The HPS SVT

Tim Nelson - SLAC

HPS DOE Review July 11, 2013



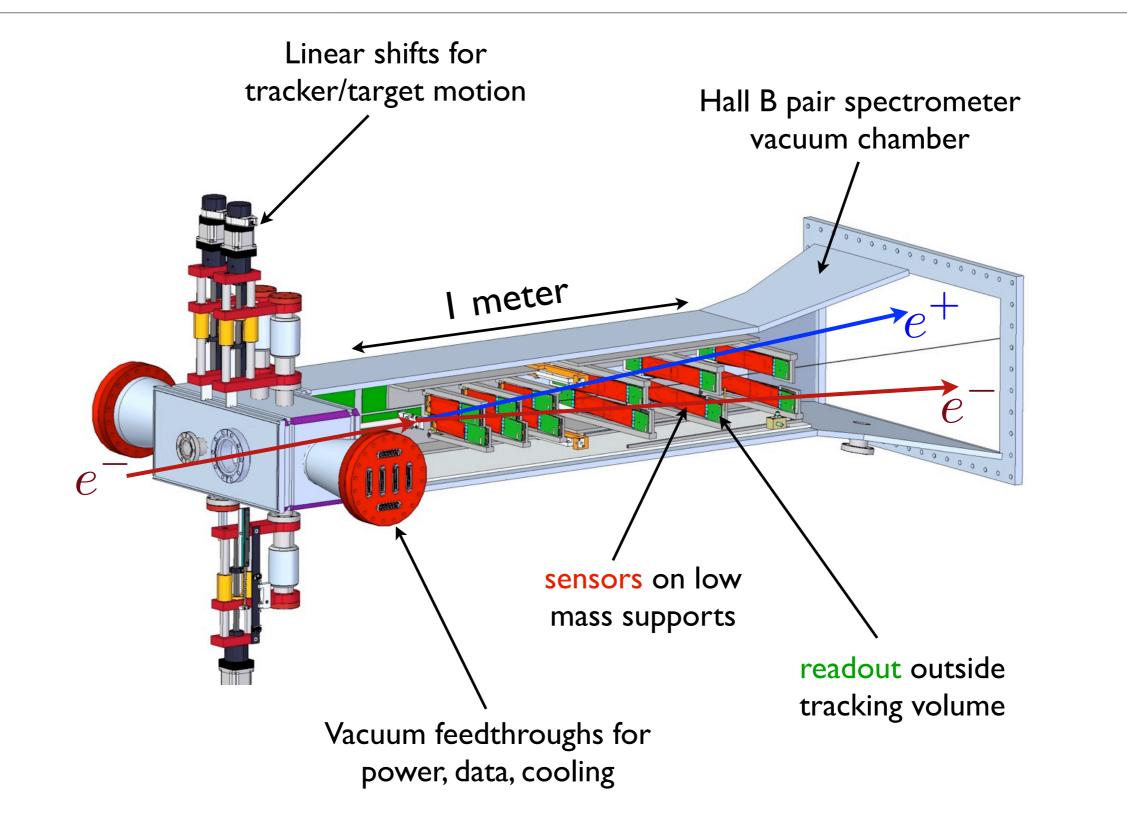
Outline

- Overview of SVT and requirements
- Key components
- •Where we've been: HPS Test SVT
- •Where we're going: HPS SVT
- How we'll get there.

The HPS SVT...

- provides estimates of trajectories of low-momentum charged particles
 - Momentum at production vertex candidate A' mass
 - Vertex position candidate A' lifetime
- minimizes multiple scattering effects that dominate uncertainties in these estimates
 - Material is the primary enemy
 - Requirements for single-hit and alignment precision are modest
- optimizes acceptance by instrumenting as close to scattered primary beam as possible
 - Operation in vacuum
 - Radiation tolerance
 - Fast trigger and DAQ
 - Excellent hit timing

SVT Overview



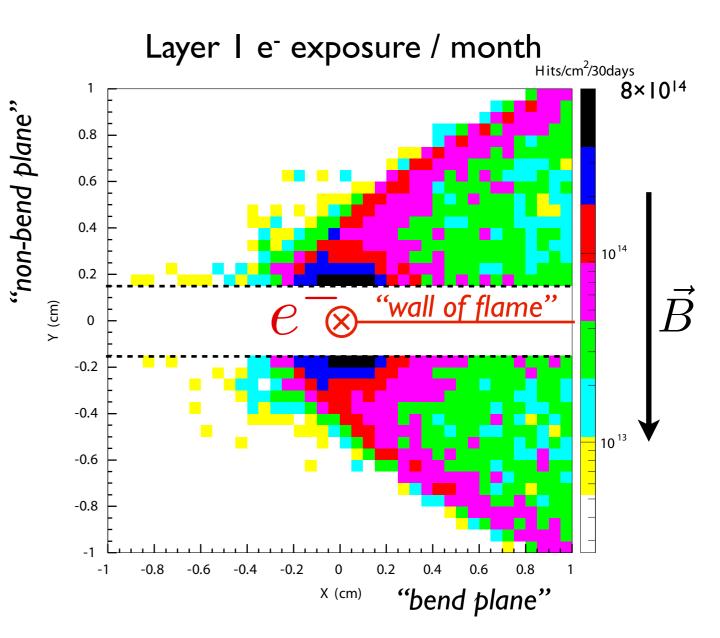
Optimizing Acceptance

High-mass is simple in principle: build it as big as you can afford!

Low-mass is harder: requires acceptance very close to beam

At 15 mrad, 10 cm from target (L1):

- Active detector ~1.5 mm from beam
- Peak occupancy ~4 MHz/mm²
- Fluence $4.8 \times 10^{15} e^{-} \cong 1.6 \times 10^{14}$ neq. in 6 months of running



Sensor Selection

Also need...

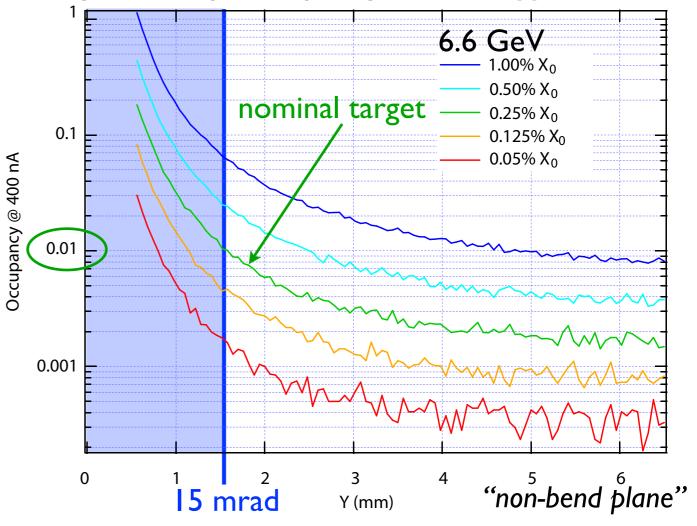
- < $1\% X_0$ per layer
- ≤ 50 µm single-hit resolution
 in both measurement coordinates
- < \$1M for a complete system, soon!

MAPS?

Hybrid pixels?

Strip sensors (edges $500 \ \mu m$ from beam!)

Layer I strip occupancy / 8 ns trigger window

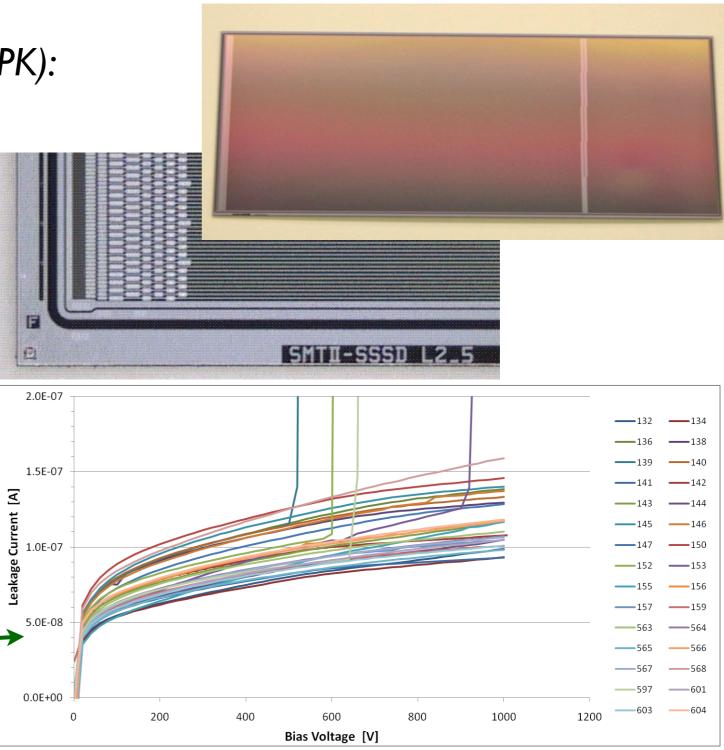


Silicon Microstrip Sensors

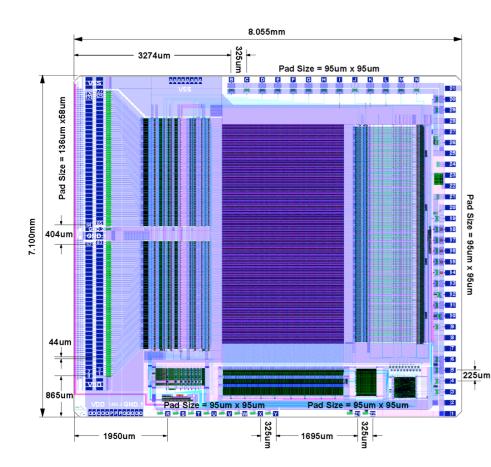
Production Tevatron RunIIb sensors (HPK):

- Fine readout granularity
- most capable of 1000V bias: fully depleted for 6 month run.
- Available in sufficient quantities
- Cheapest technology (contribution from FNAL)

Technology	<100>, p+ in n, AC-coupled
Active Area (L×W)	98.33 mm × 38.34mm
Readout (Sense) Pitch	60μm (30μm)
Breakdown Voltage	>350V
Interstrip Capacitance	<1.2 pF/cm
Defective Channels	<0.1%



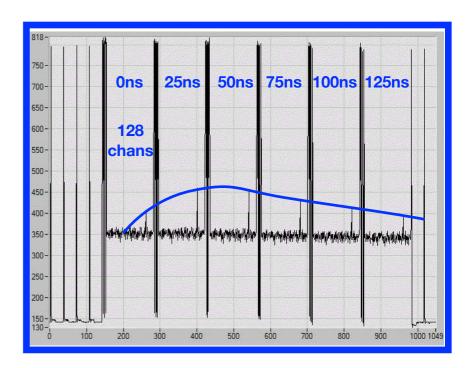
Front-end Electronics: APV25

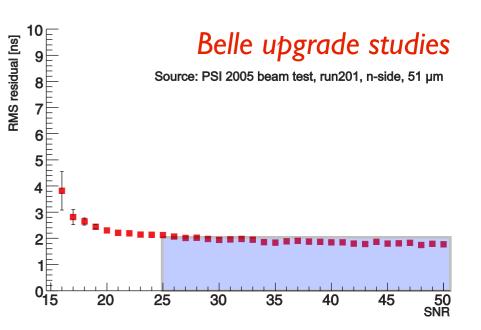


# Readout Channels	128
Input Pitch	44 μm
Shaping Time	50ns nom. (35ns min.)
Noise Performance	270+36×C(pF) e ⁻ ENC
Power Consumption	345 mW

Developed for CMS

- available (28 CHF/ea.)
- radiation tolerant
- fast front end
 (35 ns shaping time)
- low noise (S/N > 25)
- "multi-peak" readout
 ~2 ns t₀ resolution!





Optimizing Detector Layout

Using SLIC/Icsim framework for simulation and reconstruction of both MC and data

- Detailed model of detector response for MC
 - Silicon charge deposition/collection
 - Time response and multi-peak readout of APV25 front end
 - Time-sequenced overlay of backgrounds
- Same hit and track reconstruction tools for both MC and data
 - Amplitude, time reconstruction, and clustering of hits
 - Track finding and fitting
 - Can produce MC using constants established with data

This high level of detail is critical for establishing vertex reach (10-7 prompt rejection!)

Initially Proposed Layout

A no-compromises approach with best possible mass and vertexing resolution over large acceptance

- 106 sensors & hybrids
- 530 APV25 chips
- 67840 channels

A relatively large and expensive detector.

Requires large magnet, vacuum chamber and ECal also.

How do we prove this works?

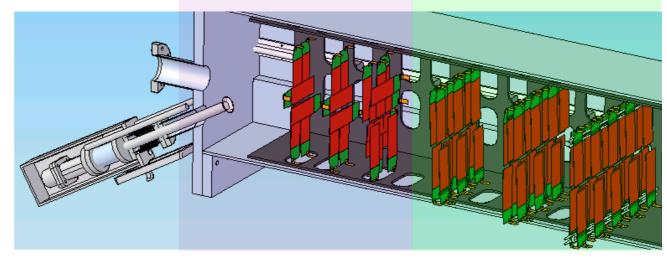
	Layer I	Layer 2	Layer 3	Layer 4	Layer 5	Layer 6
z position, from target (cm)	10	20	30	50	70	90
Stereo Angle	90 deg.	90 deg.	90 deg.	50 mrad	50 mrad	50 mrad
Bend Plane Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6
Stereo Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 120	≈ 120	≈ 120
# Bend Plane Sensors	4	4	6	10	14	18
# Stereo Sensors	2	2	4	10	14	18
Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	±13.5
Power Consumption (W)	10.5	10.5	17.5	35	49	63

Vertexing

Pattern Recognition

Мо

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HPS Test SVT

Proposed 3/11, Installed 4/12

- Develop technical solutions
- Prove operational principles
- Capable of A' physics

Linear shifts for – tracker/target motio

 e^{-}

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stalled 4/12		Layer I	Layer 2	Layer 3	Layer 4	Layer 5	
	z position, from target (cm)	10	20	30	50	70	
al solutions	Stereo Angle (mrad)	100	100	100	50	50	
	Bend Plane Resolution (µm)	≈ 60	≈ 60	≈ 60	≈ 120	≈ 120	
al principles	Non-Bend Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	
hysics	# Bend Plane Sensors	2	2	2	2	2	
hysics	# Stereo Sensors	2	2	2	2	2	
	Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	
	Power Consumption (W)	7	7	7	7	7	
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Test SVT Modules

Half Module

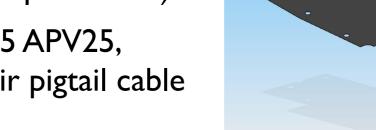
- 0.17 mm thick CF frame (FE grounded, HV passivated)
- FR4 hybrid with 5 APV25, short twisted-pair pigtail cable
- single sensor

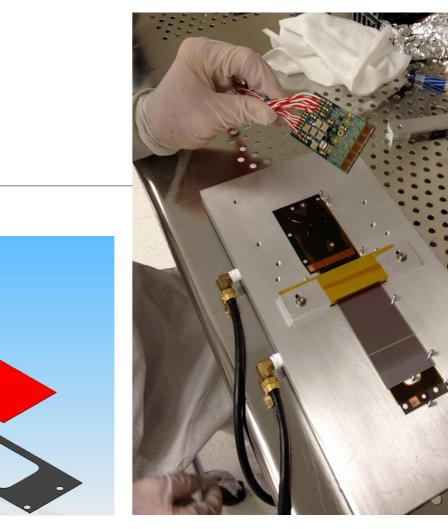
Full module -

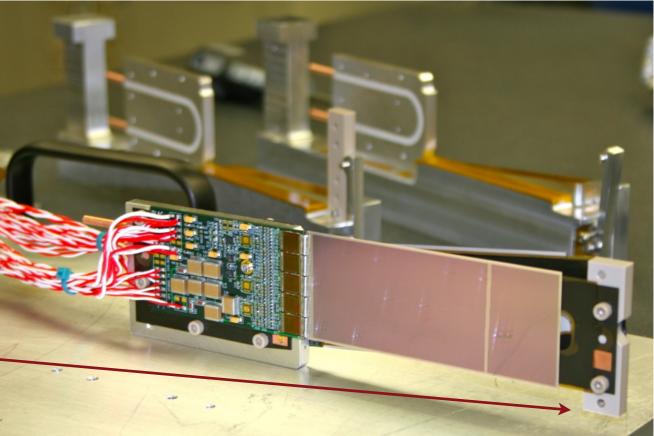
- Two half-modules back-to-back on Al cooling block w/ Cu tubes
- glue-less assembly with PEEK spacer block and hardware

$0.7\% X_0$ average per layer

Limits flatness/stability of Si -





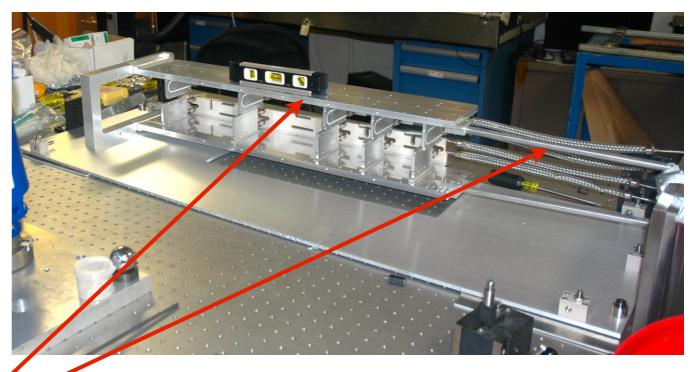


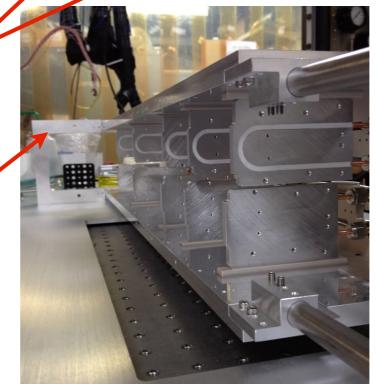
Test SVT Mechanics

Cooling blocks mount on Al support plates with hinged "C-support" and motion lever

- Provide solid mounting for modules, routing for services, and simple motion for tracker
- PEEK pedestals create 15 mr dead zone, provide some thermal isolation
- Support plates + motion levers ~1.5 m long: sag dominates x-y imprecision (300 μm)
- Load on C-support introduces small roll in top plate.

Works, but can be improved upon

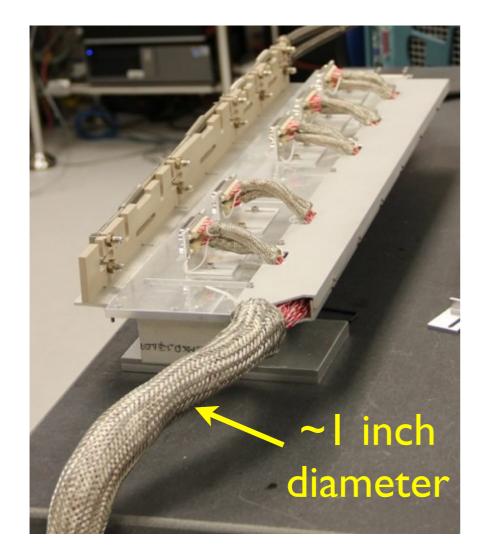


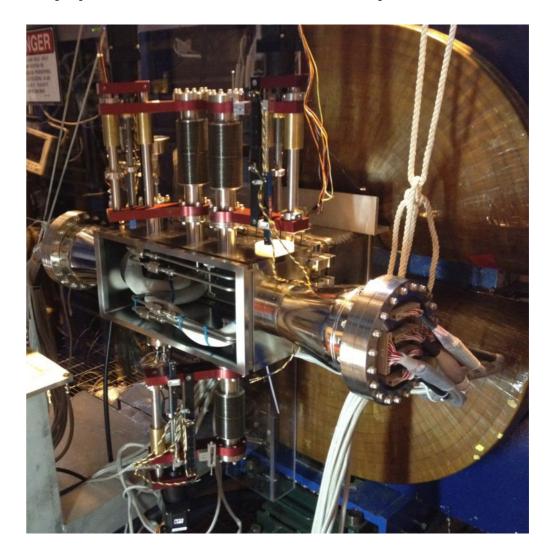




Test SVT Services

- Borrowed CDF SVXII power supplies (very crufty) and JLab chiller (limited to $> 0^{\circ}$ C)
- Intricate welded cooling manifolds with 2 compression fittings/module
- 600 wires into vacuum chamber for power and data (3600 total pairs of connector contacts): recovered three sensors with internal connectivity problems after assembly/installation at JLab



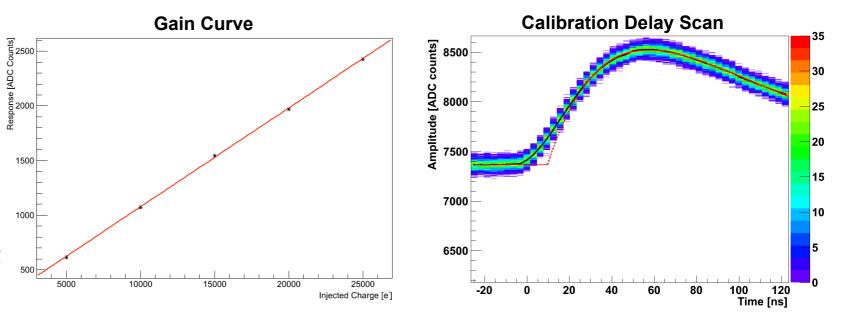


We got away with this, but it doesn't scale well to a larger detector.

Test SVT Assembly, Commissioning, Operation

At SLAC:

- Began with 165 APV25 (enough for 33 hybrids)
- 29/30 hybrids passed QA
- 28/29 half-modules passed QA
- Good noise, linearity, uniformity
- Assembly precision at cooling block: x-y ~10 μ m, z ~ 25 μ m
- Flatness (z) along sensor $\sim 200 \ \mu m$



At JLab:

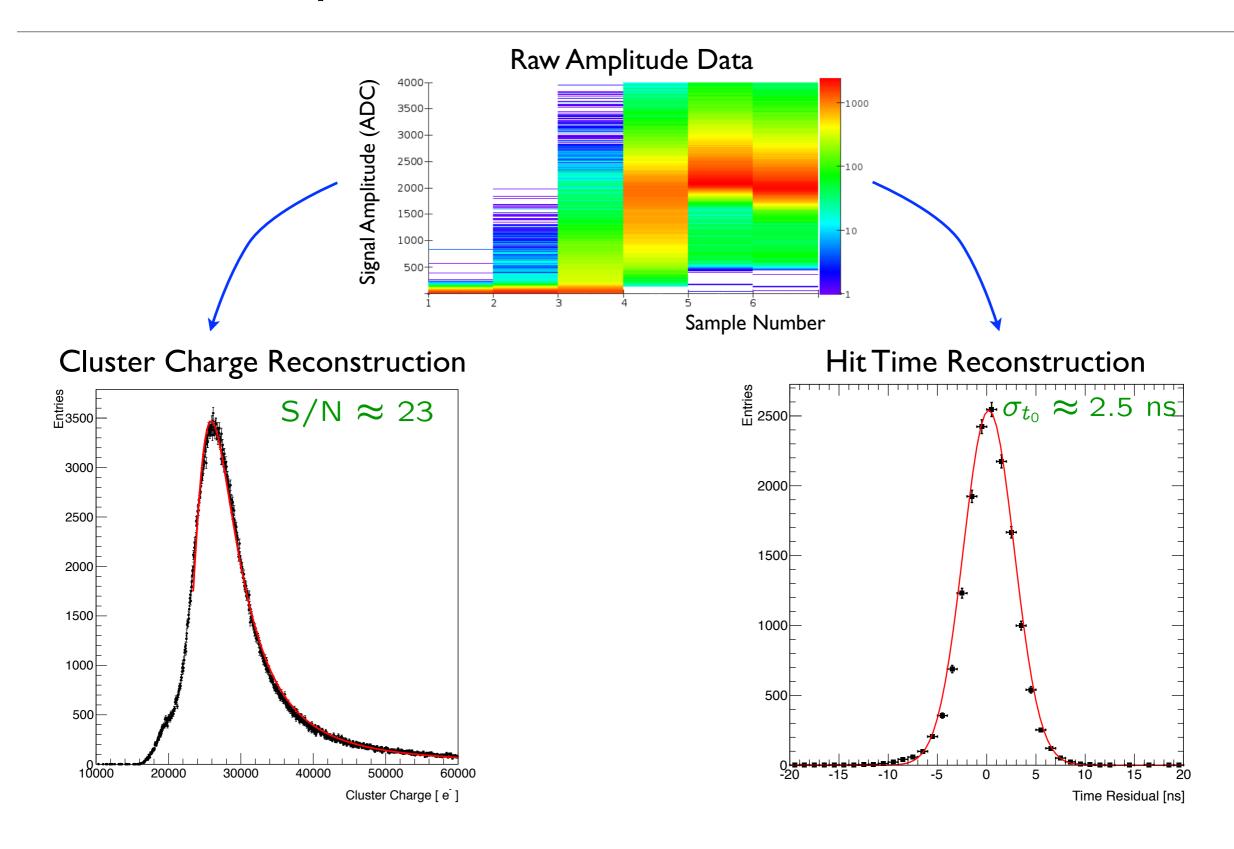
- Installed in Hall B on April 19 for parasitic photon run
- all chips responding
- no problems with vacuum

From: Graham, Mathew Thomas <mgraham@slac.stanford.edu> Subject: tracks, I think...

Date: May 3, 2012 3:10:54 PM PDT



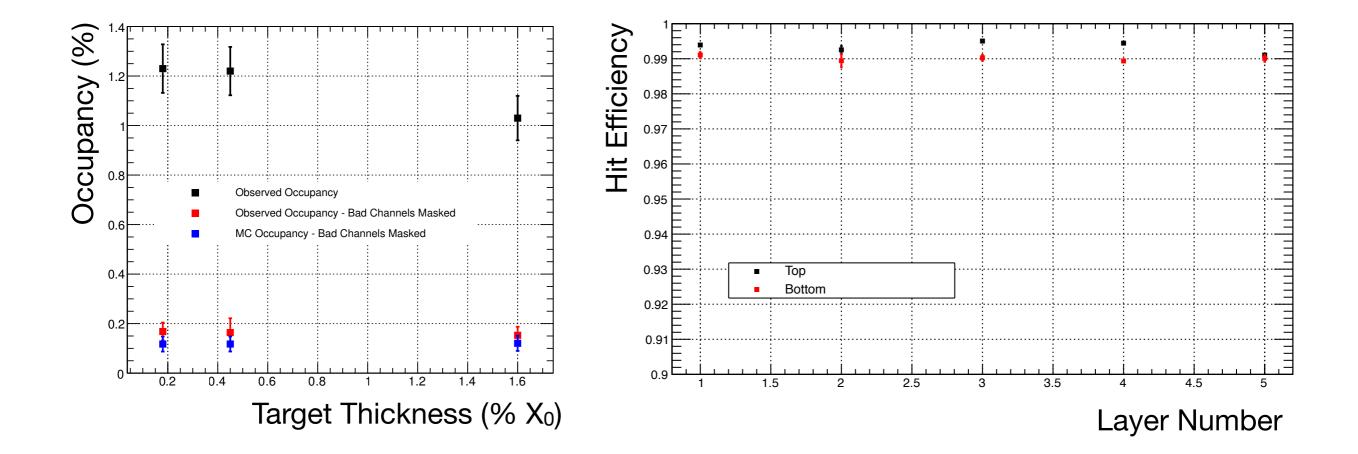
Test SVT Amplitude and Time Reconstruction



Test SVT Hit Occupancy and Efficiency

With noisy channels masked, occupancy is as expected...

and efficiency for finding hits on tracks is >99%.



HPS Test SVT Lessons Learned

- We can build a movable, liquid cooled tracker that operates in beam vacuum
- We can build tracker with $0.7\% X_0$ per 3-d measurement
- We can build a tracker with required efficiency, spatial and time resolution
- We can integrate SVT DAQ with JLab ECal DAQ and trigger
- We can do better for the HPS SVT,
 - Larger acceptance and better redundancy
 - Modules with flatter, colder sensors
 - Improved support rigidity
 - More reliable interconnect strategy
 - Fully tested and debugged DAQ

but it would be foolish to start from scratch!!

HPS SVT Layout

Evolution of HPS Test SVT

- Layers I-3: same as HPS Test SVT
- Layers 4-6: double width to match ECal acceptance and add extra hit.
- 36 sensors & hybrids
- 180 APV25 chips
- 23004 channels

z position, from target (cm)102030507090Stereo Angle (mrad)100100100505050Bend Plane Resolution (μ m) ≈ 60 ≈ 60 ≈ 60 ≈ 120 ≈ 120 ≈ 120 Non-bend Resolution (μ m) ≈ 6 ≈ 6 ≈ 6 ≈ 6 ≈ 6 ≈ 6 # Bend Plane Sensors22244# Stereo Sensors22244Dead Zone (mm) ± 1.5 ± 3.0 ± 4.5 ± 7.5 ± 10.5 Power Consumption (W)7771414Id <tdid< td="">Id<</tdid<>		Layer I	Layer 2	Layer 3	Layer 4	Layer 5	Layer 6
Bend Plane Resolution (μ m) ≈ 60 ≈ 60 ≈ 60 ≈ 120 ≈ 120 ≈ 120 Non-bend Resolution (μ m) ≈ 6 ≈ 6 ≈ 6 ≈ 6 ≈ 6 ≈ 6 # Bend Plane Sensors222444# Stereo Sensors222444Dead Zone (mm) ± 1.5 ± 3.0 ± 4.5 ± 7.5 ± 10.5 ± 13.5 Power Consumption (W)777141414VertexingPattern RecognitionMomentm	z position, from target (cm)	10	20	30	50	70	90
Non-bend Resolution (μ m) ≈ 6 # Bend Plane Sensors222444# Stereo Sensors222444Dead Zone (mm) ± 1.5 ± 3.0 ± 4.5 ± 7.5 ± 10.5 ± 13.5 Power Consumption (W)777141414VertexingPattern RecognitionM0mentM0mentm	Stereo Angle (mrad)	100	100	100	50	50	50
# Bend Plane Sensors22244# Stereo Sensors22244Dead Zone (mm)±1.5±3.0±4.5±7.5±10.5±13.5Power Consumption (W)777141414VertexingPattern RecognitionMomentm	Bend Plane Resolution (µm)	≈ 60	≈ 60	≈ 60	≈ 120	≈ 120	≈ 120
# Stereo Sensors22244Dead Zone (mm)±1.5±3.0±4.5±7.5±10.5±13.5Power Consumption (W)7771414VertexingVertexingPattern RecognitionMomentm	Non-bend Resolution (µm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6
Dead Zone (mm)±1.5±3.0±4.5±7.5±10.5±13.5Power Consumption (W)777141414VertexingPattern RecognitionM <or>omentm</or>	# Bend Plane Sensors	2	2	2	4	4	4
Power Consumption (W) 7 7 7 14 14 14 Vertexing Vertexing Pattern Recognition M o m e n t u m	# Stereo Sensors	2	2	2	4	4	4
Vertexing Pattern Recognition M o m e n t u m	Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	±13.5
Momentum	Power Consumption (W)	7	7	7	14	14	14
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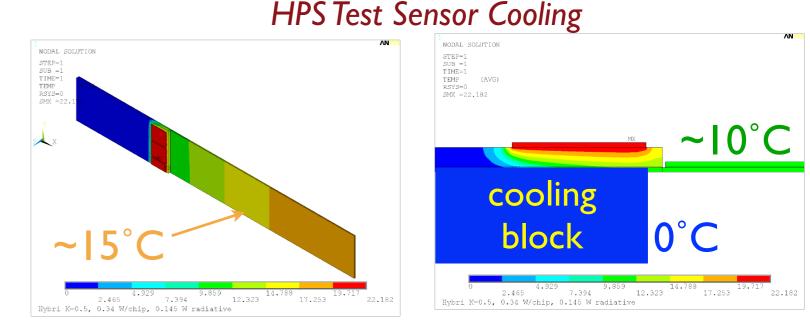
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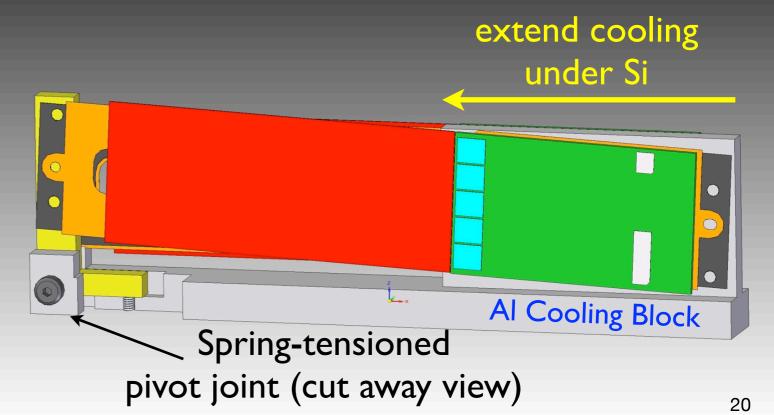
Layer 1-3 Modules

Reuse half-modules from HPS Test, but design better module supports: tension CF between cooled uprights.

- better cooling to both ends of sensor reduces Δt to "hot spot" by ~80%
- support at both ends ensures overall straightness
- spring pivot with low-viscosity thermal ٠ compound keeps CF under tension:
 - stiffens/flattens half module
 - absorbs 60 μm differential contraction during 30°C cooldown

A low-risk R&D effort



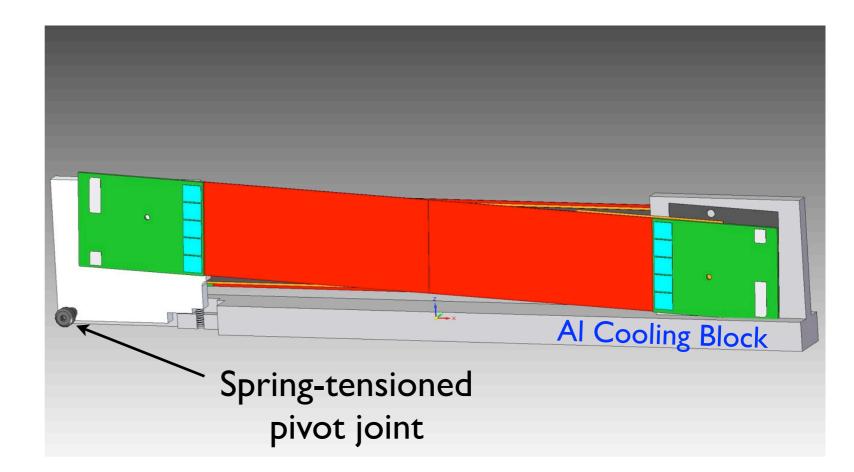


Layer 4-6 Modules

Extending concept to L4-L6 allows same material budget for long modules.

- Build new "double-ended" halfmodules using same techniques as HPS Test.
 - similar CF frame, kapton passivation
 - shorter hybrid design omits unnecessary components, uses flex pigtails

A low-risk redesign of test run half-modules



Support, Cooling and Services

Cooled support channels for L1-L3

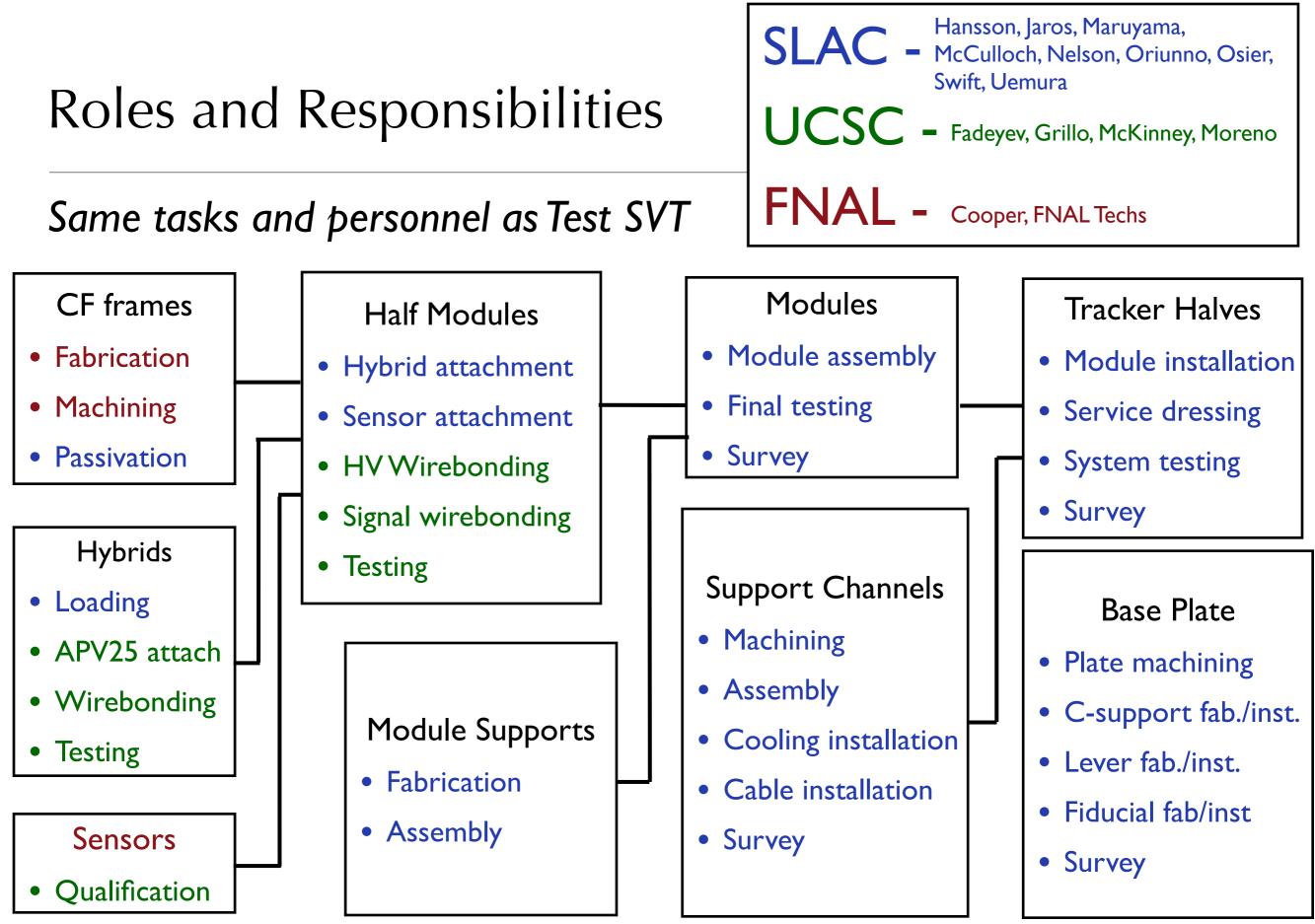
- reuse c-support, motion levers
- lighter, stiffer, shorter = less sag
- cuts radiative heat load on sensors

Cooled support channels for L4-L6 are stationary

DAQ/power inside chamber on cooling plate

- Reduces readout plant
- Low-neutron region (upstream, e⁺ side)
- Board spacing minimizes flex cable designs

- Reuse vacuum box and linear shifts with new vacuum flanges
- New chiller operable to -10°C with 1°C stability.
- Use new Wiener MPODs for power



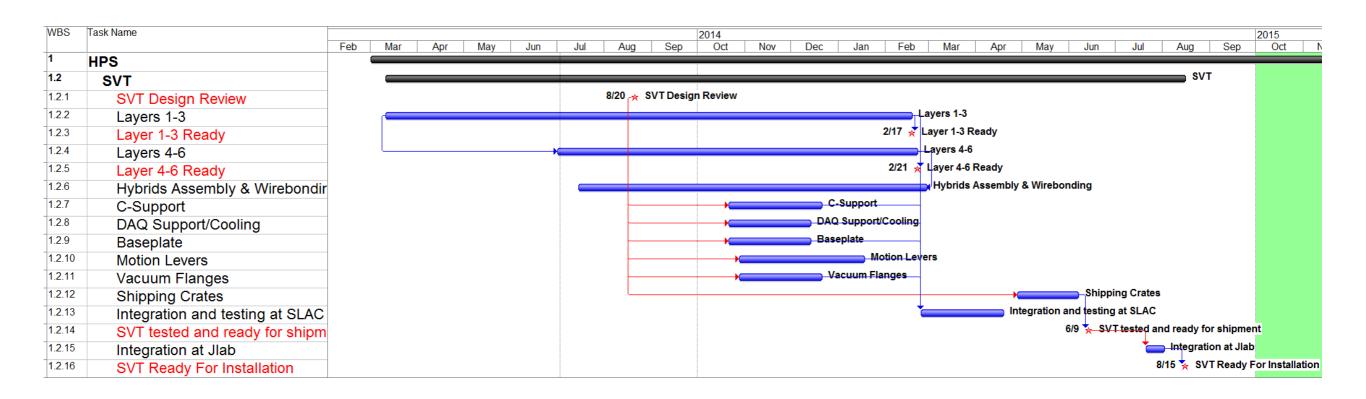
Project Budget

- SVT "upgrades" have been designed around scope we understand; scope of the Test SVT
- Budget includes significant contingency beyond actual spending on similar items for Test SVT

	Labor (w/ cont.)	Material (w/ cont.)	Total (w/ cont.)	Capital Eq.
Layers 1-3	\$66K	\$37K	\$103K	\$103K
Layers 4-6	\$107K	\$86K	\$193K	\$175K
Support, Cooling, Vacuum	\$I43K	\$20K	\$163K	\$107K
Testing, Shipping, Integration	\$136K	\$61K	\$197K	\$I54K
Total	\$452K	\$204K	\$656K	\$539K

Biggest items are completely new modules for Layers 4-6 and testing/integration at SLAC.

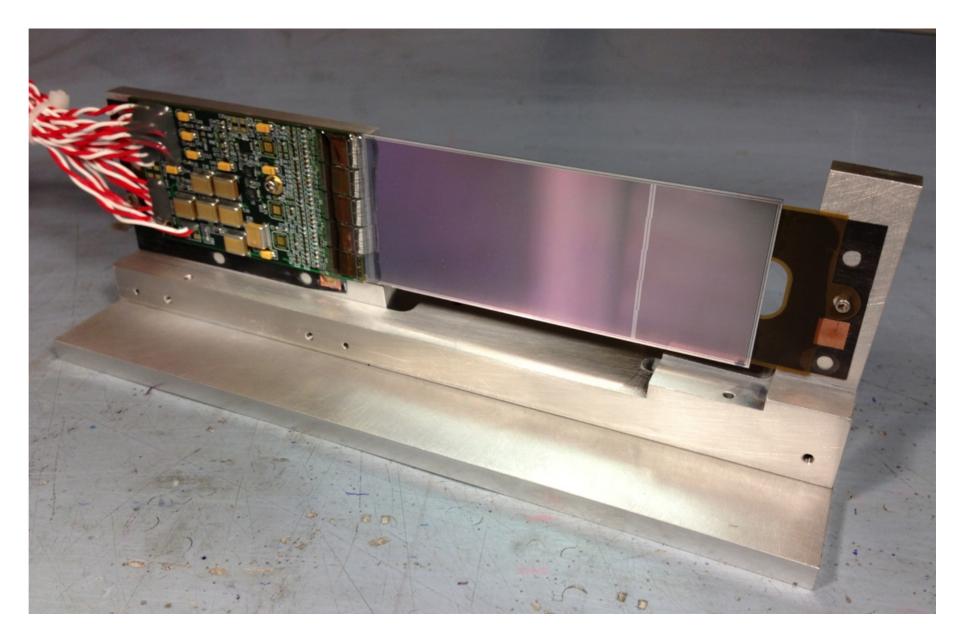
Schedule



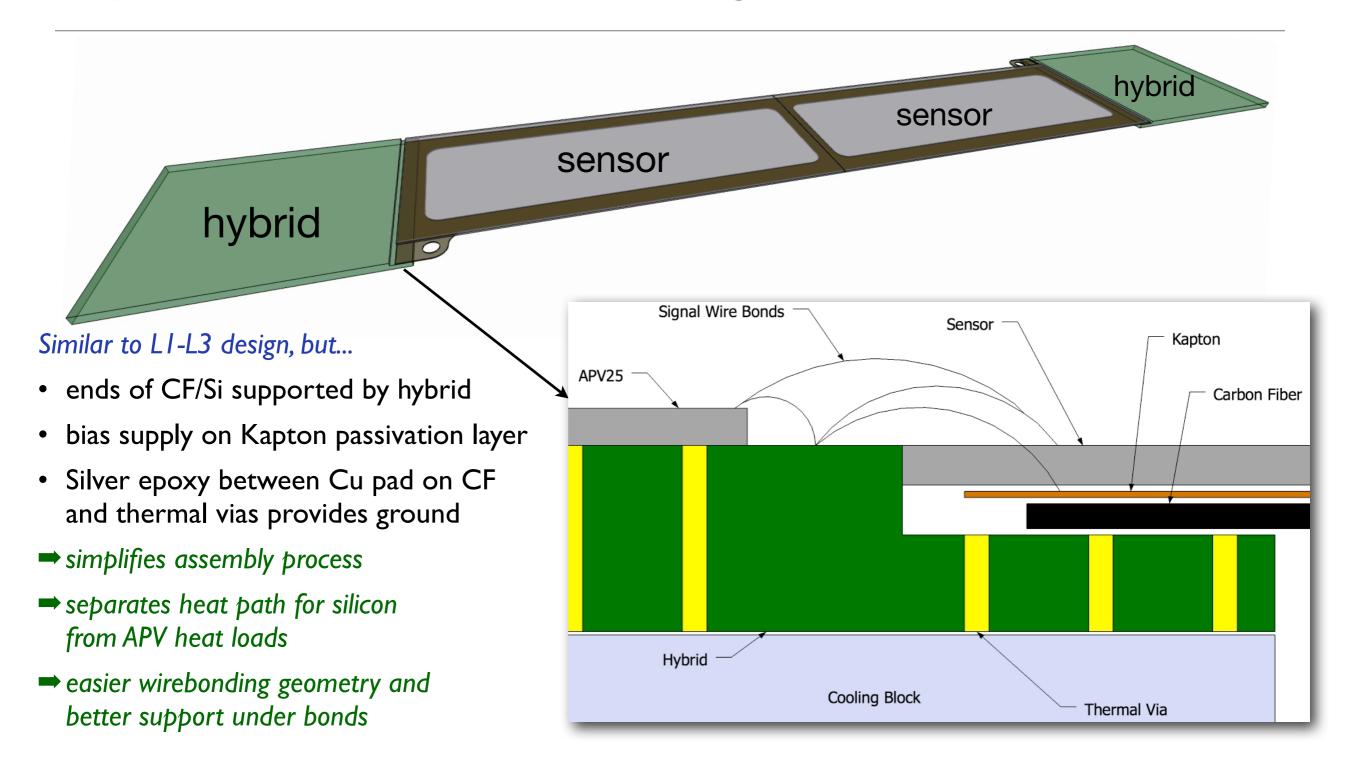
- •Comfortable relative to schedule for HPS Test, but still quite busy
- •Critical path hangs off of funding availability
- •Tasks we must begin during "keepalive" period to keep them off critical path:
 - Design and prototyping of new module supports for Layers 1-3: well underway
 - Design and prototyping of new half-modules for Layers 4-6: begun
 - Early design work on new support plates and detector integration: beginning in August

Layer 1-3 Supports

- Prototype delivered to SLAC 10 days ago.
- Testing underway, looks good so far.
- Cost was \$1100: budget is \$1640 each. (16 total for all layers)
- If testing is successful, LI-L3 modules are essentially done.



Layer 4-6 Half-Module Design

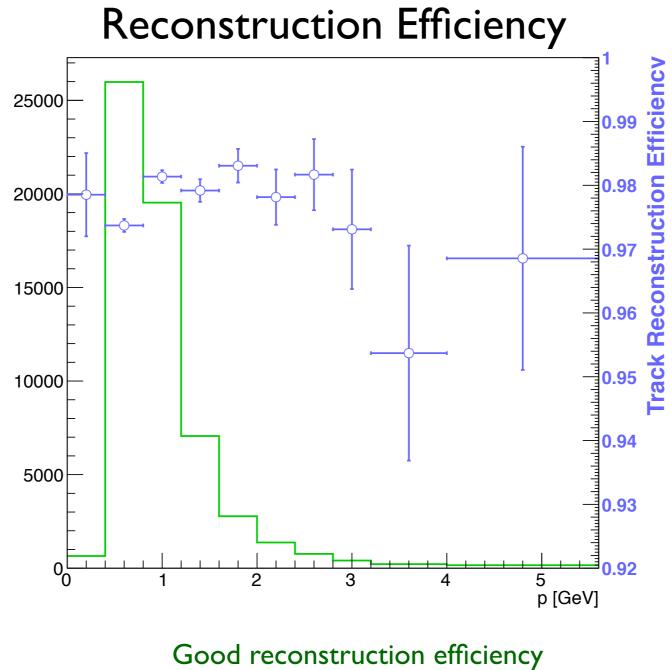


currently developing assembly fixture concept along with design details required for assembly.

Summary

- The HPS Test SVT got most things right and performed well
 - Met key performance goals for material, position and time resolution.
 - Less-than 100% coverage mostly resulted from lack of time for testing/debugging.
 - Acceptance, redundancy, mechanical precision, and cooling could be improved.
- Modest upgrades to the Test SVT can address all of these
 - Project scope is, by design, very similar to that for HPS Test SVT
 - Minimal budget risk, which is generous relative to Test SVT actual costs.
 - Schedule risk is modest if funding becomes available at beginning of FY14.
 - First steps on critical path are underway.
- Together with upgraded DAQ, the new SVT should deliver expected physics reach.

Track Reconstruction Efficiency



even without full alignment