\_halfmodule\_stereo\_hole\_sensor0 tr...



module\_L6t\_halfmodule\_stereo\_hole\_sensor0 tr...

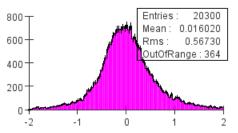


### Adjust sensors by residual offsets

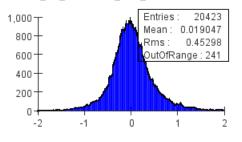
Entries : 20049 600 Mean: 0.015547 500 Rms: 0.63371 400 utOfRange : 615 300 200 100 0 -0 -2 2 -1

module\_L1t\_halfmodule\_axial\_sensor0 true resi..

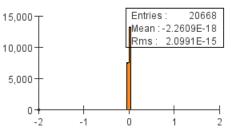
module\_L2t\_halfmodule\_axial\_sensor0 true resi..



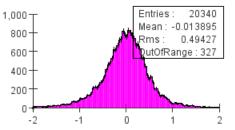
module\_L3t\_halfmodule\_axial\_sensor0 true resi...



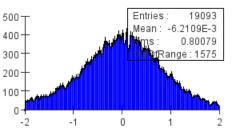
module\_L4t\_halfmodule\_axial\_hole\_sensor0 tru...



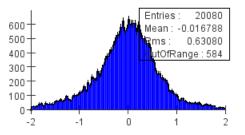
module\_L5t\_halfmodule\_axial\_hole\_sensor0 tru...



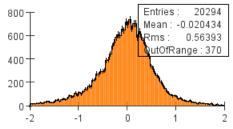
module\_L6t\_halfmodule\_axial\_hole\_sensor0 tru...



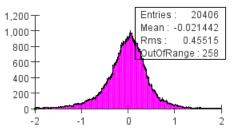
module\_L1t\_halfmodule\_stereo\_sensor0 true re...



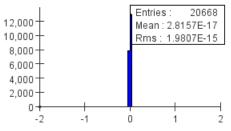
module\_L2t\_halfmodule\_stereo\_sensor0 true re...



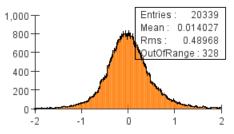
module\_L3t\_halfmodule\_stereo\_sensor0 true re...



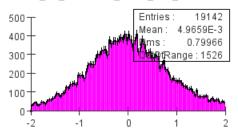
module L4t halfmodule stereo hole sensor0 tr...



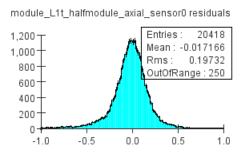
module\_L5t\_halfmodule\_stereo\_hole\_sensor0 tr...



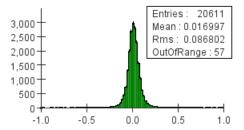
module\_L6t\_halfmodule\_stereo\_hole\_sensor0 tr...



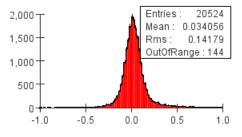
# Top Residuals axial /stereo (before)



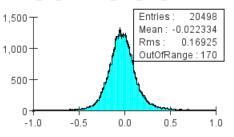
module\_L2t\_halfmodule\_axial\_sensor0 residuals



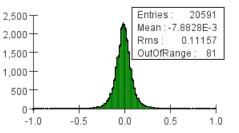
module\_L3t\_halfmodule\_axial\_sensor0 residuals



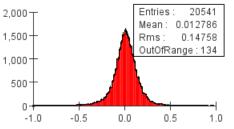
module\_L4t\_halfmodule\_axial\_hole\_sensor0 re...



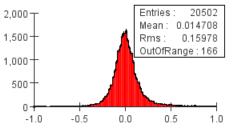
module\_L5t\_halfmodule\_axial\_hole\_sensor0 re...



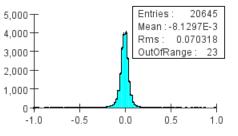
module\_L6t\_halfmodule\_axial\_hole\_sensor0 re...



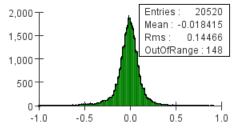
module\_L1t\_halfmodule\_stereo\_sensor0 residu..



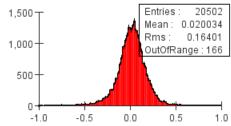
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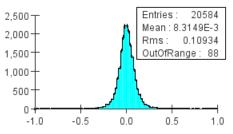
module\_L3t\_halfmodule\_stereo\_sensor0 residu...



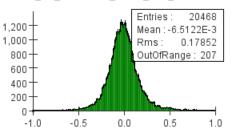
module L4t halfmodule stereo hole sensor0 r...



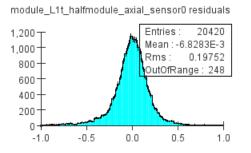
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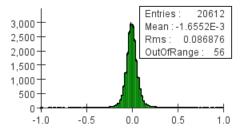
module\_L6t\_halfmodule\_stereo\_hole\_sensor0 r...



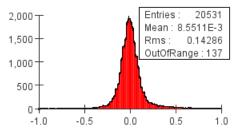
### Top Residuals axial stereo (after)



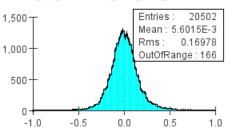
module\_L2t\_halfmodule\_axial\_sensor0 residuals



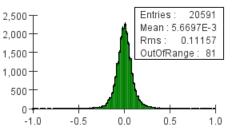




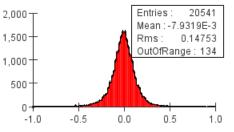
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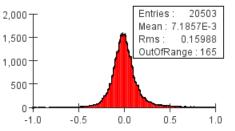
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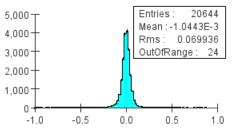
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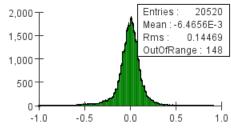
module\_L1t\_halfmodule\_stereo\_sensor0 residu...



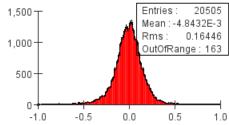
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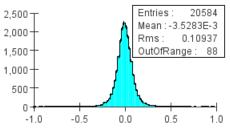
module\_L3t\_halfmodule\_stereo\_sensor0 residu...



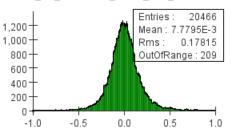
module\_L4t\_halfmodule\_stereo\_hole\_sensor0 r...



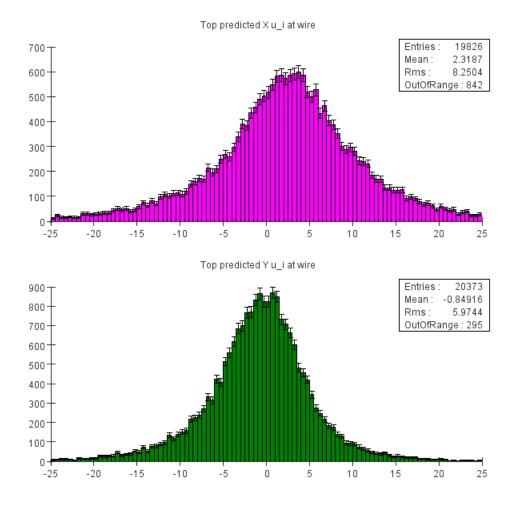
module\_L5t\_halfmodule\_stereo\_hole\_sensor0 r...



module\_L6t\_halfmodule\_stereo\_hole\_sensor0 r...

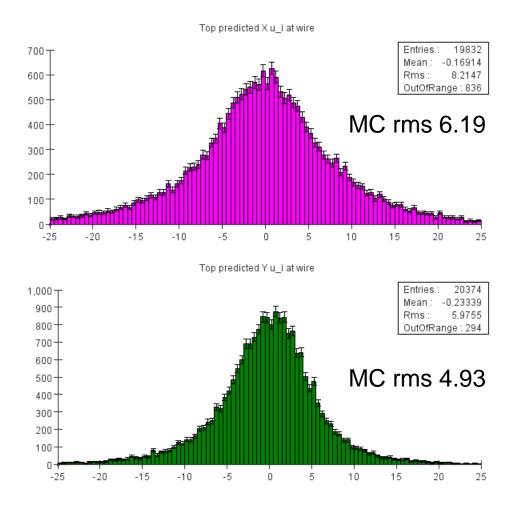


# Fit tracks and predict target position



Before

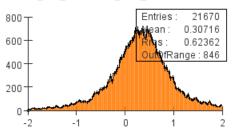
# Fit tracks and predict target position



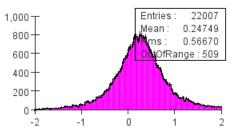
After

### Bottom "true" residuals (axial/stereo)

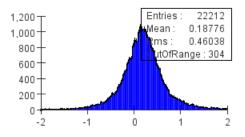
module\_L1b\_halfmodule\_axial\_sensor0 true res...



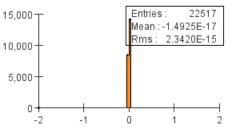
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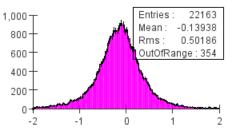
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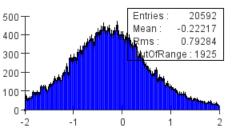
module\_L4b\_halfmodule\_axial\_hole\_sensor0 tr...



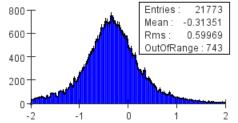
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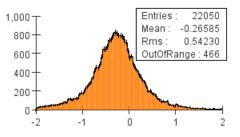
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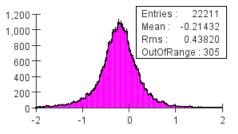
module\_L1b\_halfmodule\_stereo\_sensor0 true r...



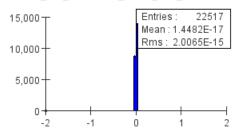
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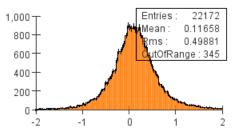
module\_L3b\_halfmodule\_stereo\_sensor0 true r...



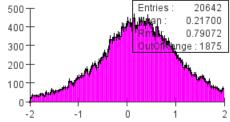
module L4b halfmodule stereo hole sensor0 t ...



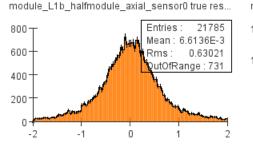
module\_L5b\_halfmodule\_stereo\_hole\_sensor0 t...



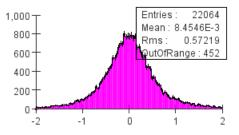
module\_L6b\_halfmodule\_stereo\_hole\_sensor0 t...



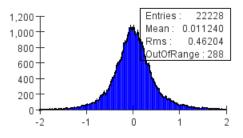
### Adjust sensors by residual offsets



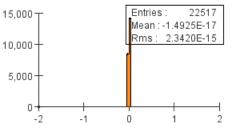
module\_L2b\_halfmodule\_axial\_sensor0 true res...



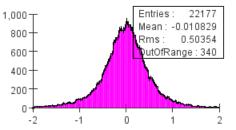
module\_L3b\_halfmodule\_axial\_sensor0 true res...



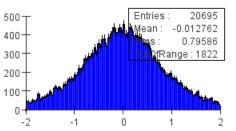
module\_L4b\_halfmodule\_axial\_hole\_sensor0 tr...



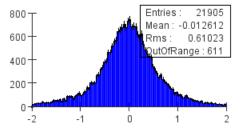
module\_L5b\_halfmodule\_axial\_hole\_sensor0 tr...



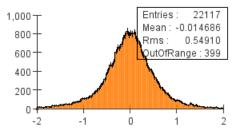
module\_L6b\_halfmodule\_axial\_hole\_sensor0 tr...



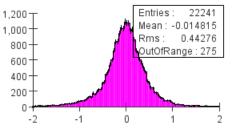
module\_L1b\_halfmodule\_stereo\_sensor0 true r...



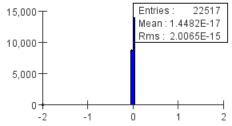
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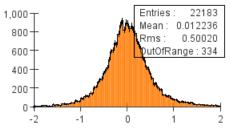
module\_L3b\_halfmodule\_stereo\_sensor0 true r...



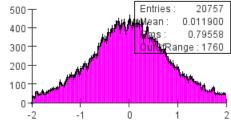
module L4b halfmodule stereo hole sensor0 t ...



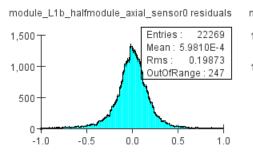
module\_L5b\_halfmodule\_stereo\_hole\_sensor0 t...



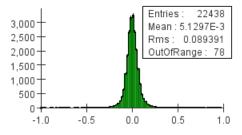
module\_L6b\_halfmodule\_stereo\_hole\_sensor0 t...



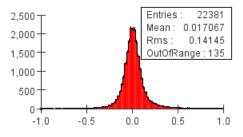
### Bottom Residuals axial/stereo (before)



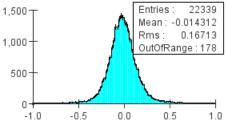
module\_L2b\_halfmodule\_axial\_sensor0 residuals



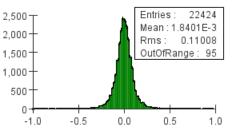
module\_L3b\_halfmodule\_axial\_sensor0 residuals



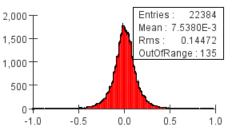
module\_L4b\_halfmodule\_axial\_hole\_sensor0 re...



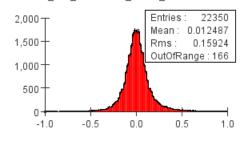
module\_L5b\_halfmodule\_axial\_hole\_sensor0 re...



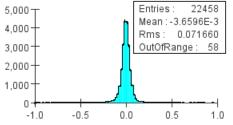
module\_L6b\_halfmodule\_axial\_hole\_sensor0 re...



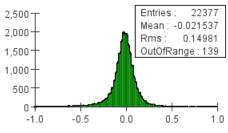
module L1b halfmodule stereo sensor0 resid...



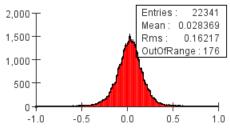
### module\_L2b\_halfmodule\_stereo\_sensor0 resid...



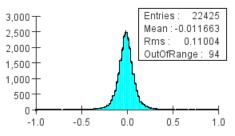
module\_L3b\_halfmodule\_stereo\_sensor0 resid...



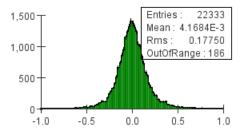
module\_L4b\_halfmodule\_stereo\_hole\_sensor0 ...



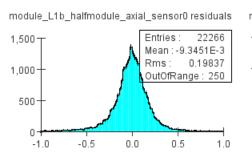
module\_L5b\_halfmodule\_stereo\_hole\_sensor0 ...



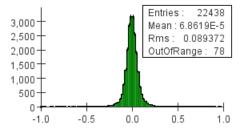
module\_L6b\_halfmodule\_stereo\_hole\_sensor0 ...



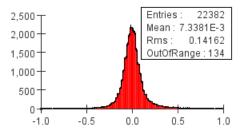
### Bottom Residuals axial/stereo (after)



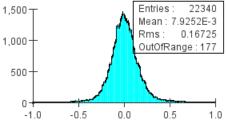
module\_L2b\_halfmodule\_axial\_sensor0 residuals



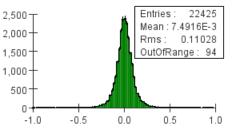
module\_L3b\_halfmodule\_axial\_sensor0 residuals



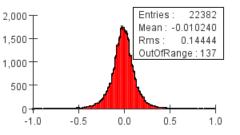
module\_L4b\_halfmodule\_axial\_hole\_sensor0 re...



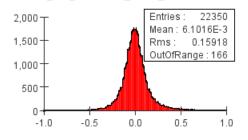
module\_L5b\_halfmodule\_axial\_hole\_sensor0 re...



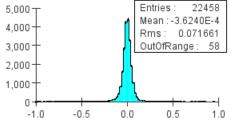
module\_L6b\_halfmodule\_axial\_hole\_sensor0 re...



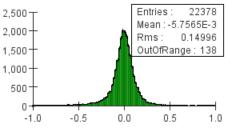
module\_L1b\_halfmodule\_stereo\_sensor0 resid...



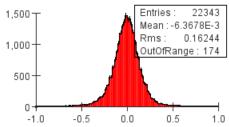
### module\_L2b\_halfmodule\_stereo\_sensor0 resid...



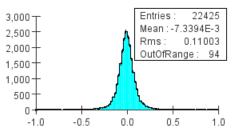
module\_L3b\_halfmodule\_stereo\_sensor0 resid...



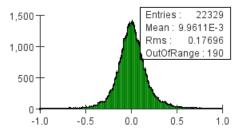
module\_L4b\_halfmodule\_stereo\_hole\_sensor0 ...



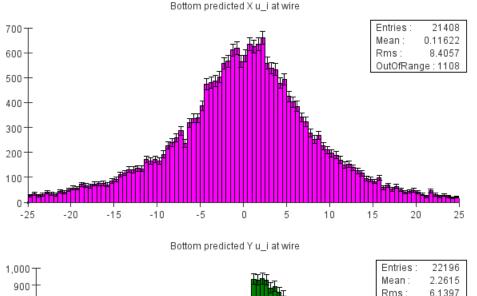
module\_L5b\_halfmodule\_stereo\_hole\_sensor0 ...



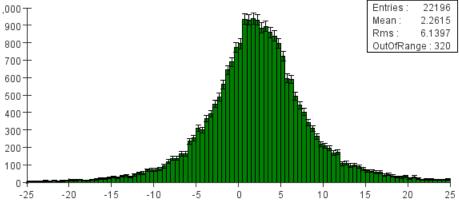
module\_L6b\_halfmodule\_stereo\_hole\_sensor0 ...



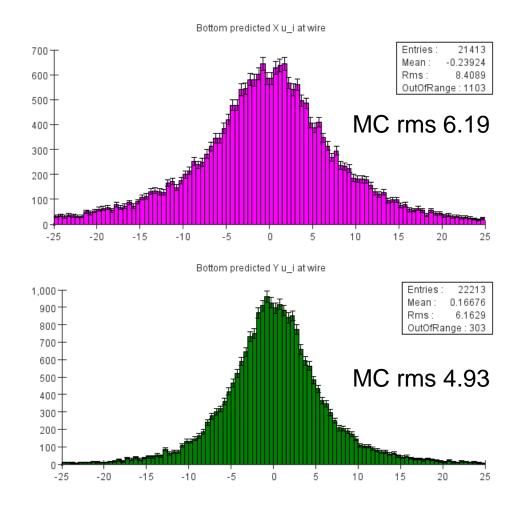
# Fit tracks and predict target position



Before



# Fit tracks and predict target position



After

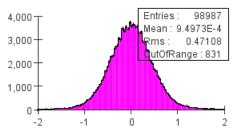
## MC comparisons

- Turn off field in detector HPS-EngRun2015-Nominal-v2\_fieldOff.lcdd
- Generate single electron events: /generator/select gps /gps/particle e-/gps/position -67.23 0.0 -2337.1 mm /gps/energy 1.056 GeV /gps/direction 0.02 0.008 1 /random/setSavingFlag true /lcio/fileExists delete /lcio/PDGFlag

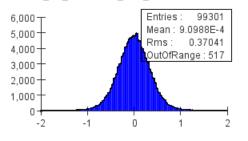
### MC "true" residuals (axial / stereo)

module L1t halfmodule axial sensor0 true resi.. Entries 98806 5.000 -Mean: 3.1002E-3 4.000-0.51480 Rms tOfRange : 1012 3.000 2.000-1.000-0 -0 -2 -1 2

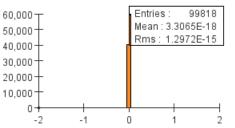
module\_L2t\_halfmodule\_axial\_sensor0 true resi...



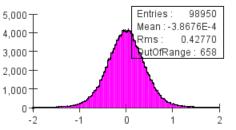
module\_L3t\_halfmodule\_axial\_sensor0 true resi...



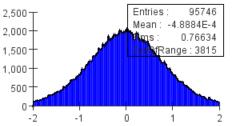
module\_L4t\_halfmodule\_axial\_hole\_sensor0 tru...



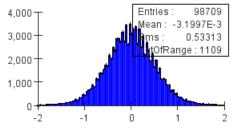
module\_L5t\_halfmodule\_axial\_hole\_sensor0 tru...



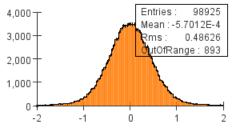
module\_L6t\_halfmodule\_axial\_hole\_sensor0 tru...



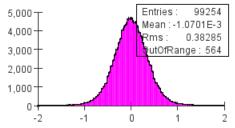
module\_L1t\_halfmodule\_stereo\_sensor0 true re...



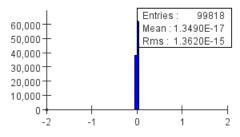
module\_L2t\_halfmodule\_stereo\_sensor0 true re...



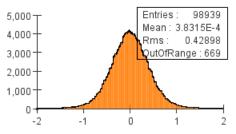
module\_L3t\_halfmodule\_stereo\_sensor0 true re...



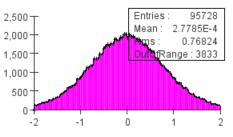
module L4t halfmodule stereo hole sensor0 tr...



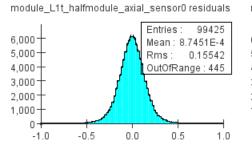
module\_L5t\_halfmodule\_stereo\_hole\_sensor0 tr...



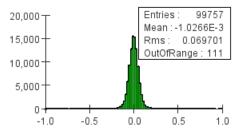
module\_L6t\_halfmodule\_stereo\_hole\_sensor0 tr...

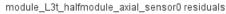


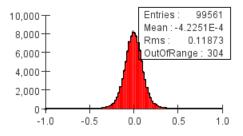
### MC Residuals axial/stereo



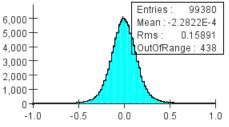
module\_L2t\_halfmodule\_axial\_sensor0 residuals



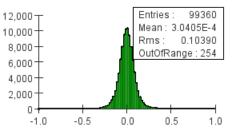




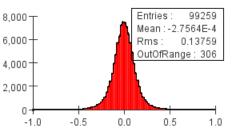
module\_L4t\_halfmodule\_axial\_hole\_sensor0 re...



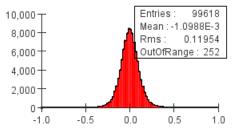
module\_L5t\_halfmodule\_axial\_hole\_sensor0 re...



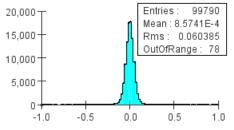
module\_L6t\_halfmodule\_axial\_hole\_sensor0 re...



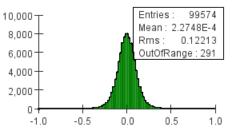
module\_L1t\_halfmodule\_stereo\_sensor0 residu...



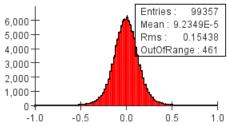
### module\_L2t\_halfmodule\_stereo\_sensor0 residu...



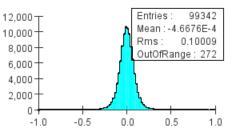
module\_L3t\_halfmodule\_stereo\_sensor0 residu...



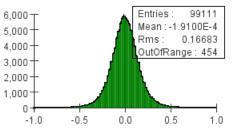
module\_L4t\_halfmodule\_stereo\_hole\_sensor0 r...



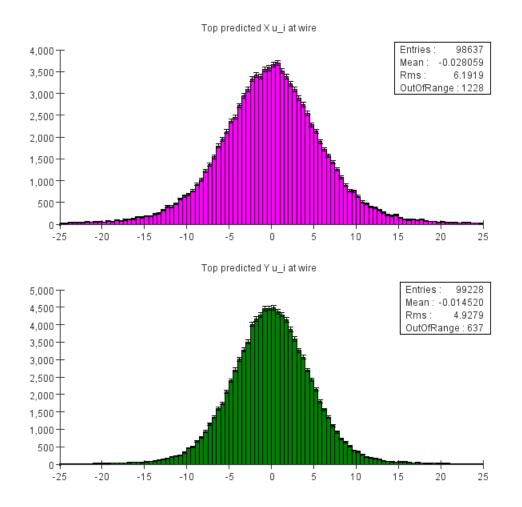
module\_L5t\_halfmodule\_stereo\_hole\_sensor0 r...



module\_L6t\_halfmodule\_stereo\_hole\_sensor0 r...



# MC predict target position



Current Corrections axial stereo				
L1t	0.103	-0.063	consistent with	
L2t	0.111	-0.066	translation of all three layers ?	
L3t	0.097	-0.059		
L4t_hole	0.	0.		
L4t_slot	0.	0.		
L5t_hole	-0.028	0.020		
L5t_slot	0.	0.		
L6t_hole	-0.036	0.027		
L6t_slot	0.	0.		

### Current Corrections axial stereo

- L1b
- L2b
- L3b
- L4b\_hole
- L4b\_slot
- L5b\_hole
- L5b\_slot
- L6b\_hole
- L6b\_slot

0.332	-0.327
0.252	-0.264
0.182	-0.204
0.	0.
0.	0.
-0.133	0.108
0.	0.
-0.259	0.254
0.	0.

consistent with rotation of all three layers ?

# Next Steps

- Keep it simple
- Chew on the results so far to understand geometry shifts
  - Quantify MC/Data comparisons
- Repeat analyses fixing other stations
- Try to understand axial/stereo shifts by constraining stations, not individual sensors
- Implement least-squares fitting for
  - translation  $\perp$  to strip direction
  - rotation about z axis (γ)
  - Keep it simple (don't reinvent millepede)
- Put some of the shifts into detector description
  - Run some field-on Fee events
    - check momentum and χ<sup>2</sup>
  - Run some field-on Møller events
    - check vertex position and mass
  - Finish by Friday (?)