

# Diffuse Emission and Map Making (1)

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Def 1: Map - a set of pixels (small patches of sky) and a value  $\{p_i\}$  (counts, flux, etc.) for each pixel.

convenient: grid. equal area.

Eq.

1	0	1
2	4	3
1	7	2
1	1	0

$f(1,1) = 7$   
0-indexed.

grid of numbers  
grayscale image


Def 2: Map - a discrete sampling  $f(\vec{x}_i)$  of a continuous function  $f(\vec{x})$  with dense "enough" sample points.

Enough? Nyquist - Shannon > sampling theorem  
Fourier

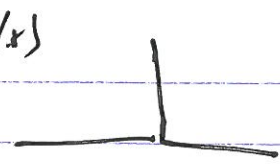
"If a function  $f(t)$  contains no frequencies higher than  $B$  Hertz, it is completely determined by giving its ordinates (values) at a series of points spaced  $1/2B$  seconds apart." Shannon '49

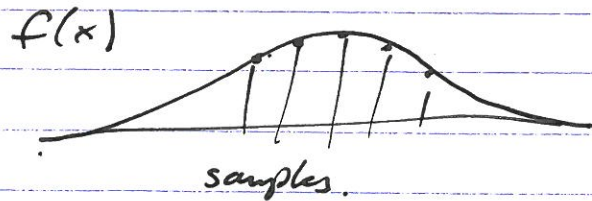
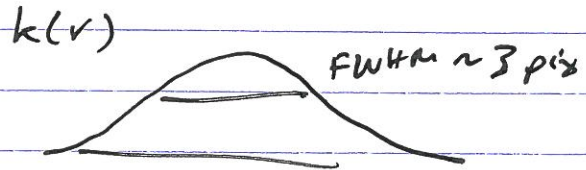
"Bandlimited" function can be perfectly reconstructed from these samples. True in 2-D also.

So, are these definitions the same?

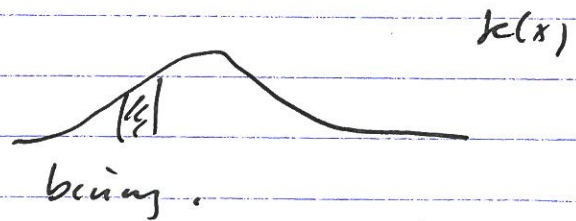
Let  $s(\vec{x})$  be the "sky"  
 $k(\vec{x})$  be psf (instrument + atmosphere, etc.)  
 $p(\vec{x})$  be pixel function 

Let  $f(\vec{x}) = s * k * p$   
 → same. ↑ convolution.

Eg. a step  $S(x)$    $\delta$ -fun ②



Exactly the same as



But wait!

What if you have additional information about each photon?

PSF, band pass (energy,  $\lambda$  pdf)

Binning loses this information

In optical ast the instrument bins for you.

Fermi does not.  $\rightarrow$  binning is bad.

To Bin or not to bin:

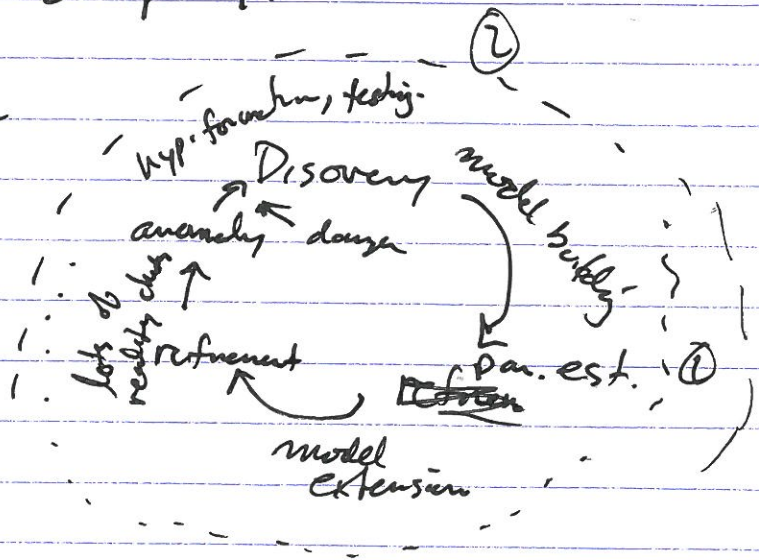
Do you have everything important in your model?

2. A correct model, just need parameter estimates and errors - formal analysis no binning.

1. Uncertain model, don't know what we're looking for. bin and play.

Non trivial difference

the anomaly - discover leg is exciting, dangerous



→ find ways to use your neural net, see things.

→ most things you see will be wrong. Must iterate fast, get on to next thing.

Now for map making.

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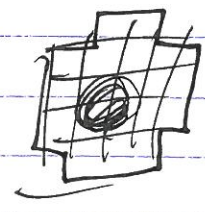
④

Diffuse emission What are we making a map of?

Unlike a flux  $(F)$  ( $\text{erg/s/cm}^2$ ) from an object, diffuse emission  $(F)$  is flux per solid angle  $\text{erg/s/cm}^2/\text{sr}$ .

obviously related by  $F = \int I d\Omega$

eg. Aperture photometry



$$F = \sum_j P_j \cdot A_{\text{pix}}$$

flux in pixel /  $A_{\text{pix}}$

$$= \sum f_j$$

Always keep track of whether you are talking about counts or counts per sr.

May be familiar with "specific intensity",  $I_\nu$

$$[I_\nu] = \cancel{\#} \text{ J/sr} \sim \text{J/s/m}^2/\text{Hz/sr} \sim \text{erg/s/cm}^2/\text{Hz/sr}$$

$$[F_\nu] \sim \text{J}$$

In gammas, we think of binning counts in energy and talk about

$$\frac{dN}{dE} = \text{counts per energy} \\ \text{i.e. counts/GeV.}$$

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Could bin in  $\ln E$

$$\frac{dN}{d \ln E} = E \frac{dN}{dE} \quad \text{counts per log } E$$

or mult by  $E$

$$E \frac{dN}{d \ln E} = E^2 \frac{dN}{dE} \quad \text{energy per log } E$$

~~Recall  $I_\nu$  is  $\text{erg/s/cm}^2$~~

These can all be per  $\text{cm}^2$  per sec, per sr.

E.g.

$$I_\nu = \text{erg/s/cm}^2/\text{s}/\text{sr} \quad (\text{energy per energy})$$

$$E^2 dN/dE \sim I_\nu.$$

$$\frac{dN}{dE} \quad \frac{\text{counts}}{\text{GeV cm}^2} \quad \frac{\text{counts}}{\text{s} \cdot \text{cm}^2 \cdot \text{GeV} \cdot \text{sr}}$$

$$I_\nu \sim E^2 \frac{dN}{dE} \sim \frac{\text{GeV}}{\text{s} \cdot \text{cm}^2 \cdot \text{sr}}$$

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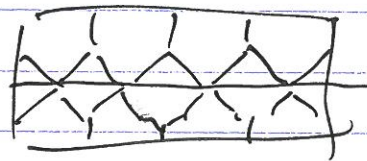
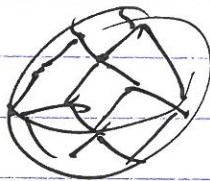
How to make a map of diffuse emission.

Want  $\frac{dN}{dE}$  counts  
GeV-s · cm<sup>2</sup> · sr

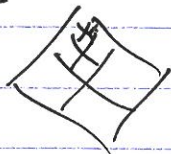
have exposure (cm<sup>2</sup> · s) from Fermi tools  
so need counts in a  $\Delta E$  bin in  $d\Omega$  pixel.

Any pixelization is fine, but equal-area pixelizations are nice.

Eg. Healpix



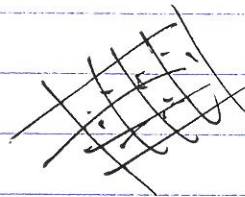
each square



Hierarchical  
Equal-area  
Iso-latitude pixelization

— Anyway...

Event list  
(ra, dec)  
(time)  
(energy)  
...  
zenith angle  
data quality cuts.



bin, space + E  
count,

counts |  
 $\Delta E \cdot A_{pix}$  Expos.

Easy, right?

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Some issues :

- psf different for front/back converting etc.
- point sources. mask? subtract?
- bad time intervals?
- Sun/Moon?
- Smoothing to same target psf?

So in more detail

- make front and back exp maps, (mask bad times,  $2 < 105$ )
- subtract sources (for wigs also). (1973 is 2FGL)
- mask 400 brightest & most variable  
(mask means remove counts, set exposure to zero). (mask some by hand)
- make front, back maps & combine.

$$I = \frac{N_f + N_b}{exp_f + exp_b}$$

- in general, smooth by  $I = \frac{\text{Smooth}(N_f)}{\text{Smooth}(E_f)}$

~~Smooth~~ pretend psf is Gaussian.

$$\sigma_T = \text{target}$$

$$\sigma_F = \sigma_T \text{ fwhm}$$

$$\sigma = \sqrt{\sigma_T^2 - \sigma_F^2}$$

write fits file (map + exp in 1st ext.)

Also f, b sep, different FWHM.

Usually use f only at  $E < 1 \text{ GeV}$ .

→ Show examples on computer

5-10 GeV  
minus 0.5-1 GeV