HPS Coordinates in Software...

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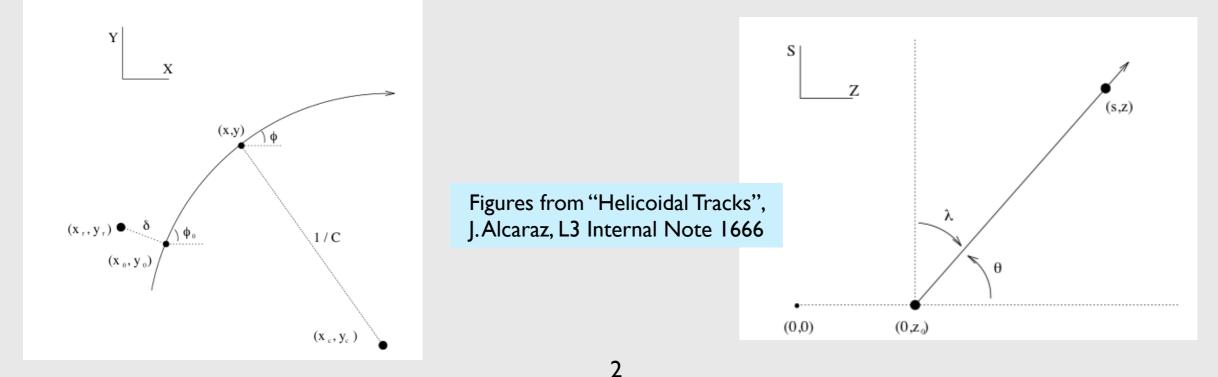
Thursday, July 7, 2011

Icsim tracking conventions

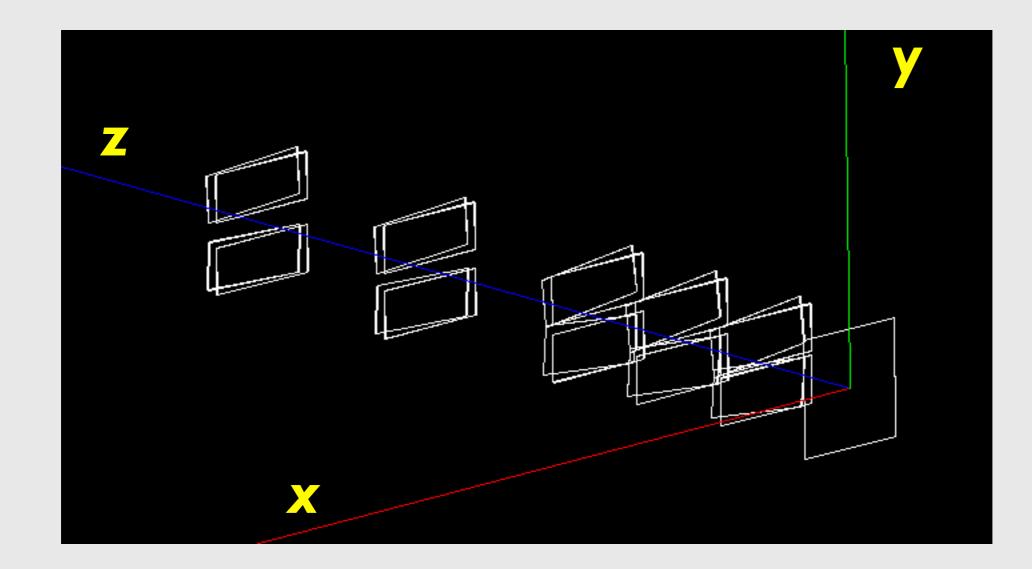
remember! In Icsim, the B-field is in the z-direction! The beam is in x and the bend is y...

•tracks use a "perigee" parameterization similar to what was introduced by Billoir & Qian (NIM A311, 1992)

•this isn't the most natural coordinate system for us...better to have the beam in z; look into transforming (transparent for enduser)



JLab Coordinates



Slic Frame to Lab Frame:

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}' = \begin{pmatrix} y \\ z \\ x \end{pmatrix}$$

Thursday, July 7, 2011

B

Changes to the geometry

- New detector type: SiTrackerSpectrometer
 - same as SiTrackerFixedTarget2 but it builds the modules along the z-axis
 - this is in GeomConverter now...



- New field type: BoxDipole
 - just a constant B-field (bx,by,bz) in a box
 - in GeomConverter and Icdd
- Haven't looked at ECal yet...

<fields< th=""><th></th><th></th></fields<>		
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	y="0*cm"	
	z="50*cm"	
	dx="10*cm"	
	dy="10*cm"	
	dz="51*cm"	
	bx="0.0"	
	by="-0.5"	
	bz="0.0">	
	•	

Changes to Reconstruction

- Digitization, clustering...nothing needed...
- Stereo hit making...make the normal (lab frame) HelicalTrackHits and also make set of hits that are rotated to the lcsim tracking frame
- Tracking is then performed using these rotated hits...works as exactly as before
 - Did have to modify MS code so that it knew detector was rotated
- These tracks get sent to vertexing as before (but vertex xyz are in lcsim frame! need to fix this...probably with a wrapper.)

org.lcsim.hps.event.HPSTransformation

package org.lcsim.hps.event;

```
import hep.physics.matrix.SymmetricMatrix;
import hep.physics.vec.BasicHep3Matrix;
import hep.physics.vec.Hep3Vector;
import org.lcsim.detector.Rotation3D;
import org.lcsim.detector.Transform3D;
/**
 * Class that contains the transformations between the JLAB and lcsim tracking coordinate systems
 * @author mgraham
 * created 6/27/2011
*/
public class HPSTransformations {
    private Transform3D detToTrk;
    public HPSTransformations() {
        BasicHep3Matrix tmp = new BasicHep3Matrix();
        tmp.setElement(0, 2, 1);
        tmp.setElement(1, 0, 1);
        tmp.setElement(2, 1, 1);
11
           detToTrk.setRotationMatrix(tmp);
        detToTrk = new Transform3D(new Rotation3D(tmp));
    3
    public Hep3Vector transformVectorToTracking(Hep3Vector vec) {
        return detToTrk.transformed(vec);
    -}
    public SymmetricMatrix transformCovarianceToTracking(SymmetricMatrix cov) {
        return detToTrk.transformed(cov);
    public Hep3Vector transformVectorToDetector(Hep3Vector vec) {
        return ( detToTrk.inverse()).transformed(vec);
    public SymmetricMatrix transformCovarianceToDetector(SymmetricMatrix cov) {
        return ( detToTrk.inverse()).transformed(cov);
    public Transform3D getTransform(){
        return detToTrk;
3
```

Simple class that defines the transformation between lcsim & jlab coordinates....probably want more later on (beam frame, ecal etc)

org.lcsim.hps.tracking.HPSTrack

* other useful things. * @author mgraham * created on 6/27/2011 public class HPSTrack extends HelicalTrackFit { private BeamSpot beam; //all of the variables defined below are in the jlab (detector) frame //this position & momentum are measured at the DOCA to the Y-axis, //which is where the tracking returns it's parameters by default private Hep3Vector _pDocaY; private Hep3Vector _posDocaY; //the position & momentum of the track at the intersection of the target (z=0)private Hep3Vector __pTarget; private Hep3Vector _posTarget; //the position & momentum of the track at DOCA to the beam axis (z) private Hep3Vector pDocaZ; private Hep3Vector _posDocaZ; private HPSTransformations _detToTrk; private double bField = 0.5; // make this set-able public HPSTrack(double[] pars, SymmetricMatrix cov, double[] chisq, int[] ndf, Map<HelicalTrackHit, Double> smap, Map<HelicalTrackHit, MultipleScatter> msmap, BeamSpot beam) { super(pars, cov, chisq, ndf, smap, msmap); beam = beam; detToTrk = new HPSTransformations(); calculateParametersAtTarget(); calculateParametersAtDocaY(); calculateParametersAtDocaZ(); } public HPSTrack(HelicalTrackFit htf, BeamSpot beam) { super(htf.parameters(), htf.covariance(), htf.chisq(), htf.ndf(), htf.PathMap(), htf.ScatterMap());

* Class HPSTrack: extension of HelicalTrackFit to include HPS-specific variables

__beam = beam; __detToTrk = new HPSTransformations(); calculateParametersAtTarget(); calculateParametersAtDocaY(); calculateParametersAtDocaZ(); }

```
private void calculateParametersAtTarget() {
    double pTot = this.p(bField);
    //currently, PathToXPlane only returns a single path (no loopers!)
    List<Double> paths = HelixUtils.PathToXPlane(this, 0.0, 100.0, 1);
    Hep3Vector posTargetTrkSystem = HelixUtils.PointOnHelix(this, paths.get(0));
    Hep3Vector dirTargetTrkSystem = HelixUtils.Direction(this, paths.get(0));
    _posTarget = _detToTrk.transformVectorToDetector(posTargetTrkSystem);
    _pTarget = VecOp.mult(pTot, _detToTrk.transformVectorToDetector(dirTargetTrkSystem));
```

wrapper extending the track fit...

•calculates momenta and track trajectory in the lab frame

 •plan is to use this instead of HelicalTrackFit objects so that the lcsim↔lab

transform is invisible to users