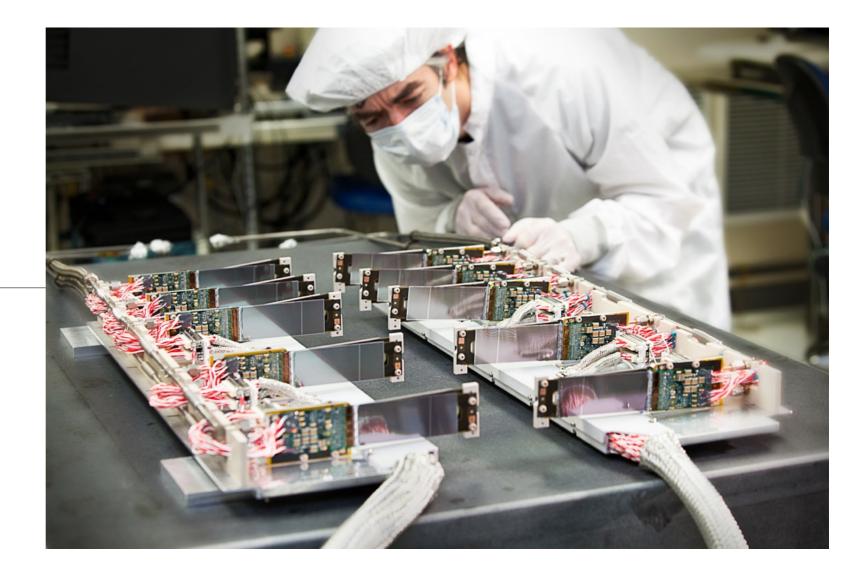
# The HPS SVT

### Tim Nelson - SLAC

### HPS DOE Review July 11, 2013



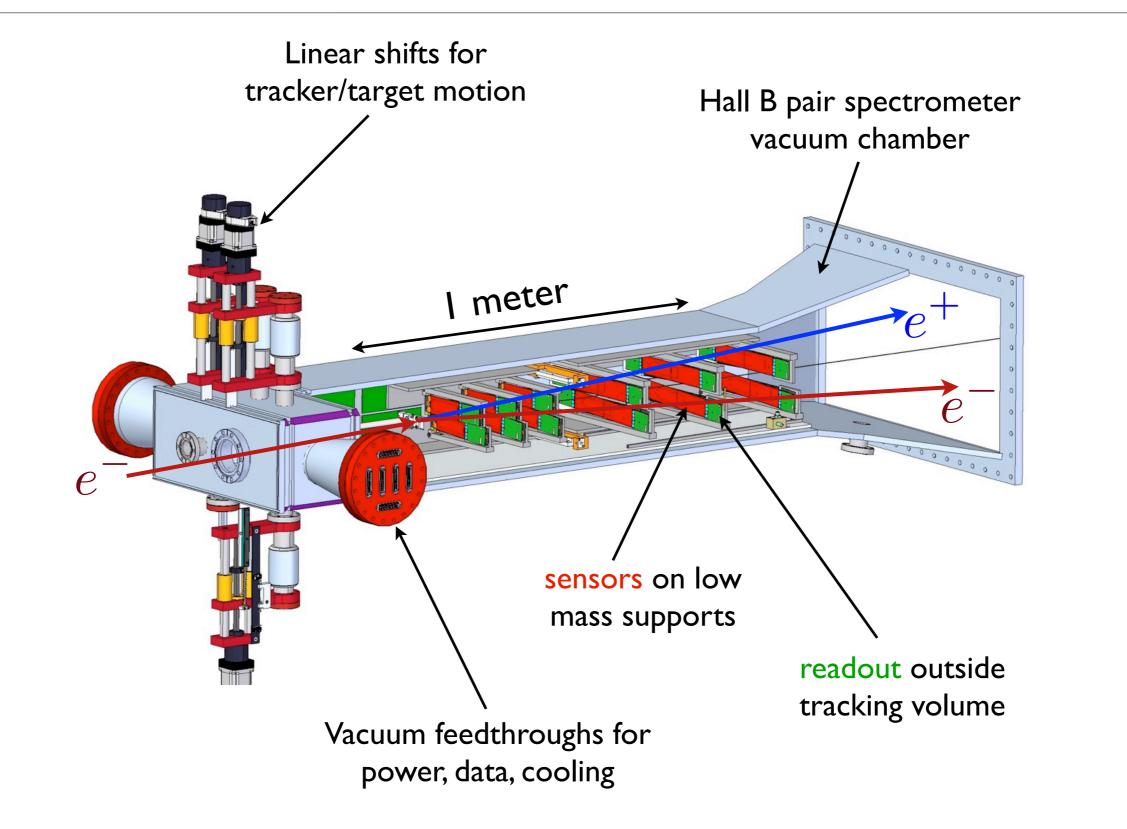
## Outline

- Overview of SVT and requirements
- Key components
- •Where we've been: HPS Test SVT
- •Where we're going: HPS SVT
- How we'll get there.

## The HPS SVT...

- provides estimates of trajectories of low-momentum charged particles
  - Momentum at production vertex candidate A' mass
  - Vertex position candidate A' lifetime
- minimizes multiple scattering effects that dominate uncertainties in these estimates
  - Material is the primary enemy
  - Requirements for single-hit and alignment precision are modest
- optimizes acceptance by instrumenting as close to scattered primary beam as possible
  - Operation in vacuum
  - Radiation tolerance
  - Fast trigger and DAQ
  - Excellent hit timing

## SVT Overview



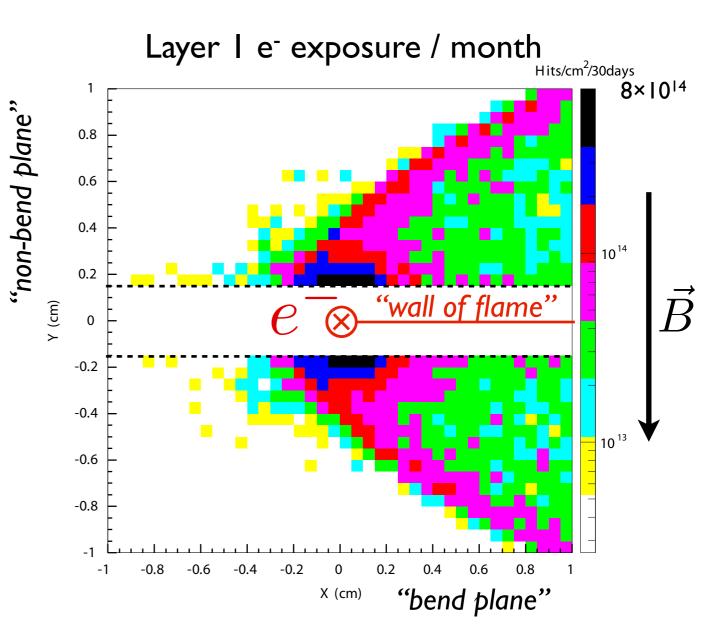
## **Optimizing Acceptance**

High-mass is simple in principle: build it as big as you can afford!

Low-mass is harder: requires acceptance very close to beam

At 15 mrad, 10 cm from target (L1):

- Active detector ~1.5 mm from beam
- Peak occupancy ~4 MHz/mm<sup>2</sup>
- Fluence  $4.8 \times 10^{15} e^{-} \cong 1.6 \times 10^{14}$  neq. in 6 months of running



## Sensor Selection

### Also need...

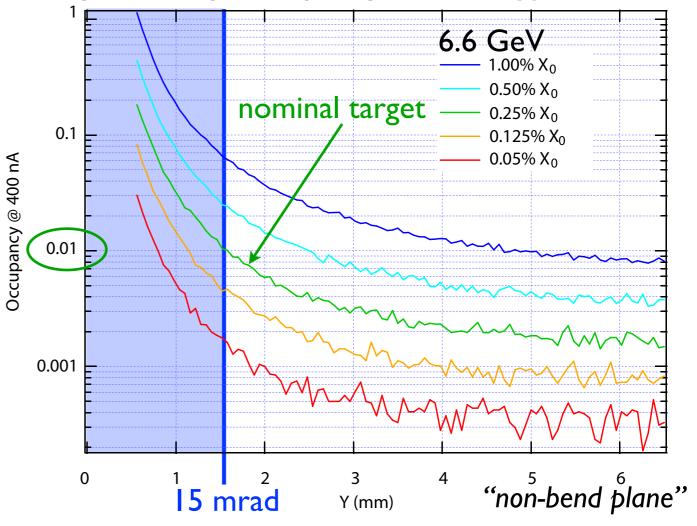
- <  $1\% X_0$  per layer
- ≤ 50 µm single-hit resolution
   in both measurement coordinates
- < \$1M for a complete system, soon!

#### MAPS?

Hybrid pixels?

Strip sensors (edges  $500 \ \mu m$  from beam!)

#### Layer I strip occupancy / 8 ns trigger window

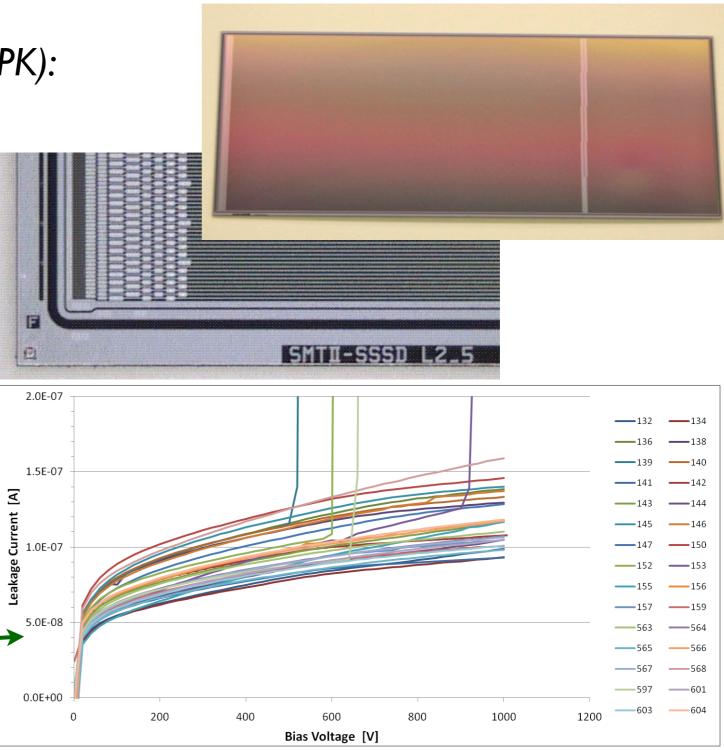


## Silicon Microstrip Sensors

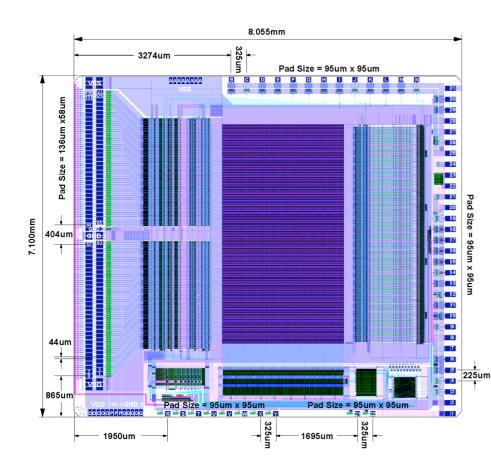
### Production Tevatron RunIIb sensors (HPK):

- Fine readout granularity
- most capable of 1000V bias: fully depleted for 6 month run.
- Available in sufficient quantities
- Cheapest technology (contribution from FNAL)

Technology	<100>, p+ in n, AC-coupled
Active Area (L×W)	98.33 mm × 38.34mm
Readout (Sense) Pitch	60μm (30μm)
Breakdown Voltage	>350V
Interstrip Capacitance	<1.2 pF/cm
Defective Channels	<0.1%



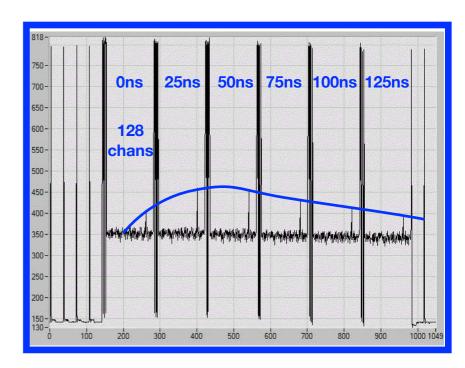
## Front-end Electronics: APV25

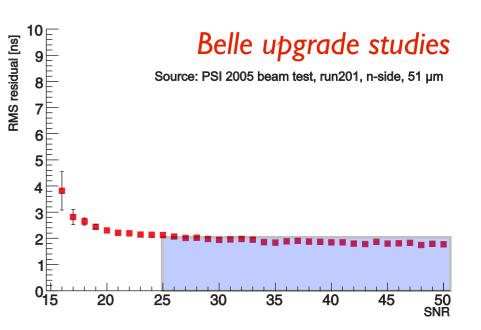


# Readout Channels	128
Input Pitch	44 μm
Shaping Time	50ns nom. (35ns min.)
Noise Performance	270+36×C(pF) e <sup>-</sup> ENC
Power Consumption	345 mW

### Developed for CMS

- available (28 CHF/ea.)
- radiation tolerant
- fast front end
   (35 ns shaping time)
- low noise (S/N > 25)
- "multi-peak" readout
  ~2 ns t<sub>0</sub> resolution!





## **Optimizing Detector Layout**

Using SLIC/Icsim framework for simulation and reconstruction of both MC and data

- Detailed model of detector response for MC
  - Silicon charge deposition/collection
  - Time response and multi-peak readout of APV25 front end
  - Time-sequenced overlay of backgrounds
- Same hit and track reconstruction tools for both MC and data
  - Amplitude, time reconstruction, and clustering of hits
  - Track finding and fitting
  - Can produce MC using constants established with data

This high level of detail is critical for establishing vertex reach (10-7 prompt rejection!)

# Initially Proposed Layout

A no-compromises approach with best possible mass and vertexing resolution over large acceptance

- 106 sensors & hybrids
- 530 APV25 chips
- 67840 channels

A relatively large and expensive detector.

Requires large magnet, vacuum chamber and ECal also.

How do we prove this works?

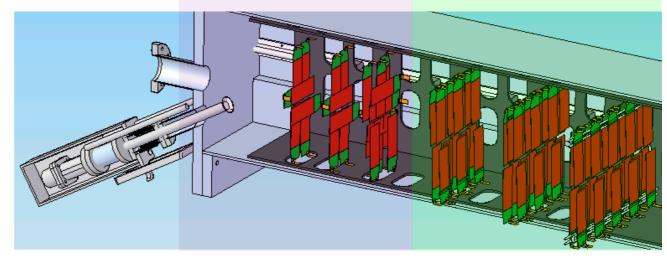
	Layer I	Layer 2	Layer 3	Layer 4	Layer 5	Layer 6
z position, from target (cm)	10	20	30	50	70	90
Stereo Angle	90 deg.	90 deg.	90 deg.	50 mrad	50 mrad	50 mrad
Bend Plane Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6
Stereo Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 120	≈ 120	≈ 120
# Bend Plane Sensors	4	4	6	10	14	18
# Stereo Sensors	2	2	4	10	14	18
Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	±13.5
Power Consumption (W)	10.5	10.5	17.5	35	49	63

Vertexing

Pattern Recognition

Мо

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m

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## HPS Test SVT

#### Proposed 3/11, Installed 4/12

- Develop technical solutions
- Prove operational principles
- Capable of A' physics

Linear shifts for – tracker/target motio

 $e^{-}$ 

		1	1		[ [		
stalled 4/12		Layer I	Layer 2	Layer 3	Layer 4	Layer 5	
	z position, from target (cm)	10	20	30	50	70	
al solutions	Stereo Angle (mrad)	100	100	100	50	50	
	Bend Plane Resolution (µm)	≈ 60	≈ 60	≈ 60	≈ 120	≈ 120	
al principles	Non-Bend Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	
hysics	# Bend Plane Sensors	2	2	2	2	2	
hysics	# Stereo Sensors	2	2	2	2	2	
	Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	
	Power Consumption (W)	7	7	7	7	7	
tion I I I I I I I I I I I I I I I I I I I	kirescanner target Definition	M	o r	n e	Pattern Re n t	ecognition u m Geographical Geographical Geographical Hinge "C" sup	ed port 11

## Test SVT Modules

### Half Module

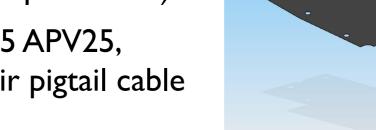
- 0.17 mm thick CF frame (FE grounded, HV passivated)
- FR4 hybrid with 5 APV25, short twisted-pair pigtail cable
- single sensor

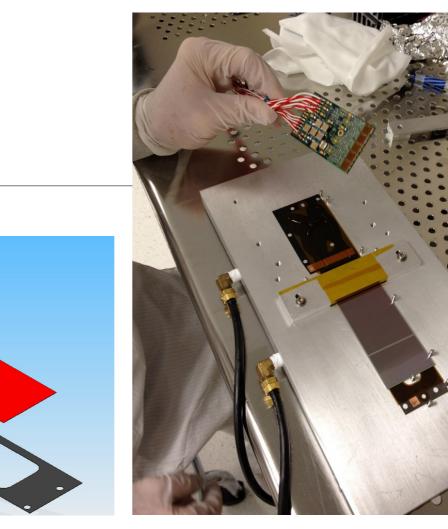
### Full module -

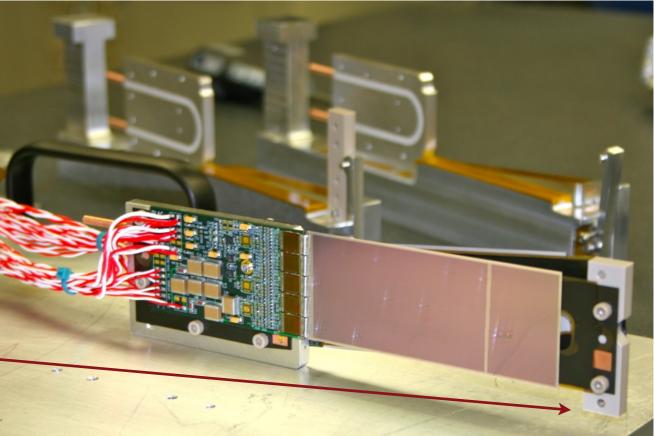
- Two half-modules back-to-back on Al cooling block w/ Cu tubes
- glue-less assembly with PEEK spacer block and hardware

### $0.7\% X_0$ average per layer

Limits flatness/stability of Si -





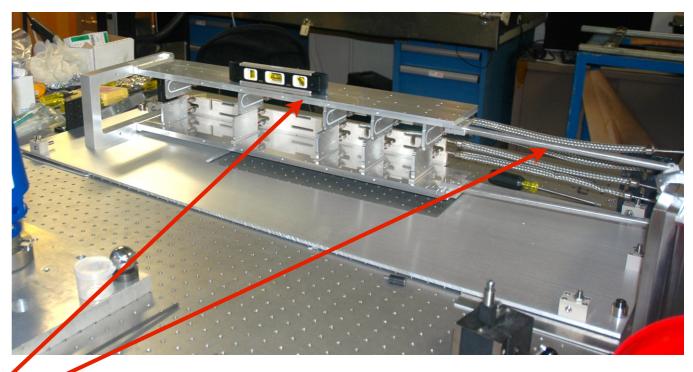


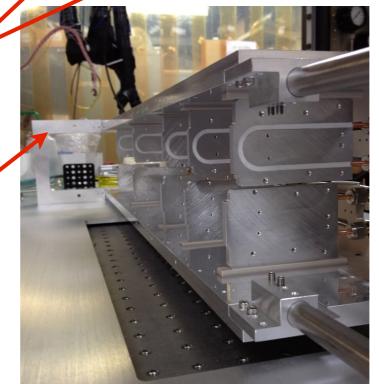
## Test SVT Mechanics

Cooling blocks mount on Al support plates with hinged "C-support" and motion lever

- Provide solid mounting for modules, routing for services, and simple motion for tracker
- PEEK pedestals create 15 mr dead zone, provide some thermal isolation
- Support plates + motion levers ~1.5 m long: sag dominates x-y imprecision (300 μm)
- Load on C-support introduces small roll in top plate.

Works, but can be improved upon

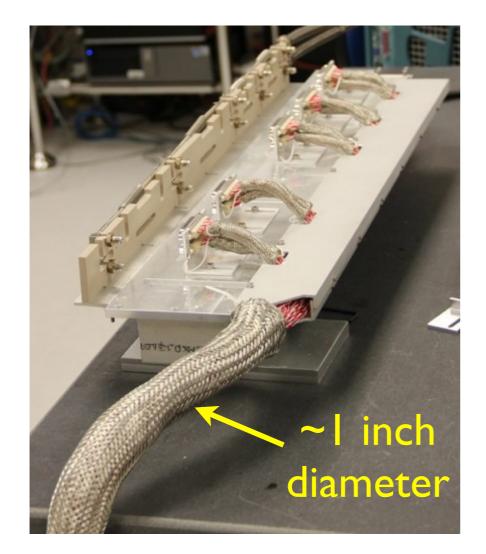


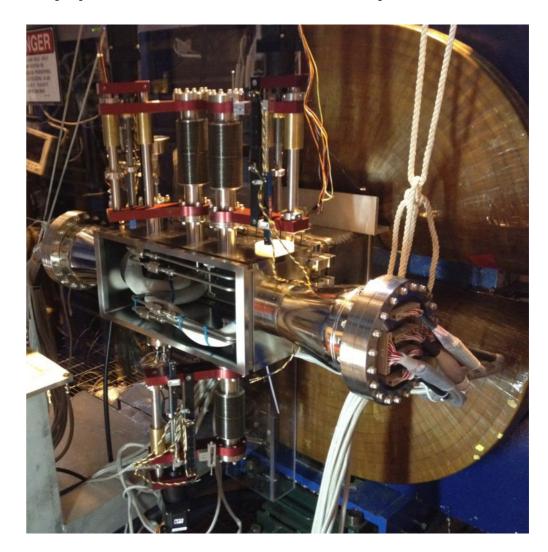




## Test SVT Services

- Borrowed CDF SVXII power supplies (very crufty) and JLab chiller (limited to  $> 0^{\circ}$ C)
- Intricate welded cooling manifolds with 2 compression fittings/module
- 600 wires into vacuum chamber for power and data (3600 total pairs of connector contacts): recovered three sensors with internal connectivity problems after assembly/installation at JLab



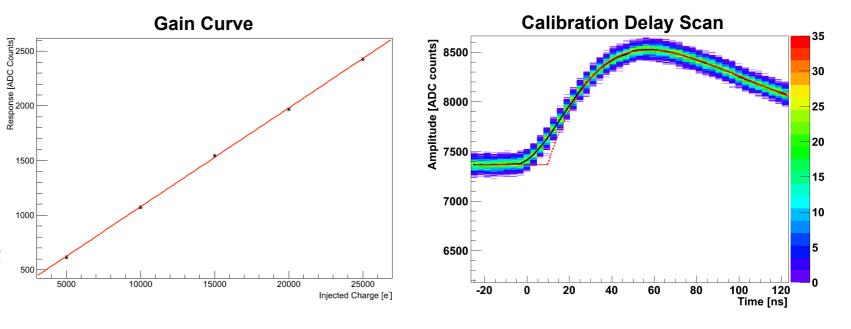


We got away with this, but it doesn't scale well to a larger detector.

# Test SVT Assembly, Commissioning, Operation

#### At SLAC:

- Began with 165 APV25 (enough for 33 hybrids)
- 29/30 hybrids passed QA
- 28/29 half-modules passed QA
- Good noise, linearity, uniformity
- Assembly precision at cooling block: x-y ~10  $\mu$ m, z ~ 25  $\mu$ m
- Flatness (z) along sensor  $\sim 200 \ \mu m$



#### At JLab:

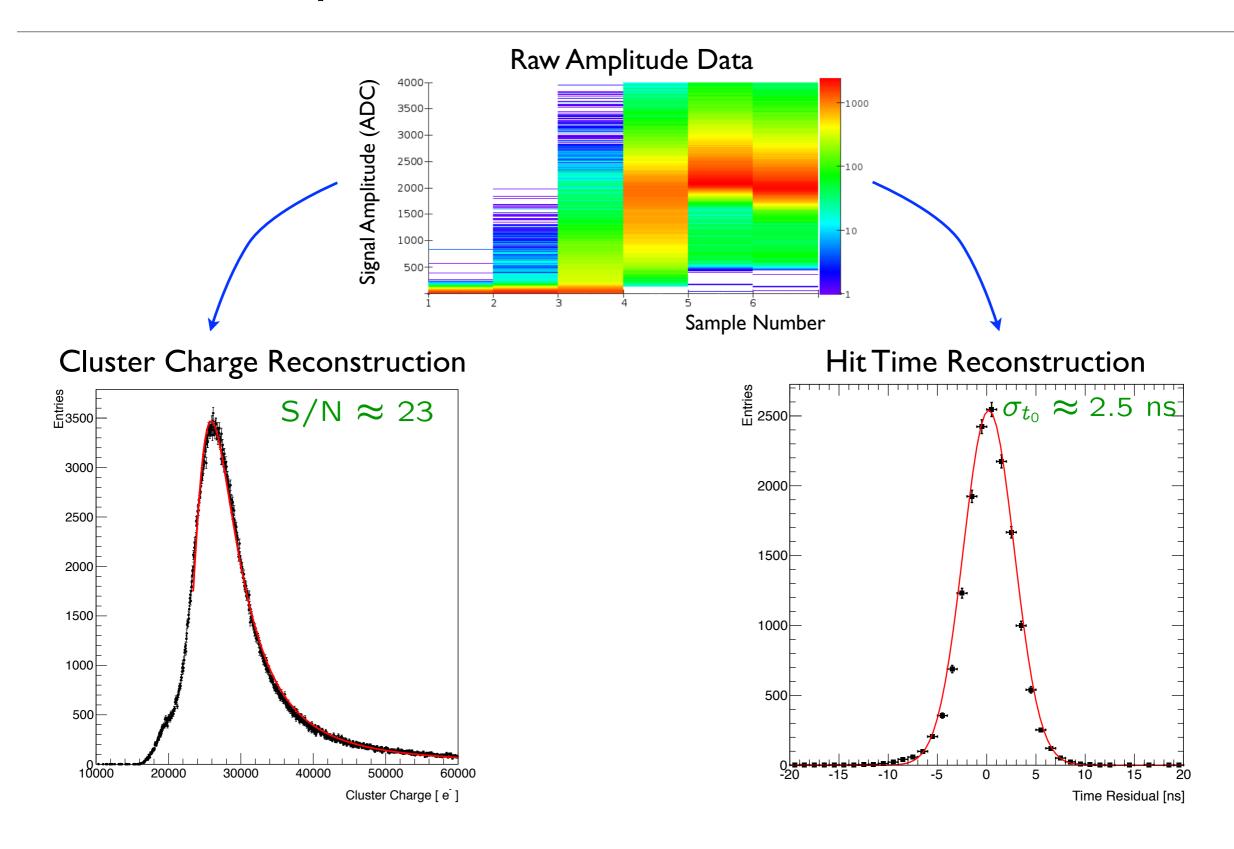
- Installed in Hall B on April 19 for parasitic photon run
- all chips responding
- no problems with vacuum

From: Graham, Mathew Thomas <mgraham@slac.stanford.edu> Subject: tracks, I think...

Date: May 3, 2012 3:10:54 PM PDT



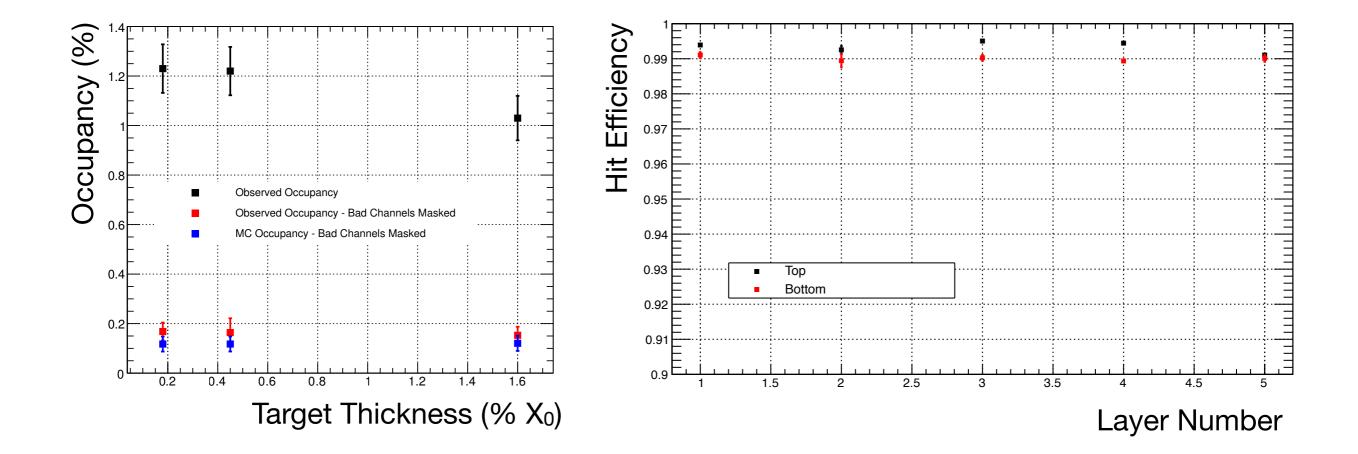
### Test SVT Amplitude and Time Reconstruction



## Test SVT Hit Occupancy and Efficiency

With noisy channels masked, occupancy is as expected...

and efficiency for finding hits on tracks is >99%.



### HPS Test SVT Lessons Learned

- We can build a movable, liquid cooled tracker that operates in beam vacuum
- We can build tracker with  $0.7\% X_0$  per 3-d measurement
- We can build a tracker with required efficiency, spatial and time resolution
- We can integrate SVT DAQ with JLab ECal DAQ and trigger
- We can do better for the HPS SVT,
  - Larger acceptance and better redundancy
  - Modules with flatter, colder sensors
  - Improved support rigidity
  - More reliable interconnect strategy
  - Fully tested and debugged DAQ

but it would be foolish to start from scratch!!

## HPS SVT Layout

### Evolution of HPS Test SVT

- Layers I-3: same as HPS Test SVT
- Layers 4-6: double width to match ECal acceptance and add extra hit.
- 36 sensors & hybrids
- 180 APV25 chips
- 23004 channels

z position, from target (cm)102030507090Stereo Angle (mrad)100100100505050Bend Plane Resolution ( $\mu$ m) $\approx 60$ $\approx 60$ $\approx 60$ $\approx 120$ $\approx 120$ $\approx 120$ Non-bend Resolution ( $\mu$ m) $\approx 6$ $\approx 6$ $\approx 6$ $\approx 6$ $\approx 6$ $\approx 6$ # Bend Plane Sensors22244# Stereo Sensors22244Dead Zone (mm) $\pm 1.5$ $\pm 3.0$ $\pm 4.5$ $\pm 7.5$ $\pm 10.5$ Power Consumption (W)7771414Id <tdid< td="">Id&lt;</tdid<>		Layer I	Layer 2	Layer 3	Layer 4	Layer 5	Layer 6
Bend Plane Resolution ( $\mu$ m) $\approx 60$ $\approx 60$ $\approx 60$ $\approx 120$ $\approx 120$ $\approx 120$ Non-bend Resolution ( $\mu$ m) $\approx 6$ $\approx 6$ $\approx 6$ $\approx 6$ $\approx 6$ $\approx 6$ # Bend Plane Sensors222444# Stereo Sensors222444Dead Zone (mm) $\pm 1.5$ $\pm 3.0$ $\pm 4.5$ $\pm 7.5$ $\pm 10.5$ $\pm 13.5$ Power Consumption (W)777141414VertexingPattern RecognitionMomentm	z position, from target (cm)	10	20	30	50	70	90
Non-bend Resolution ( $\mu$ m) $\approx 6$ # Bend Plane Sensors222444# Stereo Sensors222444Dead Zone (mm) $\pm 1.5$ $\pm 3.0$ $\pm 4.5$ $\pm 7.5$ $\pm 10.5$ $\pm 13.5$ Power Consumption (W)777141414VertexingPattern RecognitionM0mentM0mentm	Stereo Angle (mrad)	100	100	100	50	50	50
# Bend Plane Sensors22244# Stereo Sensors22244Dead Zone (mm)±1.5±3.0±4.5±7.5±10.5±13.5Power Consumption (W)777141414VertexingPattern RecognitionMomentm	Bend Plane Resolution (µm)	≈ 60	≈ 60	≈ 60	≈ 120	≈ 120	≈ 120
# Stereo Sensors22244Dead Zone (mm)±1.5±3.0±4.5±7.5±10.5±13.5Power Consumption (W)7771414VertexingVertexingPattern RecognitionMomentm	Non-bend Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6
Dead Zone (mm)±1.5±3.0±4.5±7.5±10.5±13.5Power Consumption (W)777141414VertexingPattern RecognitionM <or>omentm</or>	# Bend Plane Sensors	2	2	2	4	4	4
Power Consumption (W)     7     7     7     14     14     14       Vertexing     Vertexing     Pattern Recognition       M     o     m     e     n     t     u     m	# Stereo Sensors	2	2	2	4	4	4
Vertexing     Pattern Recognition       M o m     e n t u m	Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	±13.5
Momentum	Power Consumption (W)	7	7	7	14	14	14
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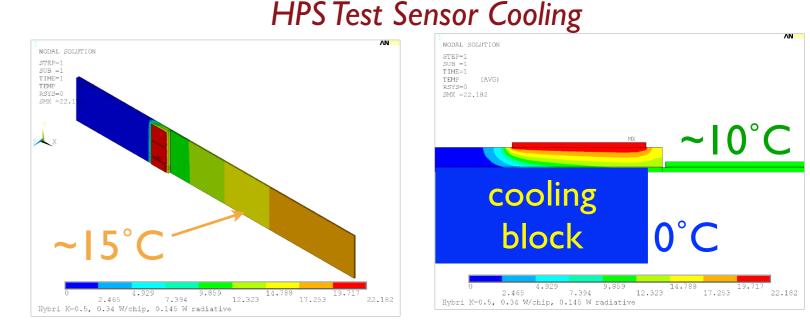
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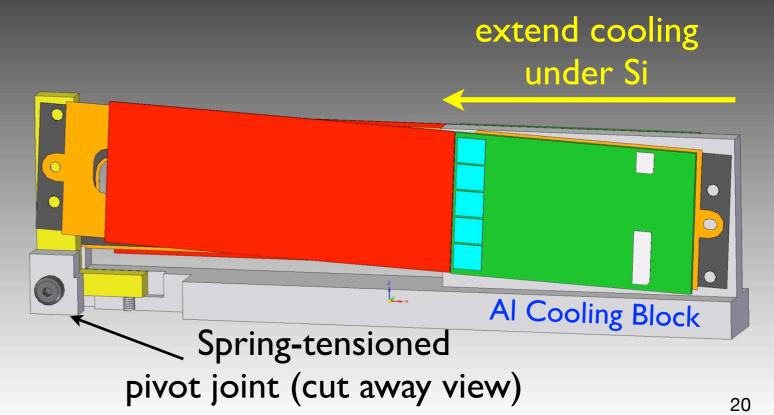
## Layer 1-3 Modules

Reuse half-modules from HPS Test, but design better module supports: tension CF between cooled uprights.

- better cooling to both ends of sensor reduces  $\Delta t$  to "hot spot" by ~80%
- support at both ends ensures overall straightness
- spring pivot with low-viscosity thermal ٠ compound keeps CF under tension:
  - stiffens/flattens half module
  - absorbs 60  $\mu m$  differential contraction during 30°C cooldown

#### A low-risk R&D effort



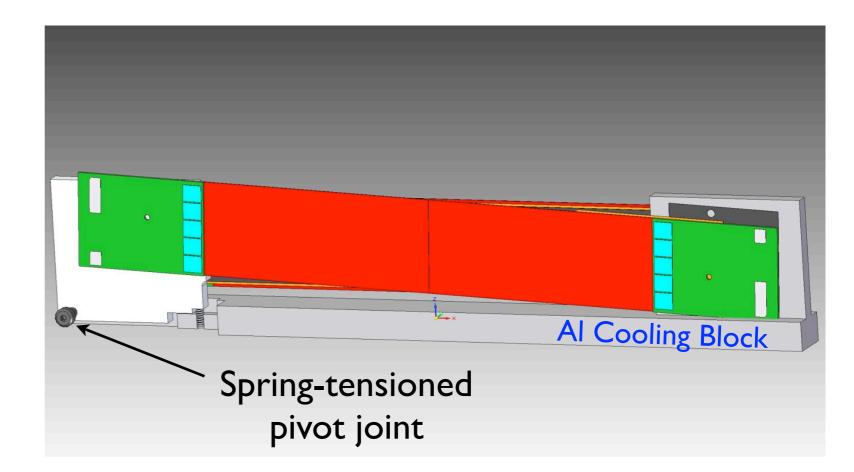


## Layer 4-6 Modules

Extending concept to L4-L6 allows same material budget for long modules.

- Build new "double-ended" halfmodules using same techniques as HPS Test.
  - similar CF frame, kapton passivation
  - shorter hybrid design omits unnecessary components, uses flex pigtails

A low-risk redesign of test run half-modules



# Support, Cooling and Services

#### Cooled support channels for L1-L3

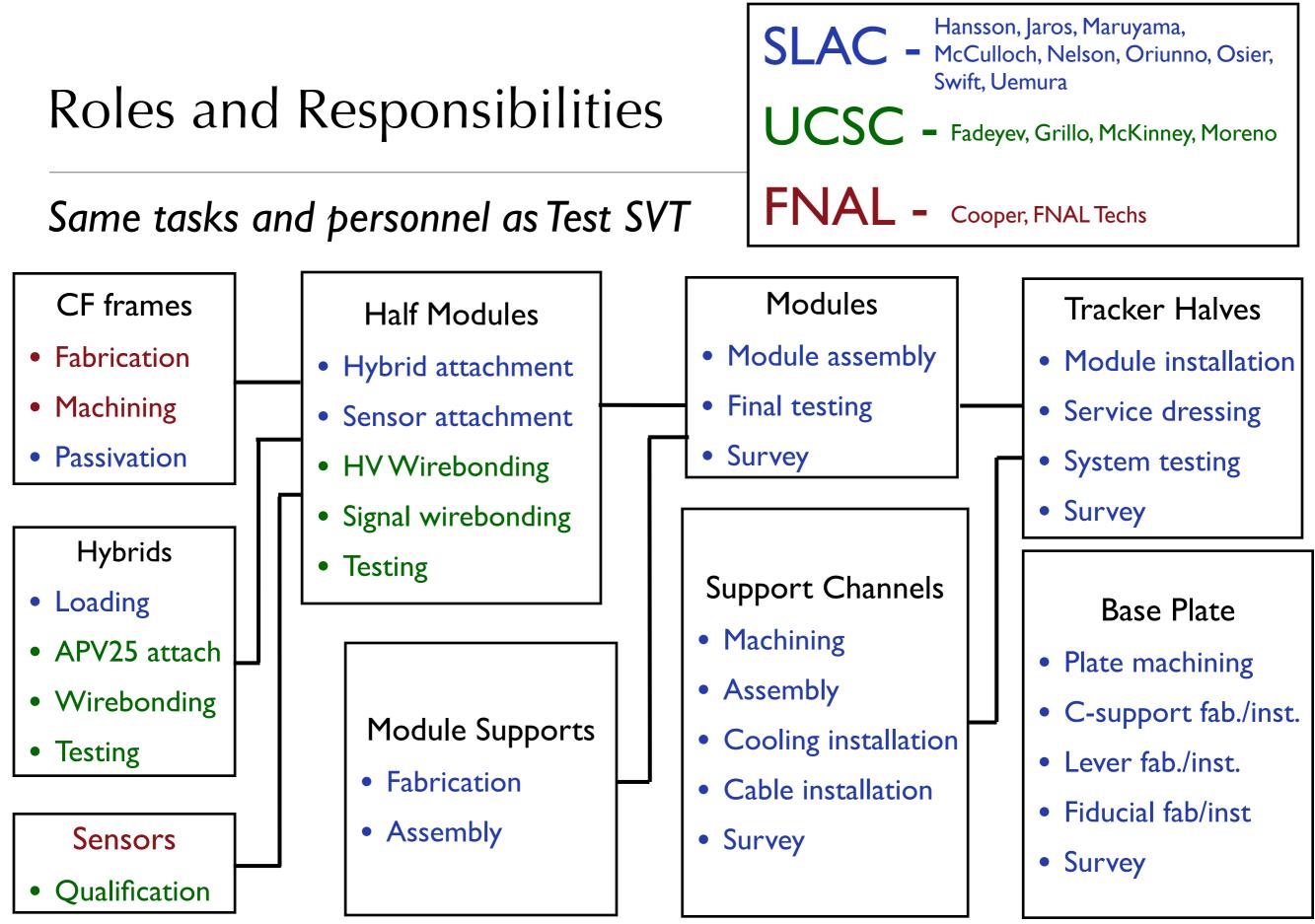
- reuse c-support, motion levers
- lighter, stiffer, shorter = less sag
- cuts radiative heat load on sensors

#### Cooled support channels for L4-L6 are stationary

#### DAQ/power inside chamber on cooling plate

- Reduces readout plant
- Low-neutron region (upstream, e<sup>+</sup> side)
- Board spacing minimizes flex cable designs

- Reuse vacuum box and linear shifts with new vacuum flanges
- New chiller operable to -10°C with 1°C stability.
- Use new Wiener MPODs for power



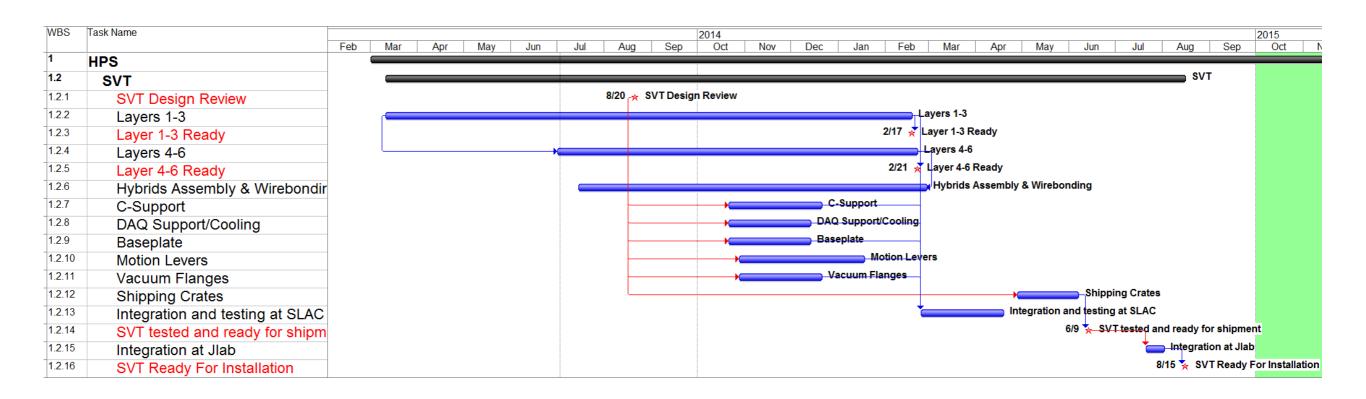
# Project Budget

- SVT "upgrades" have been designed around scope we understand; scope of the Test SVT
- Budget includes significant contingency beyond actual spending on similar items for Test SVT

	Labor (w/ cont.)	Material (w/ cont.)	Total (w/ cont.)	Capital Eq.
Layers 1-3	\$66K	\$37K	\$103K	\$103K
Layers 4-6	\$107K	\$86K	\$193K	\$175K
Support, Cooling, Vacuum	\$I43K	\$20K	\$163K	\$107K
Testing, Shipping, Integration	\$136K	\$61K	\$197K	\$I54K
Total	\$452K	\$204K	\$656K	\$539K

Biggest items are completely new modules for Layers 4-6 and testing/integration at SLAC.

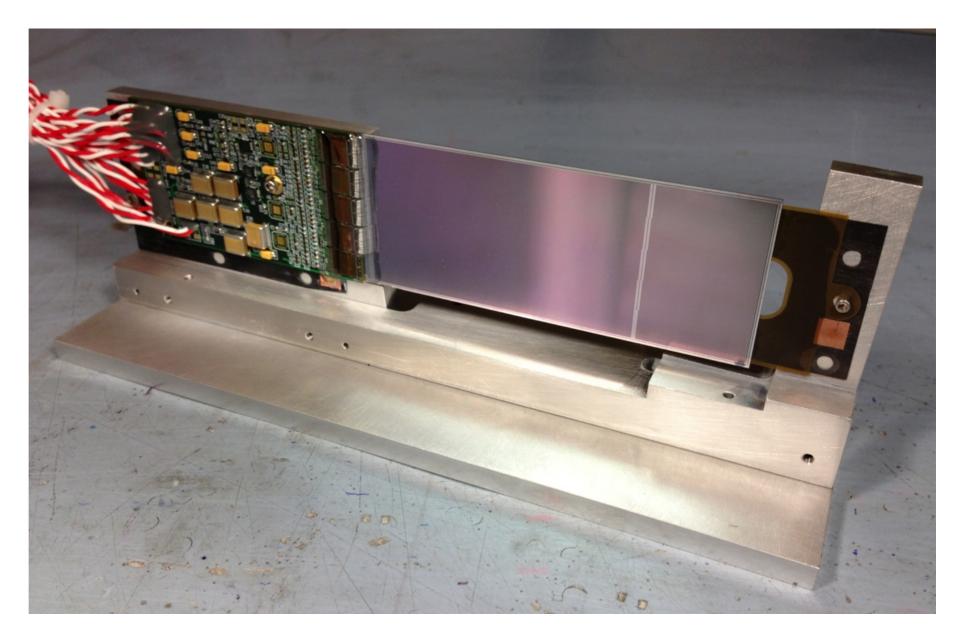
## Schedule



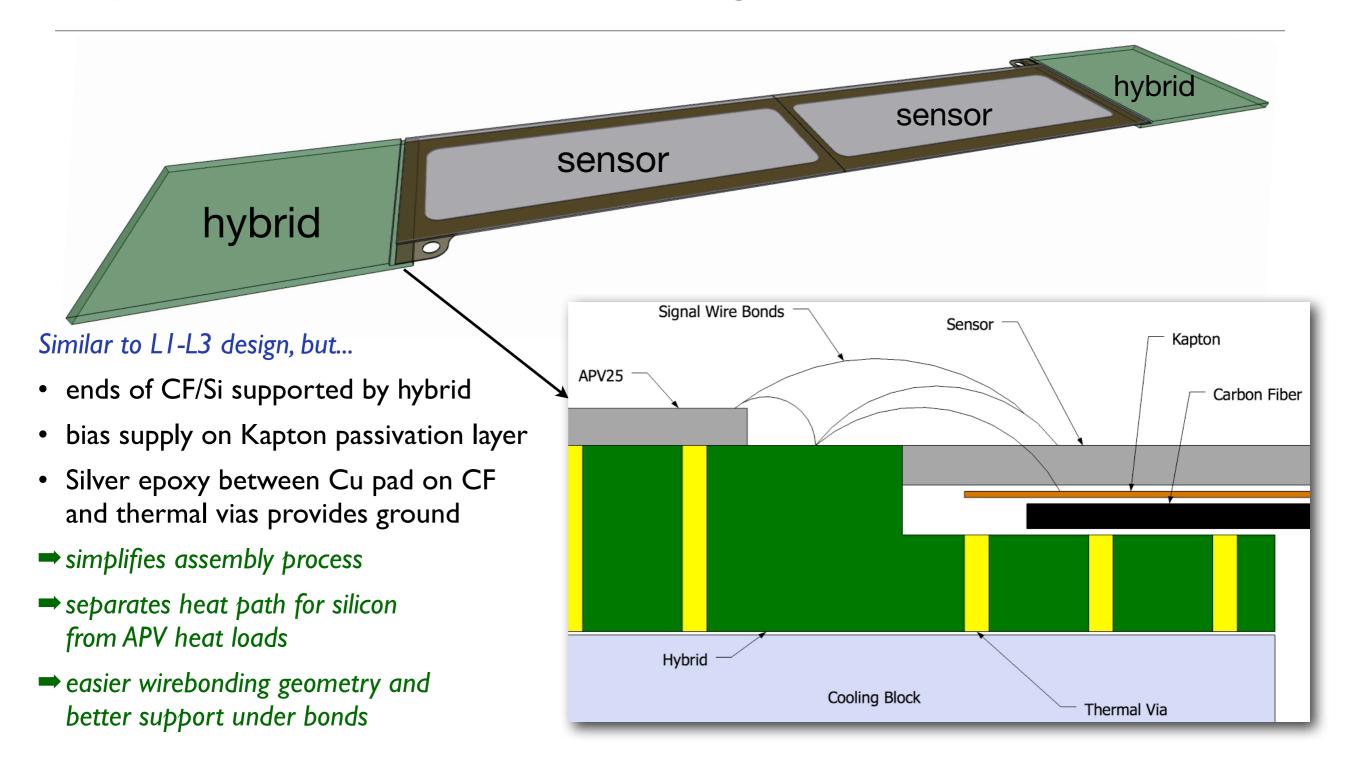
- •Comfortable relative to schedule for HPS Test, but still quite busy
- •Critical path hangs off of funding availability
- •Tasks we must begin during "keepalive" period to keep them off critical path:
  - Design and prototyping of new module supports for Layers 1-3: well underway
  - Design and prototyping of new half-modules for Layers 4-6: begun
  - Early design work on new support plates and detector integration: beginning in August

## Layer 1-3 Supports

- Prototype delivered to SLAC 10 days ago.
- Testing underway, looks good so far.
- Cost was \$1100: budget is \$1640 each. (16 total for all layers)
- If testing is successful, LI-L3 modules are essentially done.



## Layer 4-6 Half-Module Design

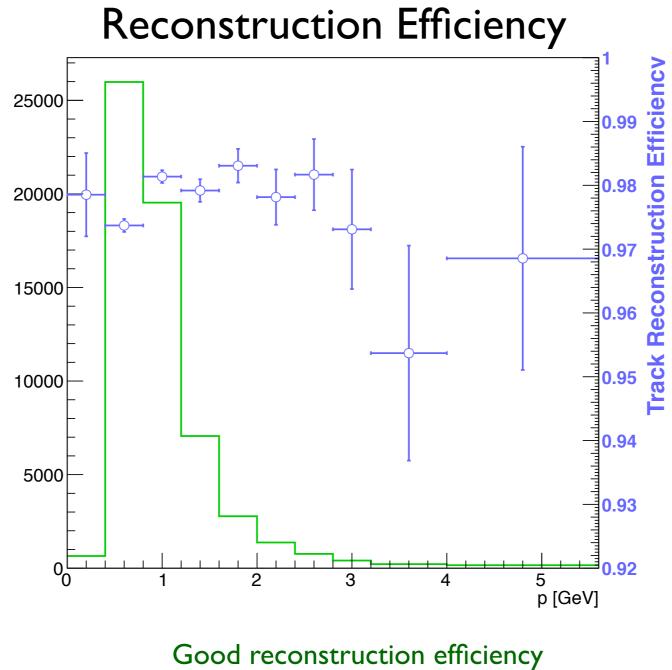


currently developing assembly fixture concept along with design details required for assembly.

## Summary

- The HPS Test SVT got most things right and performed well
  - Met key performance goals for material, position and time resolution.
  - Less-than 100% coverage mostly resulted from lack of time for testing/debugging.
  - Acceptance, redundancy, mechanical precision, and cooling could be improved.
- Modest upgrades to the Test SVT can address all of these
  - Project scope is, by design, very similar to that for HPS Test SVT
  - Minimal budget risk, which is generous relative to Test SVT actual costs.
  - Schedule risk is modest if funding becomes available at beginning of FY14.
  - First steps on critical path are underway.
- Together with upgraded DAQ, the new SVT should deliver expected physics reach.

### Track Reconstruction Efficiency



even without full alignment